## TEGAM Inc.

Model 3550
42.0Hz-5.00MHz

Fully Programmable LCR Meter


MODEL 3550

Instruction Manual<br>PN\# 3550-900-01CD<br>Publication Date July 2006<br>REV. E<br>© Copyright 2004, TEGAM, Inc. All rights reserved.

NOTE: This user's manual was as current as possible when this product was manufactured. However, products are constantly being updated and improved. Because of this, some differences may occur between the descriptions in this manual and the product received. Please refer to www.tegam.com for future updates of this manual.
I INSTRUMENT DESCRIPTION ..... 1-1
Instrument Description ..... 1-1
Feature Overview ..... 1-1
3550 Options and Accessories ..... 1-4
Performance Specifications ..... 1-5
Table 1.1 - Model 3550 Measurement Range Limits ..... 1-5
Table 1.2 - Model 3550 Measurement Frequencies ..... 1-7
Table 1.3 - Model 3550 Measurement Amplitudes ..... 1-7
Table 1.4 - Model 3550 Amplitude Accuracies ..... 1-8
Table 1.5 - Model 3550 Measurement Ranges ..... 1-8
Table 1.6 - Typical Analog Measurement Times ..... 1-9
Table 1.7a - Absolute Comparator Operation ..... 1-11
Table 1.7b - Percentage Comparator Operation ..... 1-11
Table 1.8 - Numeric Displays and Annunciators ..... 1-11
Formulas and Measurement Accuracy ..... 1-13
Table 1.9 - Series and Parallel Equivalent Circuit Measurements ..... 1-14
II
PREPARATION FOR USE ..... 2-1
Unpacking and Inspection ..... 2-2
Safety Information and Precautions ..... 2-2
Servicing Safety Summary ..... 2-4
Line Voltage and Fuse Selection ..... 2-5
III QUICK START INSTRUCTI ONS ..... 3-1
Power the Unit ..... 3-2
Instrument Settings ..... 3-2
Table 3.1 - Factory Default Settings ..... 3-2
Table 3.2 - Control Command Summary ..... 3-3
Table 3.3 - Shift Function Summary ..... 3-4
Instrument Setup for Basic Measurements ..... 3-5
Table 3.4 - Settings Summary ..... 3-5
Setting the Absolute Comparator ..... 3-6
Setting the Percent Comparator ..... 3-7
IV OPERATI NG I NSTRUCTI ONS ..... 4-1
Basic Operation ..... 4-2
Default Parameters ..... 4-2
Precautions ..... 4-2
Measurement Tips ..... 4-2
Making Measurements that are Sensitive to Voltage and Current ..... 4-2
Measuring Earth Grounded Test Pieces ..... 4-2
Measurement Circuit Modes ..... 4-3
Table 4.1 - Relationship Between Series and Parallel Equivalent Circuits ..... 4-3
Negative Capacitance or Inductance Readings ..... 4-4
Zero Correction of Parasitic Impedance ..... 4-4
Table 4.2 - Short and Open Null Connections ..... 4-4

## IV OPERATING INSTRUCTIONS CONT'D

Measurement Tips
Test Lead Requirements ..... 4-5
Figure 4.1a - Four-Wire Kelvin Measurement ..... 4-5
Figure 4.1b - Proper Application of Four Wire Kelvin Measurement ..... 4-5
Measurement Signal Levels ..... 4-6
Series or Parallel Circuit Modes ..... 4-6
Auto range Switching Threshold ..... 4-6
Display Resolution ..... 4-6
AC Resistance of Coils with Cores ..... 4-6
Front Panel Description ..... 4-7
Figure 4.2 - Front Panel Layout ..... 4-7
Power Switch ..... 4-8
Circuit Mode Panel ..... 4-8
Trigger Panel ..... 4-8
Zero Panel ..... 4-9
Range Selection Panel ..... 4-9
Shift Key ..... 4-10
Frequency Set Mode ..... 4-10
Test Voltage Set Mode ..... 4-11
Test Current Set Mode ..... 4-11
Averaging Set Mode ..... 4-12
Key Lock Mode ..... 4-12
Comparator buzzer Function ..... 4-13
Trigger Delay Time ..... 4-13
Comparator Functions Mode ..... 4-14
Defining Spot Frequencies for Zero Adjustments ..... 4-14
RS-232C Settings Mode ..... 4-15
Correction Frequency Limit Setting Mode ..... 4-16
Spot Correction Mode (Open Correction) ..... 4-16
Spot Correction Mode (Short Correction) ..... 4-16
Unknown Terminals Panel ..... 4-17
Table 4.3 - Unknown Terminals ..... 4-17
Comparator Limit Set Panel ..... 4-17
The Guard Terminal ..... 4-17
Remote Interface Status LEDs ..... 4-18
Panel Selector Switch. ..... 4-18
Panel Display LED. ..... 4-18
Display A Parameter Selection Key ..... 4-18
Display A ..... 4-18
Bin Display LED ..... 4-18
Comparator State Annunciators ..... 4-19
Sample LED (Trigger Status) ..... 4-19
Comparator ON/OFF Switch ..... 4-19
Display B Parameter Selection Key ..... 4-19
Display B ..... 4-19
IV OPERATI NG I NSTRUCTI ONS CONT'D
Front Panel Description Cont'd
Display C Measurement Panel ..... 4-20
Table 4.4 - CV/CC Indicators ..... 4-21
Display C ..... 4-21
Enter Key ..... 4-21
Rear Panel Description ..... 4-22
Figure 4.3 - Rear Panel Layout ..... 4-22
Making Accurate Measurements ..... 4-23
Connections to the Device Under Test ..... 4-23
3-Terminal Measurement ..... 4-23
4 or 5-Terminal Measurements ..... 4-23
Test Fixture Selection ..... 4-24
Table 4.4 - Impedance and Frequency Limitations of Kelvin Klip Leads ..... 4-24
Table 4.5 - Impedance and Frequency Limitations of the SMD Test Fixture ..... 4-25
Zero Corrections ..... 4-26
Table 4.6 - Zero Correction Limits ..... 4-26
Figure 4.4 - Terminal Connections for Zero Correction ..... 4-27
Equivalent Circuits ..... 4-28
Table 4.7 - Equivalent Circuit Relationships ..... 4-29
Operating the 3550 ..... 4-30
Preparation ..... 4-30
How to Perform a Zero Correction ..... 4-30
Measuring L, C, and R ..... 4-31
Measuring $|\mathrm{Z}|$ and $|\mathrm{Y}|$ ..... 4-33
Measuring D, Q, Rs, Rp, G, X, B, and $\theta$ ..... 4-34
The Comparator ..... 4-35
Important Notes for the Absolute and Comparator Functions ..... 4-35
Absolute Value Settings ..... 4-36
Percent Value Settings ..... 4-37
Bin Operation ..... 4-39
Figure 4.5 - Sequenced Bin Sorting ..... 4-39
Figure 4.6 - Nested Bin Sorting ..... 4-40
Outputting the Comparator's Results ..... 4-41
Audible Buzzer Operation ..... 4-41
V PROGRAMMI NG AND I NTERFACI NG ..... 5-1
Interfacing to the 3550 ..... 5-2
Control I/O Connector ..... 5-2
Inputs ..... 5-2
Figure 5.1 - Input Schematic ..... 5-2
Outputs ..... 5-3
Figure 5.2 - Output Schematic ..... 5-3
Timing Diagrams ..... 5-4
Figure 5.3a - Test Busy Operation ..... 5-4
Figure 5.3b - Measure End Operation ..... 5-4
Figure 5.3c-GO/NO-GO Operation ..... 5-4
Table 5.1 - Connector Pin Designations ..... 5-5
Table 5.2 - Control I/O Function Summary ..... 5-6
Sample Diagram of External Connections to Sequencer ..... 5-7
RS-232C ..... 5-8
Interface Cable ..... 5-8
Input Format ..... 5-8
Table 5.3a - Command Summary ..... 5-11
Table 5.3b - Command Summary cont'd ..... 5-12
Table 5.3c - Command Summary cont'd ..... 5-13
Table 5.4 - Comparator Instructions ..... 5-14
Data Output Format for Measurement Settings ..... 5-15
Table 5.5a - Data Output Code Functions ..... 5-16
Table 5.5b - Data Output Code Functions cont'd ..... 5-17
Monitor Output Format ..... 5-18
Table 5.6c - Monitor Output Code Functions ..... 5-21
Table 5.6b - Monitor Output Code Functions cont'd ..... 5-22
RS-232C Hardware and Computer Settings ..... 5-23
Sample Programs for RS-232C ..... 5-23
The GPIB Interface (Optional) ..... 5-28
General Description of GPIB ..... 5-28
Primary Specifications of GPIB ..... 5-28
Table 5.7-GPIB Functions ..... 5-28
Installation of the GPIB Board ..... 5-29
Figure 5.4a - Rear View ..... 5-29
Figure 5.4b - Side View ..... 5-30
Figure 5.4c - Top View. ..... 5-30
Front Panel Status LEDs ..... 5-31
Local Key Switch ..... 5-31
GPIB Switches ..... 5-31
Delimiter Output Formats ..... 5-31
Output Status Bits for Service Requests ..... 5-31
Figure 5.5 - GPIB Status Bits ..... 5-31
Additional Notes for Using the GPIB Interface ..... 5-31
Programming Examples ..... 5-33
VI SERVICE I NFORMATI ON ..... 6-1
Warranty ..... 6-2
Warranty Limitations ..... 5-2
Statement of Calibration ..... 6-2
Contact Information ..... 6-2
Repair Parts ..... 6-3
Troubleshooting ..... 6-4
Preparation for Repair or calibration Service ..... 6-5
Expedite Repair and calibration Form ..... 6-6
Performance Verification Procedure ..... 6-7
Model 3550 Calibration Adjustment Procedure ..... 6-12
VII APPENDIX ..... A. 1
Setting the Constant Voltage Mode ..... A. 3
To Enable the Constant Voltage Mode. ..... A. 3
Calculating the maximum Allowable Constant Voltage Setting ..... A. 3
Setting the Constant Current Mode ..... A. 4
Calculating the maximum Allowable Constant Current Setting. ..... A. 4
Basic Measurement Accuracy Tables ..... A. 5
Table A. 1 - Basic Accuracy Table ..... A. 5
Table A. 2 - Basic Accuracy Table [0.01V to 0.04V] ..... A. 6
Table A. 3 - Basic Accuracy Table [0.05V to 0.10V] ..... A. 7
Table A. 4 - Basic Accuracy Table [0.11V to 0.20V] ..... A. 8
Table A. 5 - Basic Accuracy Table [0.21V to 0.45V] ..... A. 9
Table A. 6 - Basic Accuracy Table [0.46V to 1.00 V ] ..... A. 10
Table A. 7 - Basic Accuracy Table [1.01V to 5.00V] ..... A. 11
LC Impedance Calculation Chart ..... A. 12
Error Codes ..... A. 13

# I NSTRUMENT DESCRI PTI ON 

 PREPARATION FOR USE QUICK START INSTRUCTIONS OPERATING INSTRUCTIONS PROGRAMMING \& I NTERFACING SERVICE INFORMATION APPENDIX
## Instrument Description

The Model, 3550, is a high-speed LCR Meter capable of measuring Inductance (L), Capacitance(C), Resistance (R), Absolute Impedance (|Z|), Absolute Admittance (|Y|), Dissipation factor (D), Quality (Q), Serial Equivalent Resistance (Rs), Parallel Equivalent Resistance (Rp), Conductance (G), Reactance (X), Susceptance (B), and Phase Angle ( $\theta$ ). It has a wide measurement range, and includes full adjustability of Measurement Frequency and Measurement Signal Level. It also features Automatic adjustment for Zero Correction, Range Switching, and Series and Parallel Mode Switching.

The basic comparator function of the 3550 is extended to allow sorting of components to up to 10 different bins. Up to 9 panels worth of measurement settings can be stored in the instrument's non-volatile memory for convenient recall. The instrument can perform a complete measurement including a comparator judgment in as little as 40ms.

The 3550 has standard RS-232C and Control I/O Connector Interfaces with the availability of an optional GPIB Interface. The Control I/Os are optically isolated thus making the instrument ideal for noise immunity.

## Feature Overview

The 3550 Programmable LCR Meter offers a complete solution for a wide variety of specialized LCR measurement applications. Listed below are some of the features.

## High Speed

The measurement time, including data display, zero correction, and comparator function is approximately 40 milliseconds.

## Extended Frequency Range

The Measurement Frequency can be adjusted between $42.0 \mathrm{~Hz}-5.00 \mathrm{MHz}$.

## Programmable Test Voltage and Current

The test signal level can be adjusted between 10 mV to 5.00 V in the constant voltage mode and from $10 \mu \mathrm{~A}$ to 99.99 mA in the constant current mode.

## Voltage \& Current Monitor

The voltage at the test piece terminals and the current, which is flowing through the test piece, can be displayed up to 3 significant digits.

## Feature Overview cont'd:

## 4 $1 / 2$ Digits Resolution

"DISPLAY A" (L, C, R, |Z|, |Y|), and "DISPLAY B" (D, Q, Rs, Rp, G, X, B, $\theta$ ) can both display up to $4^{1} / 2$ digits.

## GO/ NO-GO COMPARATOR

For $\mathrm{L}, \mathrm{C}, \mathrm{R},|\mathrm{Z}|,|\mathrm{Y}|, \mathrm{D}, \mathrm{Q}, \mathrm{R}_{\mathrm{s}}, \mathrm{R}_{\mathrm{p}}, \mathrm{G}, \mathrm{X}, \mathrm{B}$, and $\theta$, upper and lower limit values can be set for 9 items ( 10 categories), for up to 9 panels of settings.

## Series or Parallel Equivalent Circuit Mode

When in "Auto" mode, Parallel or Series Equivalent Circuit measurements are automatically determined by the active measurement range. In manual range, the Parallel or Series Equivalent Circuit mode are user selectable.

## Front Panel Key Lock

The Key Switch on the front panel can be set to lock the instrument settings for protection against accidental changes.

## Automatic Zero Correction of Parasitic Impedance

Performing Open and Short Circuit Zeroing cancel the offset errors caused by Stray Capacitance, Stray Conductance, Residual Inductance, and Residual Resistance.

## Non-Volatile Memory

All measurement settings such as the Zero Correction Values, Comparator Limits, Panel Settings etc. are stored in non-volatile memory and are retained in the event of power loss.

## Remote Operation

The TEGAM Model 3550 provides standard RS-232C and I/O Control Connector interfaces for remote operation. There is an optional GPIB (IEEE-488) interface available for purchase.

## 3550 Options and Accessories



2005B - Chip Tweezers (5ft)
This four-terminal tweezer set makes solid connections to chip components in manual sorting applications. Capacity of jaws is 12.7 mm ( 0.5 in .). The 2005B Chip Component Tweezer Set includes a 1.5 m ( 5 ft ) cable for connection to the 2150/2160. Contact tips are replaceable. P/N 47422.


## 47422 Chip Tweezer

 Replacement KitTweezer tips are intended to last 100,000 to 500,000 operations. An optional tip replacement kit includes 12 replacement tips, 2 screws and 1 wrench.


## 3511 - SMD Test Fixture

Available for performing three terminal measurements on surface mount devices. Connects directly to the front panel of the 3550 . Use the 3511 for medium and high impedance measurements.


## 3510-Radial Lead Adapter

This sorting fixture allows for efficient four-wire measurement of leaded parts. The test fixture features spring action contacts for easy insertion and removal of test components.


## 47454 - Kelvin Klips

Kelvin Klips allow solid four-terminal, Kelvin connections to leaded components. The jaws are assembled with hardened gold-plated, beryllium copper, which ensures low contact resistance, low thermal emf to copper, high corrosion resistance, and long service life. An alligator clip is provided allowing connection of a passive guard. The assembly includes a 5 ft ( 1.5 m ) cable for connection to the 3525.

NOTE: Under certain measurement conditions, Kelvin Klips can cause a loss of measurement accuracy. Fixtures 3510,3511 , or 2005B chip tweezers are recommended for the following component values:

$$
\mathrm{C}<100 \mathrm{pF} ; \mathrm{L}<100 \mu \mathrm{H} ; \mathrm{R}>1 \mathrm{M} \Omega
$$



KK100- Kelvin Klip ${ }^{\text {m }}$ Rebuild Kit
Kelvin Klip $^{\text {Tm }}$ replacements for construction or repair of Kelvin Klip leads.


## GPI B (IEEE-488) Cables

1583-3 - 1-meter GPIB buss cable
1583-6-2-meter GPIB buss cable
1583-9-3-meter GPIB buss cable


3505 - GPIB Interface
3550-900-01 - User's ManualHard Copy


CABLE NULL 9PIN-25 PIN
3740570-6-6' Cable null 9 pin - 25 pin
3740570-10-10' Cable null 9 pin - 25 pin

## Performance Specifications

The advertised specifications of the model 3550 are valid under the following conditions:

1. The instrument must be verified and/or adjusted using the methods and intervals as described in the calibration section of this user's manual.
2. The instrument must be in an environment, which does not exceed the limitations as defined under "Environmental" in the Miscellaneous Specifications section.
3. The unit is allowed to warm up for a period of at least 30 minutes before measurements are taken. A warm-up period of 60 minutes is recommended after exposure to or storage in a high humidity, (non-condensing), environment.
4. Only TEGAM-manufactured Kelvin Klips $^{\text {Tm }}$, Tweezers and other test fixtures are used with this device during measurements.

## Measurement Parameters:

Inductance (L), Capacitance(C), Resistance(R), Impedance (|Z|), Admittance (|Y|), Dissipation Factor (D), Quality (Q), Equivalent Series Resistance ( $\mathrm{R}_{\mathrm{s}}$ ), Equivalent Parallel Resistance ( $R_{P}$ ), Conductance (G), Reactance (X), Susceptance (B), and Phase Angle ( $\theta$ ).

## Measurement Ranges

Table 1.1 - Model 3550 Measurement Range Limits

| Parameter | Low Limit | High Limit |
| :--- | :--- | :--- |
| L | $320.0 \mathrm{nH}(\mathrm{At}: 10 \Omega 5 \mathrm{MHz})$ | $0.7500 \mathrm{MH}(\mathrm{At}: 199.99 \mathrm{M} \Omega 42 \mathrm{~Hz})\left(\theta=90^{\circ}\right)$ |
| C | $0.160 \mathrm{pF}(\mathrm{At}: 100 \mathrm{k} \Omega 5 \mathrm{MHz})$ | $0.037 \mathrm{~F}(\mathrm{At}: 100 \mathrm{~m} \Omega 42 \mathrm{~Hz})\left(\theta=-90^{\circ}\right)$ |
| R | $0.01 \mathrm{~m} \Omega$ | $199.99 \mathrm{M} \Omega$ |
| $\mathrm{Z} \mid$ | $0.01 \mathrm{~m} \Omega$ | $199.99 \mathrm{M} \Omega$ |
| $\mathrm{Y} \mid$ | $5.000 \mathrm{nS}(199.99 \mathrm{M} \Omega)$ | $100.00 \mathrm{~S}(100 \mathrm{~m} \Omega)$ |
| D | 0.0001 | 9.999 |
| Q | 0.1 | 1999.9 |
| $\mathrm{R}_{\mathrm{S}}$ | $0.01 \mathrm{~m} \Omega$ | $199.99 \mathrm{M} \Omega$ |
| $\mathrm{R}_{\mathrm{P}}$ | $0.01 \mathrm{~m} \Omega$ | $199.99 \mathrm{M} \Omega$ |
| G | $5.000 \mathrm{nS}(199.99 \mathrm{M} \Omega)$ | $100.00 \mathrm{~S}(100 \mathrm{~m} \Omega)$ |
| X | $0.01 \mathrm{~m} \Omega$ | $199.99 \mathrm{M} \Omega$ |
| B | $5.000 \mathrm{nS}(199.99 \mathrm{M} \Omega)$ | $100.00 \mathrm{~S}(100 \mathrm{~m} \Omega)$ |
| $\theta$ | $-180.00^{\circ}$ | $180.00^{\circ}$ |

NOTE: The Measurement Range is dependent on the Measurement Frequency. The figures in parentheses are DUT impedance values.

## Performance Specifications cont'd:

## Basic Accuracy

0.1\%

## Display Specifications:

- Numeric Display (DISPLAY A)
$\mathrm{L}, \mathrm{C}, \mathrm{R},|\mathrm{Z}|,|\mathrm{Y}|\left(4^{1} / 2\right.$ digits)
- Numeric Display (DISPLAY B)

D, $\mathrm{Q}, \mathrm{R}_{\mathrm{s}}, \mathrm{R}_{\mathrm{p}}, \mathrm{G}, \mathrm{X}, \mathrm{B}, \theta\left(4^{1} / 2\right.$ digits)

- Numeric Display (DISPLAY C)

Frequency, Voltage, Current, Terminal Voltage, Terminal Current, PANEL (3 digits)

- Unit Prefix Display (DISPLAY A)
$\mathrm{p}, \mathrm{n}, \mu, \mathrm{m}, \mathrm{k}, \mathrm{M}$
- Unit Prefix Display (DISPLAY B)
$\mathrm{n}, \mu, \mathrm{m}, \mathrm{k}, \mathrm{M}$
- Unit Display (DISPLAY A)

F, H, $\Omega$, S

- Unit Display (DISPLAY B)
$\Omega$, S, deg
- Unit Display (DISPLAY C)

Hz, kHz, MHz, V, mA

## Switch I ndicator Lamps

- RANGE - AUTO; UP; DOWN
- CIRCUIT MODE - AUTO; SER; PRL
- SHIFT
- DISPLAY C - V; I; CV/CC
- TRIGGER - INT; MAN/EXT
- SAMPLE


## Performance Specifications cont'd:

## Measurement Frequency

Table 1.2 - Model 3550 Measurement Frequencies

| Frequency Range | Resolution |
| :--- | :--- |
| $42.0 \mathrm{~Hz} \sim 99.9 \mathrm{~Hz}$ | 0.1 Hz Steps |
| $100 \mathrm{~Hz} \sim 999 \mathrm{~Hz}$ | 1 Hz Steps |
| $1.00 \mathrm{kHz} \sim 9.99 \mathrm{kHz}$ | 10 Hz Steps |
| $10.0 \mathrm{kHz} \sim 99.9 \mathrm{kHz}$ | 100 Hz Steps |
| $100 \mathrm{kHz} \sim 999 \mathrm{kHz}$ | 1 kHz Steps |
| $1.00 \mathrm{MHz} \sim 5.00 \mathrm{MHz}$ | 10 kHz Steps |

## Measurement Frequency Accuracy

$\pm 0.01 \%$

## Measurement Signal Level

Table 1.3 - Model 3550 Measurement Amplitudes

| Frequency Range | Test Voltage <br> Range | Test Current Range |
| :--- | :--- | :--- |
| $42.0 \mathrm{~Hz} \sim 1.00 \mathrm{MHz}$ | $0.01 \sim 5.00 \mathrm{Vrms}$ | $0.01 \sim 99.99 \mathrm{mArms}$ |
| $1.01 \mathrm{MHz} \sim 5.00 \mathrm{MHz}$ | $0.05 \sim 1.00 \mathrm{Vrms}$ | $0.05 \sim 20.00 \mathrm{mArms}$ |

## Open Terminal Voltage Mode

- Increment/Resolution
0.01V Steps
- Max. Shorting Current
99.99mA (Dependent on Measurement Frequency)


## Fixed Voltage Mode

- Increment/Resolution
- Max. Shorting Current
0.01V Steps
99.99mA(Dependent on Measurement Frequency)


## Fixed Current Mode

- Increment/Resolution 0.01 mA Steps
- Max. Shorting Current
99.99 mA (Dependent on Measurement Frequency)


## Performance Specifications cont'd:

## Monitor Functions

$\begin{array}{ll}\text { Voltage Monitor } & 0.00 \mathrm{~V} \sim 5.00 \mathrm{~V} \\ \text { Current Monitor } & 0.00 \mathrm{~mA} \sim 99.99 \mathrm{~mA}\end{array}$

## Settings and Monitor Accuracy

Table 1.4 - Model 3550 Amplitude Accuracies

| Frequency Range | Test Voltage <br> Accuracy | Test Current <br> Accuracy |
| :---: | :---: | :---: |
| $42.0 \mathrm{~Hz} \sim 4.00 \mathrm{MHz}$ | $\pm(10 \%+10 \mathrm{mV})$ | $\pm(10 \%+10 \mu \mathrm{~A})$ |
| $4.01 \mathrm{MHz} \sim 5.00 \mathrm{MHz}$ | $\pm(20 \%+10 \mathrm{mV})$ | $\pm(20 \%+10 \mu \mathrm{~A})$ |

## Signal Source I mpedance

$$
50 \Omega \pm 10 \%
$$

## Measurement Circuit Modes

- Auto/Manual Circuit Selection
- Parallel Equivalent Circuit Mode
- Series Equivalent Circuit Mode


## Range

Measurement Range is determined by the DUT's absolute impedance |Z|. There are 9 total ranges selectable in either AUTO or MANUAL modes. Measurement parameters (L, C, R, etc.) are calculated from actual test voltage and current values.

Table 1.5 - Model 3550 Measurement Ranges

| Range | $\mathbf{1}$ | $\mathbf{2}$ | $\mathbf{3}$ | $\mathbf{4}$ | $\mathbf{5}$ | $\mathbf{6}$ | $\mathbf{7}$ | $\mathbf{8}$ | $\mathbf{9}$ | AUTO |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Upper <br> Limit <br> $\mathbf{Z} \mid$ | $100 \mathrm{~m} \Omega$ | $1 \Omega$ | $10 \Omega$ | $100 \Omega$ | $1 \mathrm{k} \Omega$ | $10 \mathrm{k} \Omega$ | $100 \mathrm{k} \Omega$ | $1 \mathrm{M} \Omega$ | $10 \mathrm{M} \Omega$ | $100 \mathrm{~m} \Omega \sim 10 \mathrm{M} \Omega$ |

## Performance Specifications cont'd:

## Measurement Time

## Open Terminal Voltage Mode

When the Measurement Frequency is 10 kHz , no averaging, the range is held constant, RS-232C is OFF and the Comparator is ON, the shortest measurement time is 18 ms .

## Typical Analog Measurement Times

Conditions: Averaging= 1, range held, RS-232C is OFF, and Comparator ON:

Table 1.6 - Typical Analog Measurement Times

| Test Frequency | Typical Analog Measurement Time |
| :---: | :---: |
| 42 Hz | $624 \mathrm{~ms} \mathrm{Max}$. |
| 120 Hz | $221 \mathrm{~ms} \mathrm{Max}$. |
| 1 kHz | 31 ms Max. |
| 10 kHz | 18 ms Max. |
| 100 kHz | $30 \mathrm{~ms} \mathrm{Max}$. |
| 1 MHz | $25 \mathrm{~ms} \mathrm{Max}$. |
| 5 MHz | 21 ms Max. |

## About the Typical Analog Measurement Time

The Typical Analog Measurement Time is dependent upon the Measurement Frequency. For ranges $42.0 \mathrm{~Hz} \sim 750 \mathrm{~Hz}$, and $10.1 \mathrm{kHz} \sim 19.0 \mathrm{kHz}$, Typical Analog Measurement Time will exceed 40 ms .
For other frequencies, 40 ms will not be exceeded.
(Conditions: Averaging $=1$, range held, RS-232C is OFF, and Comparator ON)
With the RS-232C turned on and set to a baud rate of 9600 BPS, the additional time needed for RS-232C communication is 100 ms at any frequency setting.

## Fixed Voltage/ Fixed Current Mode

The measurement time can be up to $4 X$ the time of the Open Terminal Voltage Mode.

## Average Mode

The user can define from 1~100 averages.

## Performance Specifications cont'd:

## Measurement Terminals

- 2 - BNC Source Terminals
- 2 - BNC Detect Terminals
- 1 - Guard Banana/Binding Post


## Parasitic Impedance Correction

Open Correction $1 \mathrm{k} \Omega$ or higher Impedance
Short Correction Less than $1 \mathrm{k} \Omega$ Impedance

## Programmable Delay Time

Measurements will be started after a trigger is detected from the front panel, Control I/O Connector or RS232C interface. The delay time setting is user-definable and ranges from $0 \sim 10$ seconds in 1 ms increments.

## GO/ NO-GO Limits Comparator/ Binning

## Absolute Value

- Absolute Settings must fall within the Measurement Ranges of DISPLAY A and DISPLAY B.
- Comparator Settings must be applied to existing preset panels.
- Up to 9 programmable bins (1-9) may be defined. Bin 0 is reserved for measured values that fall outside of the limits.
- User may program the High or Low limits of DISPLAY A and DISPLAY B to be ignored.


## Percent Value

- Percent Settings must fall within the Measurement Ranges of DISPLAY A and DISPLAY B.
- Limit Values of 00000~999.99 \% for both DISPLAY A and DISPLAY B
- Comparator Settings must be applied to existing panels.
- Up to 9 programmable bins (1-9) may be defined. Bin 0 is reserved for measured values that fall outside of the limits.
- User may program the High or Low limits of DISPLAY A and DISPLAY B to be ignored.


## Performance Specifications cont'd:

## Comparator/ Binning: Absolute Limits Operation

Table 1.7a - Absolute Comparator Operation

| Operation | Function |
| :--- | :--- |
| Bins $1 \sim 9$ | "LOW LIMIT" $\leq$ Measurement Value $\leq$ "HIGH LIMIT" |
| LO | Measurement Value < "LOW LIMIT" |
| HI | "HIGH LIMIT" < Measurement Value |
| TOTAL GO | When both DISPLAY A and DISPLAY B are not LO or HI |

## Comparator/ Binning: Percent Limits Operation

*The location of the decimal point affects the \% comparator/binning values.
Table 1.7b - Percentage Comparator Operation

| Operation | Function |
| :--- | :--- |
| Bins $1 \sim 9$ | "LOW LIMIT" $\leq$ Measurement Value $\leq$ "HIGH LIMIT" |
| LO | Measurement Value < "LOW LIMIT" |
| HI | "HIGH LIMIT" < Measurement Value |
| TOTAL GO | When both DISPLAY A and DISPLAY B are not LO or HI |

## Displays

Table 1.8 - Numeric Displays and Annunciators

| Display | Display Description \& Range |
| :--- | :--- |
| Numeric DISPLAY A | $-19999 \sim 19999$ (4-1/2 digits) |
| Numeric DISPLAY B | $-19999 \sim 19999$ (4-1/2 digits) |
| Unit Prefix Annunciators for DISPLAY A | $\mathrm{p}, \mathrm{n}, \mu, \mathrm{m}, \mathrm{k}, \mathrm{M}$ |
| Unit Prefix Annunciators for DISPLAY B | $\mathrm{n}, \mu, \mathrm{m}, \mathrm{k}, \mathrm{M}$ |
| Unit Annunciators for DISPLAY A | $\mathrm{F}, \mathrm{H}, \Omega, \mathrm{S}$ |
| Unit Annunciators for DISPLAY B | $\Omega, \mathrm{S}, \mathrm{deg}$ |
| Comparator Limit | LOW \& HIGH Pushbuttons |
| Comparator Enabled | ON Pushbutton |
| Comparator State | LO-HI (For DISPLAY A \& B) |
| Comparator Total GO | TOTAL GO LED |
| BIN | $0-9$ Seven Segment LED Display |
| PANEL | $0-9$ Seven Segment LED Display |
| GPIB Status | SRQ, LTN, TLK, RMT |

## Performance Specifications cont'd:

## Digital Interfaces

RS-232C Standard interface
GPIB Optional Interface
Control I/O Standard Interface Connector
External Control Signals
CONTROL PANEL/EXT, EXT TRIGGER, PANEL No. (Isolated)
External Output Signals
MEASURE END, ERROR, DISPLAY A HI, DISPLAY A LO, DISPLAY A GO, DISPLAY B LO, DISPLAY B HI, DISPLAY B GO, TOTAL GO, TOTAL NO-GO, BIN (Optically Isolated)

## Audible Buzzer

Can be set to turn ON with GO or NO-GO comparator state; or it can be disabled.

## Panel Presets

9 panel presets including comparator settings can be programmed into non-volatile memory.

## Front Panel Key Lock

Protects accidental changing of front panel settings all panel keys except the Manual Trigger are disabled.

## Environmental

Operating Temperature $=5^{\circ} \mathrm{C} \sim 40^{\circ} \mathrm{C}\left(41^{\circ} \mathrm{F} \sim 104^{\circ} \mathrm{F}\right)<80 \%$ RH Non-Condensing
o Accuracy specifications are based on temperature conditions within $23^{\circ} \mathrm{C} \pm 5^{\circ} \mathrm{C}$ ( $73.4^{\circ} \mathrm{F} \pm 9^{\circ} \mathrm{F}$ ).
o For temperatures exceeding $23^{\circ} \mathrm{C} \pm 5^{\circ} \mathrm{C}$ and still within the operating temperature, the margin of error will be 2 times larger.

## Power Source

- Operating Voltage $=100 / 120 / 220 / 240 \mathrm{~V}$ AC $\pm 10 \%($ MAX250V $)$
- Power Frequency=50/60Hz
- Maximum Power Usage=40VA


## Dimensions

Width: 9.84" ( 250 mm )
Height: $5.83^{\prime \prime}$ ( 148 mm )
Depth: $15.74^{\prime \prime}$ ( 400 mm )

## Weight

Approximately 15.4 lb ( 7 kg )

## Formulas and Measurement Accuracy

## Parameters and Formulas

Generally speaking, the characteristics of circuit components can be evaluated in terms of impedance (Z).
The 3550 LCR Meter measures the voltage and current components of the circuit in relation to the alternating signal of the measurement frequency, and uses these values to calculate impedance $(Z)$ and phase angle ( $\theta$ ).
Displaying impedance $(Z)$ in a complex notation as below allows us to determine the following values.


$Z=R+j X$
$\theta=$ TAN $^{-1} \mathrm{X} / \mathrm{R}$
$|Z|=\sqrt{R^{2}+X^{2}}$
Z: Impedance ( $\Omega$ )
$\theta$ : Phase Angle (deg)
R: Resistance ( $\Omega$ )
X: Reactance ( $\Omega$ )
$|Z|:$ Absolute Value of Impedance ( $\Omega$ )
Depending on the properties of the DUT, Admittance $(\mathrm{Y})$, which is the inverse of Impedance $(\mathrm{Z})$, may be used to calculate parameter values instead. Admittance ( Y ), like Impedance ( Z ) can be represented in complex notation in order to calculate the following values.
$Y=G+j B$
$\Phi=\mathrm{TAN}^{-1}\left(\mathrm{~B}^{*} \mathrm{G}\right)$
$|\mathrm{Y}|=\sqrt{\mathrm{G}^{2}+\mathrm{B}^{2}}$
Y: Admittance (S)
G: Conductance (S)
B: Susceptance (S)
$|\mathrm{Y}|$ : Absolute value of Admittance (S)


## Formulas and Measurement Accuracy cont'd:

The 3550 calculates the various measurement values using the inter-terminal voltage ( V ) applied to the DUT (device under test) terminals, the current (I) that occurs in relation to the voltage, the Phase Angle $(\theta)$ of $(\mathrm{V})$ and (I), and the Angular Velocity ( $\omega$ ) of the measurement frequency.
These factors are used in the formulas below to determine values for the measurements made by the TEGAM 3550.

Note: The Phase Angle is based on Impedance (Z). In order to base the Phase Angle on Admittance ( Y ), add a "-" sign to the Impedance value to negate it. Thus, $\varphi$ for Admittance will be $\varphi=-\theta$.

Table 1.9 - Series and Parallel Equivalent Circuit Measurements

| Item | Series Equivalent Circuits | Parallel Equivalent Circuits |
| :---: | :---: | :---: |
| $Z$ | $\|Z\|=V / I\left(\sqrt{R^{2}+X^{2}}\right)$ |  |
| $Y$ | $\|Y\|=1 /\|Z\|\left(\sqrt{G^{2}+B^{2}}\right)$ |  |
| $R$ | $R_{S}=E S R=\|\|Z\| \cos \theta\|$ | $R_{P}=E P R=\|1 /(\|Y\| \cos \theta)\|=1 / G$ |
| $X$ | $X=\|Z\| \sin \theta$ | - |
| $G$ | - | $\|Y\| \cos \theta * * *$ |
| $B$ | $L_{S}=X / \omega$ | $B=\|Y\| \sin \theta * * *$ |
| $L$ | $C_{S}=1 /\left(\omega^{*} X\right)$ | $C_{P}=1 /\left(\omega^{*} B\right)$ |
| $C$ | $\mathrm{D}=1 / \tan \theta=1 / Q$ |  |
| $D$ | $Q=\tan \theta=1 / D$ |  |
| $Q$ |  |  |

*** $\varphi$ is the Phase Angle of Admittance: $\varphi=-\theta$
$L_{S}, C_{S}, R_{S}$ represent the $L, C, R$ measurements for series equivalent circuits.
$L_{p}, C_{p}, R_{p}$ represent the $L, C, R$ measurements for parallel equivalent circuits.

## Measurement Accuracy

The impedance of the DUT is either the actual measured value or a value, which is derived from the formulas below:

$$
\begin{gathered}
\text { If } \theta=90^{\circ} \rightarrow|Z|=\omega L \\
\text { If } \theta=-90^{\circ} \rightarrow|Z|=1 / \omega C \\
\text { If } \theta=0^{\circ} \rightarrow|Z|=R
\end{gathered}
$$

## Voltage Level Accuracy Limit

See the Measurement Accuracy Tables located in the Appendix. The tables contain formulas for calculating the Voltage Level Accuracies.

# INSTRUMENT DESCRIPTION PREPARATI ON FOR USE QUICK START INSTRUCTIONS OPERATING INSTRUCTIONS PROGRAMMING \& INTERFACING SERVICE INFORMATION <br> APPENDIX 

## Unpacking \& I nspection:

Each 3550 is put through a series of electrical and mechanical inspections before shipment to the customer. Upon receipt of your instrument unpack all of the items from the shipping carton and inspect for any damage that may have occurred during transit. Report any damaged items to the shipping agent. Retain and use the original packing material for reshipment if necessary.

Upon Receipt, inspect the carton for the following items:
Model 3550 General Purpose, Programmable LCR Meter
Model 3550 User's Manual CD
Power Cord

## § Safety Information \& Precautions:

The following safety information applies to both operation and service personnel. Safety precautions and warnings may be found throughout this instruction manual and the equipment. These warnings may be in the form of a symbol or a written statement. Below is a summary of these precautions.

## Terms in This Manual:

CAUTION statements identify conditions or practices that could result in damage to the equipment or other property.

WARNING statements apply conditions or practices that could result in personal injury or loss of life.

## Terms as Marked on Equipment:

CAUTION indicates a personal injury hazard not immediately accessible as one reads the marking, or a hazard to property including the equipment itself.

DANGER indicates a personal injury hazard immediately accessible as one reads the marking.

## $\triangle$

## Safety Information \& Precautions Cont'd:

## Symbols:

As Marked in This Manual:


This symbol denotes where precautionary information may be found.

As Marked on Equipment:

| ! | Caution - Risk of Danger |
| :---: | :---: |
| 4 | Danger - Risk of Electric Shock |
| $\stackrel{1}{\square}$ | Earth Ground Terminal- |
| \| | On |
| 0 | Off |
| $\dagger 7$ | Chassis Terminal |
| $\bigcirc$ | Alternating Current |
| $\perp$ | Earth Ground Terminal / Guard |

## Grounding the Equipment

This product is grounded through the grounding conductor of the power cord.
WARNING: To avoid electrical shock or other potential safety hazards, plug the power cord into a properly wired receptacle before using this instrument. The proper grounding of this instrument is essential for safety and optimizing instrument operation.

## Danger Arising from Loss of Ground

WARNING: If the connection to ground is lost or compromised, a floating potential could develop in the instrument. Under these conditions all accessible parts, including insulating parts such as keypads and buttons could develop a hazardous voltage and put the user at risk.

## ©

## Use the Proper Fuse

To avoid fire hazard, use only the correct fuse type as specified for the AC power supply in the "Preparation for Use"" or "Service" sections of this manual. Please note that the fuse rating for 100 \& 120 -volt operation is different than the rating for $200 \& 240$-volt operation. Information about the proper fuse type is also printed on the rear panel of the instrument.

Refer fuse replacement to qualified service personnel.

## Do Not Use in Explosive Environments

WARNING: The 3550 is not designed for operation in explosive environments.

## Do not Operate Without Covers

WARNING: This device should be operated with all panels and covers in place. Operation with missing panels or covers could result in personal injury.

## FOR QUALI FIED SERVI CE PERSONNEL ONLY

## ! Servicing Safety Summary:

## Do Not Service Alone

Do not perform service or adjustment on this product unless another person capable of rendering first aid is present.

## Use Care When Servicing with Power On or Off

Dangerous voltages may exist at several points in this product. To avoid personal injury or damage to this equipment, avoid touching exposed connections or components while the power is on. Assure that the power is off by unplugging the instrument when removing panels, soldering, or replacing components.
WARNING: The instrument power source is electronically controlled meaning that there is power present throughout the instrument even when the instrument is in the OFF state.
Always unplug the instrument and wait 5 minutes before accessing internal components.

## Power Source

This product is intended to connect to a power source that will not apply more than 250V RMS between the supply conductors or between either supply conductor and ground. A protective ground connection by way of the grounding conductor in the power cord is essential for safe operation.

## \. Line Voltage \& Fuse Selection:

## CAUTION: DO NOT APPLY POWER TO THE INSTRUMENT BEFORE READING THIS SECTION:

Unless other wise specified, the Model 3550 is delivered from TEGAM with its power supply set for $120 \mathrm{~V}, 60 \mathrm{~Hz}$ operation. However, the 3550 design allows it to operate under 100, 120V, 220 or $240 \mathrm{~V} @ 50 / 60$ operation. It is strongly recommended that the line voltage and fuse size be verified before powering the unit.

First, determine the supply voltage that the instrument will be operating under and verify that the supply voltage does not fall outside of the allowable ranges in the table below:

| LINE VOLTAGE RANGE |  | FUSE SIZE |
| :---: | :---: | :---: |
| $100 / 120 \mathrm{~V}$ | $90 \sim 132 \mathrm{VAC}$ | 1 A |
| $220 / 240 \mathrm{~V}$ | $198 \sim 250 \mathrm{VAC}$ | 0.5 A |

Make sure that the proper fuse size is installed.
Next, verify that the jumper block in the rear panel of the instrument is securely plugged into the correct position. There are four positions that the block may be set to. Set the jumper block to point to one of the four voltage settings. You can remove the jumper block by pulling it from the jumper socket.


Unit set for 120VAC Operation 50/60Hz

The instrument is ready for power up. Proceed to "Quick Start Instructions" for continued operation.

SPECIFICATIONS<br>PREPARATION FOR USE QUI CK START I NSTRUCTI ONS OPERATING INSTRUCTIONS PROGRAMMING \& INTERFACING SERVICE INFORMATION<br>APPENDIX

The Model 3550 is a versatile product, which can be used in many different configurations. Because of its ability to measure a large number of impedance parameters under a dynamic range of test frequencies, amplitudes, and configurations, its is highly recommended that the entire "Operating Instructions" Section of this manual be reviewed to insure proper use of this equipment.

This Quick Start section is designed to give the user a general instruction set for the speedy setup and measurement of impedance values where arbitrary measured values are needed and accuracy is not critical. Whenever additional information is applicable, a reference will be made to other parts of this manual so that the user, at their discretion, can decide whether or not to pursue additional information.

## Power the Unit

The power supply of the Model 3550 is designed for $50-60 \mathrm{~Hz}$ operations and a voltage range of $90-250$ VAC. It is assumed that the "Preparation for Use" section of this manual has been read an understood and the line voltage and fuse settings have been verified to be correct.

Power the unit by depressing the pushbutton located on the lower right corner of the front panel. Allow at least 30 minutes for the unit to warm up and verify that the unit will be operated in its specified operating environment described on page 1-12.

## I nstrument Settings

## Factory Default Settings

Before performing an actual impedance measurement, there are a number of test parameters, which must be defined. The factory default settings can be used for most general-purpose measurements.

The 3550 is shipped from the factory with default settings as follows:
Table 3.1 - Factory Default Settings

|  | Parameter | Setting |  | Parameter | Setting |
| :--- | :---: | :---: | :---: | :---: | :---: |
| $\mathbf{1}$ | DISPLAY A | Capacitance | $\mathbf{9}$ | Communications | *RS232 |
| $\mathbf{2}$ | DISPLAY B | Dissipation Factor | $\mathbf{1 0}$ | Trigger | INT |
| $\mathbf{3}$ | DISPLAY C | Frequency | $\mathbf{1 1}$ | PANEL | 0 |
| $\mathbf{4}$ | Comparator | Data Cleared | $\mathbf{1 2}$ | Circuit Mode | AUTO |
| $\mathbf{5}$ | Comparator | OFF | $\mathbf{1 3}$ | Range | AUTO |
| $\mathbf{6}$ | Zero Correction | Data Cleared | $\mathbf{1 4}$ | LOCK | OFF |
| $\mathbf{7}$ | Test Frequency | 1kHz | $\mathbf{1 5}$ | Test Voltage | 1.00 V |
| $\mathbf{8}$ | Measurement Mode | Open Terminal <br> Voltage |  |  |  |

* not storable in a setup location.

At any time during use, you may recall these default settings by pressing the [MAN/EXT] key while powering the unit.

NOTE: When the unit is reset to factory defaults, user-defined comparator settings and zero correction factors will be lost.

Table 3.2a - Control Command Summary

|  | 1 | Change measure item of DISPLAY A | A |
| :---: | :---: | :---: | :---: |
|  | 2 | Change measure item of DISPLAY B | B |
|  | 3 | Show measure frequency on DISPLAY C | FREQ |
|  | 4 | Show terminal voltage on DISPLAY C | V |
|  | 5 | Show measure. current on DISPLAY C | 1 |
| $\begin{aligned} & \text { D} \\ & 0 \\ & n \\ & n \\ & 0 \\ & 0 \\ & 0 \\ & 3 \\ & 3 \\ & 0 \\ & 0 \\ & \text { in } \end{aligned}$ | 6 | Change panel number | 0-9 |
|  | 7 | Change measurement frequency | FREQ $\rightarrow$ DISPLAY C's UP and DOWN |
|  | 8 | Change measurement voltage | $\mathrm{V} \rightarrow$ DISPLAY C's UP and DOWN |
|  | 9 | Carry out open correction | OPEN |
|  | 10 | Carry out short correction | SHORT |
|  | 11 | Change to auto range | RANGE's AUTO |
|  | 12 | Change to auto circuit mode | CIRCUIT MODE's AUTO |
|  | 13 | Change to fixed voltage mode | $\mathrm{V} \rightarrow \mathrm{CV} / \mathrm{CC}$ |
|  | 14 | Change the fixed voltage setting | When V and CV/CC LED are flashing, DISPLAY C's UP and DOWN |
|  | 15 | Change to fixed current mode | $\square \rightarrow \mathrm{CV} / \mathrm{CC}$ |
|  | 16 | Change the fixed current setting | When 1 and CV/CC LED are flashing DISPLAY C's UP and DOWN |
|  | 17 | Raise the range | RANGE's UP |
|  | 18 | Lower the range | RANGE's DOWN |
|  | 19 | Parallel equivalent circuits mode | PRL |
|  | 20 | Serial equivalent circuits mode | SER |
|  | 21 | Measure with continuous trigger | INT |
|  | 22 | Measure with manual (single shot) trigger | MAN/EXT $\rightarrow$ MAN/EXT $\rightarrow$ MAN/EXT $\rightarrow$ |
|  | 23 | Set comparator lower limit | LOW |
|  | 24 | Set comparator upper limit | HIGH |
|  | 25 | Turn comparator on | ON |
|  | 26 | Move cursor forward in setting mode | $\checkmark$ |
|  | 27 | Move cursor backward in setting mode | $\triangle$ |
|  | 28 | Set measurement frequency | SHIFT $\rightarrow 0 \rightarrow$ Frequency Value $\rightarrow$ ENTER |
|  | 29 | Set voltage for measurement or fixed voltage mode | SHIFT $\rightarrow 1 \rightarrow$ Voltage Value (V) $\rightarrow$ ENTER |
|  | 30 | Set current for fixed current mode | SHIFT $\rightarrow 2 \rightarrow$ Current Value (mA) $\rightarrow$ ENTER |
|  | 31 | Set number of measurements | SHIFT $\rightarrow 3 \rightarrow$ Number Setting $\rightarrow$ ENTER |

Table 3.2b - Control Command Summary cont'd

|  | 32 | Release Key Lock | SHIFT $\rightarrow 4 \rightarrow 0 \rightarrow$ ENTER |
| :---: | :---: | :---: | :---: |
|  | 33 | Lock Key | SHIFT $\rightarrow 4 \rightarrow 1 \rightarrow$ ENTER |
|  | 34 | No buzzer for decision | SHIFT $\rightarrow 5 \rightarrow 0 \rightarrow$ ENTER |
|  | 35 | Buzzer for GO decision ON | SHIFT $\rightarrow 5 \rightarrow 1 \rightarrow$ ENTER |
|  | 36 | Buzzer for NO GO decision ON | SHIFT $\rightarrow 5 \rightarrow 2 \rightarrow$ ENTER |
|  | 37 | Set start delay time | SHIFT $\rightarrow 6 \rightarrow$ delay time (ms) $\rightarrow$ ENTER |
|  | 38 | To use absolute value comparator | SHIFT $\rightarrow 7 \rightarrow 0 \rightarrow$ ENTER |
|  | 39 | To use percent comparator | SHIFT $\rightarrow 7 \rightarrow 1 \rightarrow$ ENTER |
|  | 40 | Set $1^{\text {st }}$ spot correction frequency | SHIFT $\rightarrow 8 \rightarrow 1 \rightarrow$ frequency value $\rightarrow$ ENTER |
|  | 41 | Set 2nd spot correction frequency | SHIFT $\rightarrow 8 \rightarrow 2 \rightarrow$ frequency value $\rightarrow$ ENTER |
|  | 42 | Set 3rd spot correction frequency | SHIFT $\rightarrow 8 \rightarrow 3 \rightarrow$ frequency value $\rightarrow$ ENTER |
|  | 43 | Set low frequency of correction | SHIFT $\rightarrow-\square \rightarrow$, $\rightarrow$ frequency value $\rightarrow$ ENTER |
|  | 44 | Set high frequency of correction | SHIFT $\rightarrow-\square \rightarrow 2 \rightarrow$ frequency value $\rightarrow$ ENTER |
|  | 45 | Do spot or open correction | SHIFT $\rightarrow$ OPEN |
|  | 46 | Do spot or open correction | SHIFT $\rightarrow$ SHORT |
|  | 47 | Change RS-232C baud rate | SHIFT $\rightarrow 9 \rightarrow 1 \rightarrow$ Setting $\rightarrow$ ENTER |
|  | 48 | Change RS-232C data length setting | SHIFT $\rightarrow 9 \rightarrow 2 \rightarrow$ Setting $\rightarrow$ ENTER |
|  | 49 | Change RS-232C parity setting | SHIFT $\rightarrow 9 \rightarrow 3 \rightarrow$ Setting $\rightarrow$ ENTER |
|  | 50 | Change RS-232C stop bit setting | SHIFT $\rightarrow 9 \rightarrow 4 \rightarrow$ Setting $\rightarrow$ ENTER |

Table 3.3-Shift Function Summary

| SHIFT 0 | Set measurement frequency |
| :--- | :--- |
| SHIFT 1 | Set voltage for measure voltage/fixed <br> voltage mode |
| SHIFT 2 | Set current for fixed current mode |
| SHIFT 3 | Set number of measurements |
| SHIFT 4 | Set key lock |
| SHIFT 5 | Set buzzer |
| SHIFT 6 | Set start delay time |
| SHIFT 7 | Set comparator mode |
| SHIFT 8 | Set spot correction frequency |
| SHIFT 9 | Set RS-232C communication parameters |
| SHIFT | S |
| SHIFT | OPEN |

## I nstrument Setup for Basic Measurements

To perform basic measurements with the Model 3550, perform the steps below: Refer to "Operating Instructions" for more details about specific commands or functions of the 3550. NOTE: The numerals in parentheses reference the Control Command Tables on the previous pages. The letters in parentheses reference the Settings Summary below:

* Perform an open and closed circuit zero correction \{Normal correction (9,10), Frequency limit correction (F), or Spot correction (E) \} on the test leads or fixture.
* Set DISPLAY A measurement parameters (1)
* Set DISPLAY B measurement parameters (2)
* Set measurement frequency ( 7 or 28 )
* Set measurement mode \{Voltage (8 or 29), Constant Voltage (A), or Constant Current (B) \}
* Set the comparator limits and operation if necessary \{Absolute Comparator (C) or Percent Comparator (D) \}
* Set the trigger mode \{Continuous (21) or One-Shot (22) trigger\}

Table 3.4-Settings Summary

| A | To use fixed voltage mode | * Set voltage for fixed voltage mode (14 or 29) <br> * Change to fixed voltage mode (13) |
| :---: | :---: | :---: |
| B | To use fixed current mode | * Set current for fixed current mode (16 or 30) <br> * Change to fixed current mode (15) |
| C | To use absolute value comparator | * Select absolute value comparator (38) <br> * Set comparator lower limit value (23) <br> * Set comparator upper limit value (24) <br> * Turn comparator ON (25) <br> * For comparator setting details, see absolute value comparator setting instructions. |
| D | To use percent comparator | * Select percent comparator (39) <br> * Set comparator lower limit value (23) <br> * Set comparator upper limit value (24) <br> * Turn comparator ON (25) <br> * For comparator setting details, see percent comparator setting instructions. |
| E | To use spot correction | * Set spot correction frequency (40~42) <br> * Carry out spot-open correction (45) <br> * Carry out spot-short correction (46) |
| F | To use frequency limit correction | * Set upper frequency limit for correction (44) <br> * Set lower frequency limit for correction (43) <br> * Carry out open correction (9) <br> * Carry out short correction (10) |

## Setting the Absolute Comparator

To set the Absolute Value Comparator, following the procedure below:

1. Select either the upper or lower comparator limit.

To input an upper limit, press [HIGH]
To input a lower limit, press [LOW]
2. Input the BIN No.

After the [HIGH] or [LOW] key is pressed, the BIN LED will begin to flash. Use keys [1]~[9] to designate the number.
3. Input a limit value for DI SPLAY A

After selecting the bin number, use the cursor to highlight DISPLAY A.
Enter the 5 -digit upper or lower value using the keys [1]~[9]. When this is complete, the decimal point will flash.
Press [DP] to move the decimal point to the position of the setting value.
Use the cursor [ ] to highlight the unit. Here, each time [UNIT] is pressed, the unit will change. Designate the unit for the Nominal value.
4. Input a limit value for DI SPLAY B

When the setting for DISPLAY A is complete, use the cursor [ $\boldsymbol{\square}$ ] to highlight DISPLAY B. Enter the 5 digits, decimal point and unit as done for DISPLAY A.
If the setting is a negative value, use the cursors keys, [ $\boldsymbol{\square}$ ] or [ $\mathbb{4}$ ] to highlight the $1^{\text {st }}$ digit of DISPLAY B.
Press [-] to negate the value.
5. Finalize the Comparator Settings

If defining an upper limit, press [HIGH] to complete the setting.
If defining a lower limit, press [LOW] to complete the setting.
To input settings for other bins, repeat the steps above.
6. I nvalidating the DI SPLAY A or DI SPLAY B Comparator settings.

To invalidate the settings, take the cursor, [ $\boldsymbol{D}$ ] or [ 4], to any digit location in DISPLAY A or DISPLAY B. Then press [IGNORE] to invalidate the settings of DISPLAY A or DISPLAY B.

## NOTES:

* The comparator can only be set using panels [1]~[9]. [0] is not used.
* The above procedure applies only to the Absolute Value Comparator. The procedure for setting the Percent Comparator is different. Before attempting to set the Absolute Comparator limits, verify that the 3550 is in the Absolute Comparator Mode.
* After setting the limit values for the comparator, the measurement parameters for DISPLAY A and DISPLAY B cannot be changed. The measurement parameters must be defined before the comparator is set.
* For DISPLAY B, there are no units for D, Q, or $\theta$.


## Setting the Percent Comparator

To set the Percent Comparator, follow the procedure below.
The upper and lower limit for the nominal value are the same. For the threshold values, different values for the upper and lower limit must be set. In order to proceed, the 3550 must be in the percent comparator mode.

1. Select the Upper or Lower Limit to Enter the \% Comparator Mode

To input the Nominal value, press the [HIGH] key. (The [LOW] key may also be pressed to enter the \% Comparator Set Mode)
2. Select the Nominal Value Input Mode

To input the Nominal Value, press [0] when the first digit of DISPLAY C is flashing.
3. Input the BIN No.

After selecting the Nominal Value Input Mode, use the cursor [ $\boldsymbol{\nabla}$ ] to highlight the bin number, and then press [1]~[9] to select the desired bin.
4. Set the Nominal Value for DISPLAY A

After inputting the bin number, use the cursor, [ ] to highlight DISPLAY A. Enter a 5 digit Nominal Value for DISPLAY A using keys [0]~[9]. (NOTE: The $1^{\text {st }}$ digit, is restricted to only a " 1 " or " 0 " setting.)
When this is complete, the decimal point will flash. Press [D.P] to move the decimal point to the desired position. Then, use the cursor [ $\quad$ ] to highlight the unit. Press the [UNIT] key until the required unit annunciator is lit. This designates the measurement unit for the Nominal value.
5. Input the Nominal Value for DI SPLAY B

When the setting for DISPLAY A is complete, use the cursor [ $\quad$ ] to highlight DISPLAY B. Enter the 5 digits, decimal point and unit just as in DISPLAY A.
If the setting is to be a negative value, use cursors [ $\boldsymbol{D}$ ] or [ 4] to highlight the $1^{\text {st }}$ digit of DISPLAY $B$ then press [-] to negate the value.

## 6. Completing the Nominal Value Setting

Press the [HIGH] key to finalize the Nominal Value Setting for the \% Comparator.
(If the [LOW] key was pressed to enter into the \% Comparator Mode then press it instead of the [ HIGH ] key to exit the mode and finalize the settings.)
7. Set an Upper or Lower Limit for the \% Threshold Values

To input an upper limit threshold value, press the [HIGH] key. Press the [LOW] key to set the lower limit threshold value. Then, highlight the first digit of DISPLAY C and press [1].

## Setting the Percent Comparator

8. Input the BIN No.

After selecting the threshold value input mode, use the cursor key, [ $\quad$ ] to highlight the bin
LED, and then press [1]~[9] to select the desired bin.
9. Input the Threshold Value for DI SPLAY A

After entering the bin number, use the cursor key [ ] to highlight DISPLAY A.
Enter the 5 -digit threshold value for DISPLAY A using keys [0]~[9]. (The setting range is
from 000.00\%~199.99\%)
10. I nput the Threshold Value for DISPLAY B

Enter the 5-digit threshold value for DISPLAY B using keys [0]~[9]. (The setting range is 000.00\% ~ 199.99\%)
11. Finalizing the Setting

To finalize an upper limit, press [HIGH] or press [LOW] to finalize a low limit setting.
NOTE: Whether a high or low limit \% comparator setting is defined is determined in step 7.
To input settings for other bins, return to Step 1 and repeat the process.
12. Invalidating the DI SPLAY A or DISPLAY B Percent Comparator settings

To invalidate the settings, for threshold values, simply enter the Threshold Percent Comparator Set Mode and move the cursor to any segment in DISPLAY A or DISPLAY B. Then press [IGNORE] to invalidate the \% comparator settings for that DISPLAY.

## NOTES:

* The comparator can only be set using panels 1~9. 0 cannot be used.
* This procedure is only for the percent comparator setting. Note that the procedure for the absolute value comparator is different.
* Make sure the comparator mode is set for "Percent Mode" otherwise the procedure will not work correctly.
* After setting the limit values for the comparator, the measurement parameters for DISPLAY A and DISPLAY B cannot be changed. This means that the measurement parameters must be defined before the comparator settings.
* For DISPLAY B, there are no units for D, Q, or $\theta$.


## Basic Operation

The Model 3550 is a fully programmable LCR meter, designed for use in many different low and high frequency applications. There are ideal configurations of the 3550 for each type of measurement. These configurations optimize test conditions while enhancing accuracy and measurement speed. In order to maximize the effectiveness the 3550, the user should have a thorough understanding of the instrument's operation along with a basic knowledge of LCR measurement techniques. This section will provide the user with the necessary information to make accurate and repeatable measurements.

## Default Parameters

Each unit is delivered from the factory with predefined settings intended for general-purpose LCR measurement and ease of use. Chapter III, Quick Start Instructions, contains information on factory default settings.
$\wedge_{\text {caution: }}$

## NEVER APPLY DI RECT CURRENT TO THE MEASUREMENT TERMI NALS

Never apply direct voltage to the measuring terminals. When testing capacitors, always make sure that they are fully discharged otherwise damage to the instrument will result.

## NEVER MEASURE COMPONENTS IN A POWERED CIRCUIT

If you are measuring components, which are integrated into circuit boards, always check that power is disconnected from the circuit before taking measurements. When measuring transformers, always verify that no induced voltage is present before making connections.

## Measurement Tips

## Making Measurements that are Sensitive to Voltage and Current

The measured values of many components such as core-filled coils, layered ceramic capacitors etc. are dependent upon the applied level of test current or voltage. In applications where the test signal must remain constant, it is recommended that the range of the 3550 be manually set.

In the event that AUTO Range must be used, then operation of the 3550 in the "Constant Current" or "Constant Voltage" Mode will maintain signal levels while allowing range adjustments.

## Measuring Earth-Grounded Test Pieces

The L-side ( $\mathrm{L}_{\text {force }} \& \mathrm{~L}_{\text {sense }}$ ) of the measurement terminals is set up to be the virtual grounding point of the internal amplifiers. The L-side is a high-impedance point with zero electrical potential. These terminals cannot be directly connected to Earth Ground. Measurement of devices with one lead tied to earth ground is not recommended.

## Measurement Tips cont'd:

## Measurement Circuit Modes

When the Measurement Circuit Mode is set to "AUTO", the Parallel Mode (PRL) or the Serial Mode (SER) is automatically selected by the instrument based on the Measurement Range. The measurement range is determined by the instrument by the magnitude of $|Z|$ with no regards to $D$ or Q of the DUT.

Thus, the measured values of a component will vary depending on whether series or parallel equivalent circuit modes are used. The relationship between series and parallel equivalent circuit measurements is illustrated in Table 4.1.

Table 4.1: Relationship Between Series and Parallel Equivalent Circuit Values

| Equivalent Circuit Mode |  | Dissipation Factor: D | Conversion Formula |  |
| :---: | :---: | :---: | :---: | :---: |
|  | $\begin{aligned} \text { (SER) } & \\ \text { LS } & \mathrm{R} \end{aligned}$ | $\mathrm{D}=\frac{\mathrm{R}}{\omega L_{\mathrm{s}}}=\frac{1}{\mathrm{Q}}$ | $\mathrm{LP}^{\prime}=\left(1+\mathrm{D}^{2}\right) \cdot \mathrm{Ls}$ | $\mathrm{G}=\frac{\mathrm{D}^{2}}{1+\mathrm{D}^{2}} \cdot \frac{1}{R}$ |
| L | $\text { (PRL) } \overbrace{\cdot 1 / 0}^{G}$ | $D=\omega L_{p} G=\frac{1}{Q}$ | $\mathrm{Ls}=\frac{1}{1+\mathrm{D}^{2}} \cdot \mathrm{Lp}$ | $\mathrm{R}=\frac{\mathrm{D}^{2}}{1+\mathrm{D}^{2}} \cdot \frac{1}{\mathrm{G}}$ |
|  | $\begin{gathered} \text { (SER) } \\ C_{s} \end{gathered}$ | $D=\omega C_{s} R=\frac{1}{Q}$ | $\mathrm{CP}_{\mathrm{P}}=\frac{1}{1+\mathrm{D}^{2}} \cdot \mathrm{Cs}$ | $\mathrm{G}=\frac{\mathrm{D}^{2}}{1+\mathrm{D}^{2}} \cdot \frac{1}{\mathrm{R}}$ |
| c | $\text { (PRL) } \overbrace{\sim_{-}}^{\mathrm{G}} \text {, }$ | $\mathrm{D}=\frac{\mathrm{G}}{\omega \mathrm{C}_{\mathrm{P}}}=\frac{1}{\mathrm{Q}}$ | $\mathrm{Cs}=\left(1+\mathrm{D}^{2}\right) \cdot \mathrm{Cp}$ | $\mathrm{R}=\frac{\mathrm{D}^{2}}{1+\mathrm{D}^{2}} \cdot \frac{1}{\mathrm{G}}$ |

As a general rule, when measuring components where the reactive component is high, $>10 \mathrm{k} \Omega$ then the parallel equivalent mode should be used as parallel leakage becomes more significant to the measurement.
For low reactance components, $<10 \Omega$ the series equivalent mode should be used since lead resistance becomes more significant to the reading than parallel leakage.
For measurements of component values that fall somewhere in between, follow the manufacturer's recommendations.

## Measurement Tips cont'd:

## Negative Capacitance or Inductance Readings

If a capacitor is connected to the 3550 while in the inductance measurement mode or if an inductor is connected to the 3550 while in the capacitance mode, a negative sign will appear in the display. The negative sign in the capacitance mode indicates an inductive measurement. The negative sign in the inductance mode indicates a capacitive measurement.
If the resonant frequency of a DUT is reached, a "-" sign will appear in the display.

## Zero Correction of Parasitic I mpedance

"Open Correction" is for the purpose of compensating for the stray capacitance and stray conductance of cables or test fixtures. Executing an "Open Correction" procedure on the test leads of fixture before measurement of high impedance DUTs improves measurement accuracy.
"Short Correction" compensates for the residual inductance and resistance of cables or test fixtures. Performing a "Short Correction" procedure on cables or test fixture before measurement of low impedance DUTs improves measurement accuracy.

If the condition or position of a cable or test fixture changes, you MUST carry out Zero Correction to compensate for the change. When performing a Zero Correction, keep hands and metallic objects away from the cable or fixture.

Table 4.2: Short and Open Null Connections

| Connection | Open Correction |  | Short Correction |  |
| :---: | :---: | :---: | :---: | :---: |
|  | Correct | Incorrect | Correct | Incorrect |
| Terminal Only |  | $\stackrel{G}{\mathrm{G}} \stackrel{\mathrm{~L}}{\mathrm{H}}$ | $\text { G } L$ | G L H |
| 5-Terminal |  |  |  | G |
| Kelvin Klips $^{\text {™ }}$ | $\underbrace{L_{F}}_{L_{s}} \underbrace{H_{F}}_{H_{s}}$ |  | $\begin{array}{ll} \mathrm{L}_{\mathrm{F}} & \mathrm{H}_{\mathrm{F}} \\ \hline \mathrm{~L}_{\mathrm{s}} & \mathrm{H}_{\mathrm{s}} \end{array}$ | $\underbrace{\mathrm{L}_{\mathrm{F}}}_{L_{\mathrm{L}}} \mathrm{H}_{\mathrm{S}}$ |

## Measurement Tips cont'd:

## Test Lead Requirements

Four-wire Kelvin-type cables or fixtures must be used with the 3550 in order to obtain accurate impedance measurements. The Kelvin measurement technique allows significant accuracy advantage over the two-wire method. This is because it virtually eliminates lead resistance and inductance and reduces stray capacitance between the source and sense leads.
Two of the four conductors are designated as source leads. These source leads provide the precision test current that will be referenced in making the resistance measurement. Since current is the same throughout a series circuit, the lead resistance of the test leads will not have any effect on the level of reference current.

The other two conductors are designated as voltage sense leads. These leads originate from a high impedance, volt measurement circuit. When these leads are terminated at the points of contact, an exact resistance reading is calculated by the 3550 's microprocessor. The series lead resistance of the voltage sense leads is negligible due to the high impedance of the voltage measurement circuitry within the 3550 .

Figure 4.1a: Four-Wire Kelvin Measurement


Figure 4.1b: Proper Application of Four Wire Kelvin Measurement


## Measurement Tips cont'd:

## Measurement Signal Levels

Measurement signal levels are adjustable between $0.01 \mathrm{~V} \sim 5.00 \mathrm{~V}$. It is recommended that the voltage level be kept at a high value (usually IV or larger) to avoid potential stability problems associated with test frequency, device impedance and noise.

## Series or Parallel Circuit Modes

The "CIRCUIT MODE" should always be "AUTO" mode, unless there is a special circumstance that requires otherwise. The 3550 is in the AUTO circuit mode when the pushbutton's LED is illuminated. Manually setting the circuit mode should only be done in special circumstances where series or parallel measurement is necessary even if some discrepancy is known to occur.

## Auto Range Switching Threshold

When using Auto Range for measurement, the relationship between the switching direction and indicated switching values are as follows: (When Dissipation Factor: $D=0$ )

$$
\begin{array}{ll}
\text { Range UP } & \text { When }|Z| \geq 19999 \text { counts } \\
\text { Range DOWN } & \text { When }|Z| \leq 17999 \text { counts }
\end{array}
$$

As the dissipation factor, D increases then these threshold values will change.

## Display Resolution

The absolute impedance, $|Z|$ of the DUT determines the range of the 3550 . All subsequent measurements will display with a resolution that is consistent with the instrument's current range setting.

## AC Resistance of Coils with Cores

In most cases the AC resistance of a coil with no core at low frequencies is the same as the DC resistance. This is not the case for coils with high permeability cores such as ferrite or iron. Higher permeability will promote core losses from an AC signal causing the resistance measurement to appear larger than it would be for a DC measured resistance value. Therefore, an inductance measurement taken at 42 Hz (the lowest frequency setting of the 3550 ) will not necessarily reflect a DC equivalent resistance value.

## Front Panel Description

## Front Panel Layout



Figure 4.2: Front Panel layout

Except for the "POWER" switch, a buzzer will be sounded whenever the function of a switch is changed.

## Front Panel Description cont'd:

## 1 - [POWER] Switch - [POWER]

With the power switch in the down state, power is applied to the 3550 and in the up state power is off. When the power is turned on, the remaining operational switches will retain the same status as they had before the power was previously turned off.
If the power is turned on while simultaneously pushing the [MAN/EXT] Key, the machine will return to its factory default settings.

2 "CI RCUIT MODE" Panel - [AUTO] [SER] [PRL]
This panel contains the keys used for setting the Series or Parallel Equivalent Circuit Mode. When verifying incoming component values it is usually good practice to consult the manufacturer for the recommended test mode.
In general, parallel mode is used when the reactance of a device is large. Parallel mode should be used when a capacitor's leakage or an inductor's core losses significantly affects the reading.
Series mode is recommended for small reactance measurements in capacitors and inductors where series lead resistance must be considered and leakage and core losses become negligible.

- [AUTO] - When this key is illuminated, the instrument is in AUTO equivalent circuit mode. This means that the 3550 will automatically select either series or parallel equivalent circuit mode based on the impedance of the DUT. It does not necessarily mean that the correct equivalent circuit mode will be selected.
- [SER] - Series equivalent circuit mode is typically desirable for low reactance measurements. This is because Rs or series resistance becomes more significant than parallel resistance to the measured value.
- [PRL] - Parallel equivalent circuit mode is often more effective for measurement of impedances with high reactive components. This is because in a capacitor or inductor with a high reactance, the parallel leakage is more significant to the measured value.

3 "TRIGGER" Panel - [INT] [MAN/EXT]
Select either an internal or external trigger by pressing either the [INT] or [MAN/EXT] key. The active trigger mode of the 3550 is indicated by an illuminated pushbutton.

- [INT] - When the [INT] key is pressed, the 3550 operates in the continuous trigger mode. The instrument automatically takes readings at regular intervals.
- [MAN/EXT] - Depressing the [MAN/EXT] key will put the 3550 into manual one-shot trigger mode, which requires the [MAN/EXT] key to be pressed for each reading.


## Front Panel Description cont'd:

4 "ZERO" Panel - [OPEN] [SHORT]
Performing OPEN and SHORT corrections before making an impedance reading greatly improves measurement accuracy. Refer to page 4-4, "Zero Correction of Parasitic Impedance" for connection diagrams and other details regarding these procedures.

- [OPEN] - The OPEN circuit zero correction procedure compensates for stray capacitance and conductance between test leads/fixture. Pressing the [OPEN] key initiates the open circuit zero correction procedure. Make sure that the test fixture is in the open state before performing the OPEN circuit zero correction procedure.
- [SHORT] - The SHORT circuit zero correction procedure compensates for residual resistance and inductance in the test leads/fixture. Pressing the [SHORT] key initiates this procedure. Make sure that the test fixture is shorted before performing the SHORT circuit zero correction procedure.

There are three variations of zero correction procedures:

1) Standard Zero Correction: corrects all frequencies. This process requires several minutes to step through all of the test frequencies. See 4 (p. 4-9) for details.
2) Spot Zero Correction, allows up to three user-defined frequencies to be corrected: see [SHIFT] $\rightarrow$ [8] (p. 4-14) to define spot frequencies; [SHIFT] $\rightarrow[\mathrm{OPEN}]$ (p. 4-16) for Open circuit spot correction; \& [SHIFT] $\rightarrow[$ SHORT] (p. 4-16) for short circuit spot correction.
3) Correction Frequency Limit Mode: allows the user to define a range of test frequencies to be zero corrected during a standard zero correction.
Refer to [SHIFT] $\rightarrow[-]$ (p. 4-16) and 4 (p. 4-9) for more details.

## 5 "RANGE" Selection Panel - [AUTO] [DOWN] [UP]

The Range panel is used to select either automatic or manual measurement ranges. If AUTO range is used to find the correct measurement range and the 3550 is then switched to MANUAL range, the 3550 will retain the current measurement range.

- [AUTO] - Pressing the [AUTO] key will toggle between Auto and Manual Range Modes. When the 3550 is in the AUTO mode, the pushbutton will be illuminated. When the instrument is in the manual mode the AUTO pushbutton is not illuminated.
- [DOWN] - In the manual mode, pressing the [DOWN] key will lower the range of the instrument. The [DOWN] key will flash to indicate when the current range is under ranged and needs to be lowered for a reading to take place. When the [DOWN] key is pressed, then an audible beeper will sound to indicate that the range has been lowered.
- [UP] - In the manual mode, pressing the [UP] key will raise the current range of the 3550. The [UP] key will flash to indicate when the current range is over ranged and needs to be raised in order for a reading to take place. When the [UP] key is pressed, then an audible beeper will sound to indicate that the range has been raised.


## Front Panel Description cont'd:

## 6 [SHI FT] Key

The [SHIFT] key has dual functionality. Its primary purpose is to allow access to the secondary functions of the numeric keys. Its secondary function allows the user to switch from Remote communications Mode (GPIB or RS-232C Operation) to Local (Front Panel) Operation.

Below is a summary of the secondary functions accessible by pressing the [SHIFT] key and then a corresponding function key. The secondary function keys are [0]~[9], [OPEN], [SHORT] and [-]. For descriptive convenience, notation such as [SHIFT] $\rightarrow$ [0] etc will be used to indicate that first the [SHIFT] Key should be pushed, and then the [0]" Key.

## [SHI FT] $\rightarrow$ [0]: Frequency Set Mode

The 3550 test frequency settings may be programmed from 42.0 Hz to 5.00 MHz with a resolution of three significant digits. If DISPLAY C is set to indicate test frequency and the 3550 is in the Measurement mode, the frequency can be adjusted changed by pressing the [UP] and [DOWN] keys in the DISPLAY C panel.
Pressing [SHIFT] $\rightarrow$ [0] will cause the 3550 to enter the frequency set mode.

## Entering the Frequency Values

The most significant digit in DISPLAY C will flash indicating that a new value must be entered. Press a key from [0]~[9] to set the value of the first digit and to proceed to set the next digit value. Once again, press a key from [0]~[9] and proceed to the next digit.

## Set the Decimal Point Location

Once values for all of the three digits have been defined, the decimal point will start to blink indicating that the decimal point needs to be positioned. Press the [DP] key and notice that the position of the decimal point will change. Continue to press the [DP] key until the decimal point is positioned correctly.

## Select the Frequency Units

Press either the [CURSOR - ] or [CURSOR 4] keys repeatedly until one of the frequency units annunciators ( $\mathrm{Hz}, \mathrm{kHz}$, or MHz ) begins to blink. This indicates that the frequency units mode is now active. Press the [UNIT] key until the desired frequency units annunciator starts to blink.

## Verify and Set the Frequency

The user can go back and edit any of the previous settings by pressing the [CURSOR $\quad$ ] or [CURSOR 4] keys to access the settings. Verify that all frequency settings are correct and then press the [ENTER] key. This will store the new frequency settings and return the instrument back to measurement mode.

## Front Panel Description cont'd:

> [SHI FT] $\rightarrow$ [1]: Test Voltage Set Mode
> *See the Appendix for detailed information concerning the measurement ranges for constant current or constant voltage modes and for instructions for setting either of these modes.
> The 3550 test voltage values may be modified if the open circuit voltage or constant voltage setting is displayed on DISPLAY C. Constant voltage mode is indicated when the [CV/CC] and [V] pushbuttons are illuminated. The 3550 is in open circuit voltage mode when only the [V] key is lit.
> The Model 3550 has programmable test voltages from $0.01 \mathrm{~V} \sim 5.00 \mathrm{~V}$ for test frequencies of $42.0 \mathrm{~Hz} \sim 1.00 \mathrm{MHz}$. For test frequencies above 1.00 MHz , the voltage can be adjusted between 0.01V and 1.00 V . Test voltages are adjustable in steps of 0.01 V and are displayed in DISPLAY C to three significant digits. Refer to the Appendix to calculate the maximum voltage range of the constant voltage mode.
> If DISPLAY C is set to indicate test voltage and the 3550 is in the Measurement mode, the voltage amplitude can be incremented or decremented by pressing the [UP] and [DOWN] keys in the DISPLAY C panel. If the [UP] and [DOWN] keys are held down the 3550 will increase the speed at which the voltage is incremented or decremented.
> If more dramatic changes are required, then the test voltage must be manually entered by accessing the 3550's voltage set mode.
> Pressing [SHIFT] $\rightarrow$ [1] will cause the 3550 to enter the voltage set mode. Below are instructions to set the test voltage.

## Enter the Voltage Values

The most significant digit in DISPLAY C will flash indicating that a new value must be entered. Press a key from [0]~[9] to set the value of the first digit and to proceed to set the next digit value. Once again, press a key from [0]~[9] and proceed to the next digit.

## Verify and Set the Test Voltage

Once all three digits have been entered, double-check the final voltage value. The values are changed by pressing the [CURSOR - ] or [CURSOR 4] keys and entering a new value. Press the [ENTER] key to save the voltage setting and to return back to the measurement mode.
If a programmed voltage exceeds the instrument's sourcing capability, the 3550 will beep three times and not allow the illegal value to be saved if the [ENTER] key is pressed.
[SHIFT] $\rightarrow$ [2]: Test Current Set Mode
*See the Appendix for detailed information concerning the measurement ranges for constant current or constant voltage modes and for instructions for setting either of these modes.
The 3550 test current values may be modified if the open circuit current or constant current setting is displayed on DISPLAY C. Constant current mode is indicated when the [CV/CC] and [I] pushbuttons are illuminated. The 3550 is in open circuit current mode when only the [I] key is lit.

Programmable test currents are available from $0.01 \mathrm{~mA} \sim 99.99 \mathrm{~mA}$ for test frequencies of $42.0 \mathrm{~Hz} \sim 1.00 \mathrm{MHz}$. For test frequencies above 1.00 MHz , the current can be adjusted between 0.01 mA and 20.00 mA . The 3550 's test current is adjustable in 0.01 mA steps and is displayed to three significant digits. Refer to the Appendix for instructions to calculate the maximum test current available in the constant current mode for a given impedance.

## Front Panel Description cont'd:

## [SHIFT] $\rightarrow$ [2]: Test Current Set Mode cont'd:

If DISPLAY C is set to indicate test current and the 3550 is in the Measurement mode, the current amplitude can be incremented or decremented by pressing the [UP] and [DOWN] keys in the DISPLAY C panel. If the [UP] and [DOWN] keys are held down the instrument will increase the speed at which the current is incremented or decremented.
The test current can be manually entered by accessing the instrument's current set mode. Below are instructions to manually set the test current.

## Enter the Current Values

Press [SHIFT] $\rightarrow$ [2] to enter the current set mode. The most significant digit in DISPLAY C will flash indicating that a new value must be entered. Press a key from [0]~[9] to set the value of the first digit and to proceed to set the next digit value. Once again, press a key from [0]~[9] and proceed to the next digit.

## Verify and Set the Test Current

Once all three digits have been entered, double-check the final current value. Any of the digits may be accessed and modified by pressing the [CURSOR - ] or [CURSOR 4] keys and entering a new value. Press the [ENTER] key to save the current setting and to return back to the measurement mode. The 3550 will beep three times and will not return to measurement mode if a programmed test current exceeds the instrument's sourcing capability.

## [SHIFT] $\rightarrow$ [3]: Averaging Set Mode

You can define the number of measurements the 3550 makes before it produces a readable measurement. Averaging is used to stabilize the output reading and to increase the accuracy of a reading. To set the number of averages per reading, press [SHIFT] $\rightarrow$ [3]. The active average setting will be displayed on DISPLAY B. The first digit will flash indicating that one of the numeric keys, [0]~[9] must be pressed to set the value of the first digit. Once a value has been entered then the next digit will flash. Enter the desired values for the three digits and press the [ENTER] key to store the new setting. The number of averages may be set from 1~100 readings. If an illegal value is attempted the instrument will beep three times when the [ENTER] key is pressed to indicate that the attempted value is outside of the instrument's acceptable range.

## [SHIFT] $\rightarrow$ [4]: Key Lock Mode

In the Key Lock mode, all front panel keys except the [SHIFT]" Key, [4] Key, and (in the case that the Measurement Trigger is set to Manual) the [MAN/EXT] Key will be locked. The Key lock mode is used to protect the 3550 settings from unintentional changes. To access the Key Lock Mode settings, press the [SHIFT] $\rightarrow$ [4] keys. A single digit, either a " 1 " or a " 0 " will be displayed in DISPLAY B. Set the digit to " 1 " to lock the front panel or to " 0 ' to unlock the front panel keys. Press the [ENTER] key to finalize the setting.

## Front Panel Description cont'd:

## [SHI FT] $\rightarrow$ [5]: Comparator Buzzer Function

Press the [SHIFT] $\rightarrow$ [5] keys to enter the Buzzer Settings Mode. The active setting, 0~2 will blink in DISPLAY B.

| Buzzer Function | Value |
| :--- | :---: |
| Buzzer OFF | 0 |
| GO = Buzzer ON | 1 |
| NO-GO $=$ Buzzer ON | 2 |

Press either [0], [1] or [2]. The new entry will appear in DISPLAY B. Press [ENTER] to finalize the setting and to return to the measurement mode.

## [SHI FT] $\rightarrow$ [6]: Trigger Delay Time

The trigger delay time is programmable from $0 \sim 10,000$ milliseconds (10s). It is used to add a time delay immediately after the detection of a trigger signal from either the [MAN/EXT] key, external control device (I/O Control Connector), RS-232C or GPIB Interfaces.
In the Trigger Delay Time Settings Mode, the active setting for the trigger delay time will appear flashing on DISPLAY B. The default setting for the Trigger Delay Time is "00000 ms" The active flashing number can be changed by highlighting the active digits by pressing the [CURSOR - ] or [CURSOR 4] keys and entering a new value by pressing the [0]~[9] keys. When all the necessary digits have been changed press the [ENTER] Key to finalize the settings and return to Measurement mode.

## Front Panel Description cont'd:

## [SHIFT] $\rightarrow$ [7]: Comparator Functions Mode

Press [SHIFT] $\rightarrow[7]$ to access the Comparator Functions Mode. Either a flashing " 0 " or a " 1 " will appear on DISPLAY B. The meaning of the numbers is as follows:

0: Absolute Value Comparator Function
1: Percent Comparator Function

To change the flashing digit, press either [0] or [1] and press [ENTER] to store the new setting and return to the measurement mode.
[SHI FT] $\rightarrow$ [8]: Defining Spot-Correction Frequencies for Zero Adjustments The spot-correction frequency mode allows the user to identify up to three specific test frequencies where open and short-circuit, zero adjustments may be performed. This feature condenses the default zero adjustment procedure by limiting the zero adjustments to user-defined frequency points instead of stepping through the entire range of test frequencies ( $42 \mathrm{~Hz} \sim 5 \mathrm{MHz}$ ). Performing spot-correction frequency zero adjustment saves time by eliminating the zero adjustment of unused test frequencies.

Select the Spot Frequency Number
Press [SHIFT] $\rightarrow$ [8] to enter the spot-correction frequency editing mode. The BIN LED will display a flashing " 1 ", " 2 ", or " 3 ". Press either the [1], [2], or [3] keys to select the spot frequency you would like to set.
Entering the Spot Frequency Value
Once a key is pressed, DISPLAY C will display "---" indicating that a spot frequency must be defined. Press the [0]~[9] keys to enter the spot frequency digits. Next, press the [DP] key to position the decimal point. Press either of the [CURSOR - ] or [CURSOR 4 ] keys to highlight the frequency units. Press the [UNIT] key until the desired frequency units annunciator starts to blink. Press the [ENTER] key to finalize the spot frequency setting.

To disable the Spot Correction Frequency, make sure that you are in the spot frequency editing mode (press [SHIFT] $\rightarrow$ [8]) use the [CURSOR] keys to highlight DISPLAY C. When this is done, press the [IGNORE] key to erase the current spot frequency setting.

## Front Panel Description cont'd:

## [SHI FT] $\rightarrow$ [9]: RS-232C Settings Mode

For the RS-232C, the baud rate, data length, parity and stop bit can be defined by the user. Press the [SHIFT] $\rightarrow$ [9] key to enter into the RS-232C setup mode.

After entering the RS-232C setup mode, you will notice that the BIN LED will begin to blink. Press a key from [1] ~[4] to select the RS-232C parameter that you wish to set.

| [1]: Set the Baud Rate | Default=5,9600BPS |
| :--- | :--- |
| [2]: Set the Data Length | Default=1,8 Bits |
| [3]: Set the Parity | Default=0, No Parity |
| [4]: Set the Stop Bit | Default=0, 1 Stop Bit |

Notice that after selecting a parameter from 1-4, DISPLAY B will show a number that corresponds to the parameter setting as summarized in the tables below: Use the tables to determine the appropriate setting for the RS-232C communications. Use the [CURSOR $\downarrow$ ] or [CURSOR 4] keys to navigate between the RS-232C parameter and the setting on DISPLAY B.
Press the [ENTER] key to finalize the settings and return to measurement mode.

| BI N Display "1" |  |
| :--- | :--- |
| Baud Rate Settings |  |
| DISPLAY <br> Settings | BS-232C Settings |
| 0 | 300 bps |
| 1 | 600 bps |
| 2 | 1200 bps |
| 3 | 2400 bps |
| 4 | 4800 bps |
| 5 | 9600 bps |
| 6 | 19.2 kbps |
| 7 | 38.4 kbps |


| BI N Display "2" <br> Settings | Data Length |
| :--- | :--- |
| DI SPLAY B <br> Settings | RS-232C <br> Settings |
| 0 | 7bits |
| 1 | 8bits |


| BI N Display "3" | Parity Settings |
| :--- | :--- |
| DI SPLAY B <br> Settings | RS-232C <br> Settings |
| 0 | No parity |
| 1 | Odd parity |
| 2 | Even parity |


| BI N Display "4" | Stop Bit Settings |
| :--- | :--- |
| DI SPLAY B <br> Settings | RS-232C <br> Settings |
| 0 | 1bit |
| 1 | 2 bit |

## Front Panel Description cont'd:

## [SHIFT] $\rightarrow$ [-]: Correction Frequency Limit Setting Mode

As an alternative to zero correcting the entire frequency range $42 \mathrm{~Hz} \sim 5 \mathrm{MHz}$, this function allows the user to set the correction frequency range in terms of upper and lower limits. Press [SHIFT] $\rightarrow[-]$ to enter the Correction Frequency Setting Mode. The "BIN" LED will be flashing. Press either [1] to edit the low limit correction frequency or [2] to edit the high limit correction frequency.
Use the [CURSOR -] or [CURSOR 4] keys to navigate between the "BIN" LED, DISPLAY C Digits, Decimal Point and Frequency Units. To change the frequency value indicated on DISPLAY C, simply press the [0]~[9] keys.
Press the [DP] key to change the position of the decimal point and use the [UNIT] key to select $\mathrm{Hz}, \mathrm{kHz}$, or MHz units.
Press the [ENTER] key in order to finalize the new setting and to return to measurement mode.

NOTE: While in the Spot Correction Frequency Mode, the Spot Correction Frequency high or low limit setting can be enabled or disabled. This is done by pressing the [IGNORE] key.

## [SHI FT] $\rightarrow$ [OPEN]: Spot Correction Mode (Open Correction)

The spot correction Mode is used for making open and short-circuit frequency corrections. Pressing the [SHIFT] $\rightarrow$ [OPEN] keys will allow an open circuit, spot frequency correction to take place. The open circuit correction is performed only on the three spot frequencies that are defined by pressing [SHIFT] $\rightarrow$ [8], (see Defining Spot-Correction Frequencies for Zero Adjustments).
Note that Spot Frequency Zero Corrections have precedence over Normal Zero Corrections. This means that the open and closed-circuit, zero correction factors for the spot frequencies will be stored and retained in the instrument's memory and will be written over unless an additional spot frequency correction procedure is performed. Performing a standard zero correction procedure will write over the zero adjustment factors of all test frequencies except the three user-defined, spot correction frequencies.

## [SHIFT] $\rightarrow$ [SHORT]: Spot Correction Mode (Short Correction)

Pressing [SHIFT] $\rightarrow$ [SHORT] initiates the Short-Circuit, Spot Frequency Correction process. The offset adjustment affects only the three user-defined Spot Correction Frequencies discussed in the, Defining Spot-Correction Frequencies for Zero Adjustments section ([SHIFT] $\rightarrow$ [8]).
Like the Open Circuit Spot Frequency Correction Mode, Short Circuit Spot Corrections have precedence over Normal Short Circuit Zero Corrections. Closed circuit, spot correction factors will be stored and retained in the instrument's memory and cannot be written over unless an additional spot frequency correction procedure is performed. Performing a standard zero correction procedure will write over the zero adjustment factors of all test frequencies except the three user-defined, spot correction frequencies.

## Front Panel Description cont'd:

## 7 "UNKNOWN" Terminals Panel

Four BNC-type terminals plus one GUARD are available for making shielded or unshielded Kelvintype measurement connections to the DUT. Their designations and functions are summarized below:

Table 4.3 - Unknown Terminals

| Connection <br> Type/ Description | Measurement Function |
| :--- | :--- |
| BNC L |  |
| BNCRCE | Low Side Current Source |
| BNC $H_{\text {SENSE }}$ | Low Side Voltage Sense |
| BNC $H_{\text {SENSE }}$ | High Side Current Source |
| Binding Post GUARD | High Side Voltage Sense |

## 8 "COMPARATOR LI MIT SET" Panel - [CURSOR -] [CURSOR 4] [LOW] [HIGH]

When programming comparator settings, the keys in the Comparator Limit Set Panel are used to define the DISPLAY A \& DISPLAY B Comparator values. The two left most keys are the [CURSOR -] or [CURSOR 4] keys. In the comparator set mode, these cursor keys allow navigation between the present BIN number (1-9) and DISPLAY A and DISPLAY B comparator value settings.

If a value is defined for either DISPLAY A or DISPLAY B (by pressing digits [0]~[9] while the DISPLAY digits are blinking.) then the functionality of the [CURSOR - ] or [CURSOR 4] keys extends to allow navigation of the comparator value's decimal point location and selection of the DISPLAY A and DISPLAY B units of measure.

The Comparator's High and Low Limit Values for DISPLAY A and DISPLAY B can be set by pressing the [LOW] and [HIGH] Keys while in the measurement mode. Pressing either of these keys will put the 3550 into the Comparator Limits Set Mode.
Once in the Comparator Limits Set Mode, the BIN\# and values for DISPLAY A and DISPLAY B comparator settings can be defined by using the secondary functions (blue text) of the keys located in the CIRCUIT MODE, RANGE, DISPLAY C, and DISPLAY A-B Panels. These secondary functions include [0]~[9], [-], [D.P.], [UNIT], and [IGNORE] commands.

NOTE: Only panels 1~9 can have comparator limit values assigned to them.

## 9 The "GUARD" Terminal

This terminal is connected to the chassis of the 3550. When measuring High-Impedance devices, connect the device's shield to this binding post.

## Front Panel Description cont’d:

10 Remote Interface Status LEDs - "SRQ" "LTN" "TLK" "RMT"
These LEDs indicate the status of remote communications using the 3550's standard RS-232C and optional GPIB (IEEE-488.2) interfaces
All four annunciators are used for GPIB communications. If the RS-232C is the controller, then only the "RMT" LED is used.

## 11 "PANEL" Selector Switch

Pressing the [0-9] key in the Panel section allows the user to select a preset panel setting from 09. Each consequent press of the [0-9] key will increment to the next preset panel number. The active instrument settings are automatically updated to the panel number indicated on the seven segment LED (Panel Display LED). If the instrument settings are changed while a panel number ( $0-9$ ) is active and the panel key is pressed then the existing settings will be stored into the panel location indicated by the Panel Display LED.
Only panels 1~9 can have comparator limit values assigned to them.

## 12 "PANEL" Display LED

The PANEL Display LED is a seven segment LED that displays the active panel setting.
Press the [0-9] key located in the Panel Section to increment through panel settings 0-9.

## 13 "DI SPLAY A" Parameter Selection Key - [A]

Press this key to select the measurement parameter of DISPLAY A. Measurements of $\mathrm{L}, \mathrm{C}, \mathrm{R},|\mathrm{Z}|$ and $|Y|$ are available.

## 14 "DISPLAY A"

Measured values of $\mathrm{L}, \mathrm{C}, \mathrm{R},|\mathrm{Z}|$, and $|\mathrm{Y}|$ are shown in this panel. The measurements values range from 0000 to 19999 and are displayed with $4^{1 / 2}$ - digit resolution. In addition, units of measure are annunciated above and beside the display for reading convenience.
To change the parameters shown by DISPLAY A, press the [A] key located in the DISPLAY A-B instrument panel until the desired measurements are shown.

## 15 "BI N" Display LED

The BIN Display LED is a seven segment LED that displays the active sorting bin number of the Comparator. When the Comparator is ON, this LED displays which BIN Number the present measurement is associated with. "1" through "9" are for OK products, while "0" is reserved for defects such as open circuit conditions.

## Front Panel Description cont'd:

## 16 Comparator State Annunciators

Located in the Comparator Panel there are three total comparator state annunciators. The annunciators become active when the comparator is on. The comparator is turned on by pressing the [ON] key in the Comparator Panel. See below for a summary of the annunciator functions.

| Annunciator | Functional Description |
| :--- | :--- |
| DISP-A LO-HI | Indicates when the measured value of DISPLAY A is equal to or outside of the <br> Low or High Comparator setting. |
| DISP-B LO-HI | Indicates when the measured value of DISPLAY B is equal to or outside of the <br> Low or High Comparator setting. <br> Indicates when the measured value of DISPLAY A and DISPLAY B are within <br> the High and Low limits of the Low or High Comparator setting. If DISPLAY A <br> comparator is disabled then the TOTAL GO DISPLAY B determines condition <br> only. If DISPLAY B comparator is disabled then the TOTAL GO condition is <br> determined by DISPLAY A only. |

## 17 Sample LED (Trigger Status)

This LED displays the measurement status. When the TRIGGER mode is set to "INT", this LED will flash continuously. When the TRIGGER mode is set to "MAN/EXT", this LED will flash every time a measurement is made.

18 "COMPARATOR ON/ OFF" Switch - [ON]
This switch enables or disables the Comparator. When the switch is in the ON state (LED on), the BIN Display LED, Comparator State Annunciators, and Comparator functions are enabled.

## 19 "DI SPLAY B" Parameter Selection Key - [B]

Press this key to select the measurement parameter of DISPLAY B. Measurements of D, Q, RS, RP, $\mathrm{G}, \mathrm{X}, \mathrm{B}$ and $\theta$ are available.

## 20 "DI SPLAY B"

Measured values of D, Q, RS, RP, G, X, B and $\theta$ are shown in this panel. The measurements values are displayed with $4 / 2$ - digit resolution. In addition, units of measure are annunciated above and beside the display for reading convenience.
To change the parameters shown by DISPLAY B, press the [B] key located in the DISPLAY A-B instrument panel until the desired annunciator is lit.

## Front Panel Description cont'd:

21 DI SPLAY C Measurement Panel - [FREQ] [ V ] [ I ] [CV/CC] [DOWN] [UP]
The keys on the DISPLAY C Measurement panel are used to set the measurement frequency, constant voltage, voltage or constant current mode, test signal amplitude and the measurement that will be shown on DISPLAY C.
[FREQ] - Test Frequency Select Key
When [FREQ] is pressed, the test frequency will be shown on DISPLAY C. The displayed test frequency setting can be adjusted using the [DOWN] and [UP] Keys to increment or decrement the existing test frequency setting. To define the test frequency value, decimal point location and units refer to the [SHIFT] $\rightarrow$ [0]: Frequency Set Mode section.

## [V] - Show Test Voltage on DISPLAY C

When the [ V ] key is pressed the test voltage will be shown on DISPLAY C. Pressing either the [UP] or [DOWN] keys will adjust the test voltage. The test voltage, decimal point and units can be set by using the [SHIFT] $\rightarrow$ [V] key sequence.

The Model 3550 has programmable test voltages from $0.01 \mathrm{~V} \sim 5.00 \mathrm{~V}$ for test frequencies of $42.0 \mathrm{~Hz} \sim 1.00 \mathrm{MHz}$. For test frequencies above 1.00 MHz , the voltage can be adjusted between 0.01 V and 1.00 V . Test voltages are adjustable in steps of 0.01 V and are displayed in DISPLAY C to three significant digits.

When in the constant voltage mode, and the [UP] or [DOWN] keys are pressed, DISPLAY C will momentarily show the open circuit test voltage setting before displaying the constant voltage applied to the actual test device terminals. If either the [UP] or [DOWN] key is pressed and held, the voltage setting will display and the setting will either scroll up or down (depending on whether the [UP] or [DOWN] key is pressed.

## [I] - Show Test Current on DISPLAY C

When [I] is pressed, the test current flowing through the DUT will be displayed. Pressing either the [UP] or [DOWN] keys will adjust the test current level. The test current, decimal point and units can be set by using the [SHIFT] $\rightarrow$ [I] key sequence.

Programmable test currents are available from 0.01mA~99.99mA for test frequencies of $42.0 \mathrm{~Hz} \sim 1.00 \mathrm{MHz}$. For test frequencies above 1.00 MHz , the current can be set between 0.01 mA and 20.00 mA . The 3550's test current is adjustable in 0.01 mA steps and is displayed to three significant digits.

When in the constant current mode, and the [UP] or [DOWN] keys are pressed, DISPLAY C will momentarily show the open circuit test voltage setting before displaying the actual current flowing through the test device. If either the [UP] or [DOWN] key is pressed and held, the voltage setting will display and the setting will either scroll up or down (depending on whether the [UP] or [DOWN] key is pressed.

## Front Panel Description cont'd:

## Test Signal Modes - [CV/CC]

Model 3550 is capable of three different measurement modes. These are Open Circuit Test Voltage Mode, Constant Voltage Mode, and Constant Current Mode. The active measurement mode can be confirmed by looking at the [V], [I], and [CV/CC] LED Keys in the DISPLAY C panel.
The relationship between the operation modes and the LED displays are as follows:
Table 4.4-CV/ CC Indicators

| Measurement Mode | $[$ V] <br> LED | $[$ II <br> LED | $[$ CC/ CV] <br> LED |
| :--- | :--- | :--- | :--- |
| Open Circuit Test Voltage Mode | ON | OFF | OFF |
| Constant Voltage Mode | ON | OFF | ON |
| Constant Current Mode | OFF | ON | ON |

## Set Voltage Mode

Measurements are taken using the open circuit Test Voltage. The test voltage varies with current. Use this mode for ordinary test objects that possess an overall impedance value with real and imaginary components.

## Constant Voltage Measurement Mode

This makes the measurement while keeping the voltage of the measurement terminals at a fixed level. For example, this mode can be used for testing inductors where terminal voltage will vary. Using Constant Voltage mode can help stabilize a reading.
Constant Current Measurement" Mode
This makes the measurement stable by keeping the current passing through the DUT at a fixed level. For example, this mode can be used for testing capacitors where test current continuously varies with applied voltage.

## 22 "DI SPLAY C"

Displays Frequency ( $\mathrm{Hz}, \mathrm{kHz}$, and MHz ), Open Circuit Test Voltage (V), Terminal Voltage (Constant V ), and DUT Test Current (Constant mA ) based on the settings of the DISPLAY C Measurement Panel. The measurement values are displayed with $4 \frac{1}{2}$ - digit resolution. Units of measure are annunciated beside the display for reading convenience.

## 23 ENTER Key - [ENTER]

Used in the various programming modes to finalize user-defined instrument settings. For example, the [ENTER] key is pressed to finalize any of the [SHIFT] $\rightarrow$ [0~9] commands and to return back to the measurement mode.

## Rear Panel Description

Figure 4.3-Rear Panel Layout


Line Voltage Selector Plug - The Model 3550 is capable of 100/120/220/240 VAC 50/60 Hz Operation. To change the line voltage, remove the plug by pulling it from the rear panel. Put the plug back in to the socket with the arrow pointing to one of four supply voltage settings.

Fuse Input - Use 3AG Type Fuses, $1 / 4^{\prime \prime} \times 11 / 4$ " (6.35X31.75mm)

Fuse Rating Chart - See Rear Panel or Preparation for Use Section for fuse ampere ratings. Use fast acting fuses only.

VAC Input - 100/120/220/240, power input. An internal line filter is included in this input.

GND Terminal - The GND binding post provides a direct connection to the instrument's chassis and the grounded connector of the VAC input plug.

Cooling Fan Ventilation Holes - To prevent overheating, keep these ventilation holes free of obstructions. Periodically inspect these holes to assure they are free of obstructions.

Control I/ O Port - The Control I/O Port has optically isolated TTL inputs and outputs used for remote operation. Inputs include BCD Panel Selection and trigger inputs. Outputs include A, B and total Comparator outputs, End of measurement, BIN, Busy and Error Outputs. The control connector also includes pins for external power connections.

RS-232C Port - Standard RS-232C Port.
GPIB Board Slot - Slot provided for factory installed GPIB (IEEE-488.2) option PN\# 3505.

## Making Accurate Measurements:

## Connections to the Device Under Test (DUT)

The relationship between the connections schemes and impedance, |Z| ranges are shown in Table $5-1$. It is extremely important, for measurement accuracy purposes, to observe appropriate connection methods for the subject test piece and measurement range.

| Range | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| I mpedance Mode | Low Impedance (Series Equivalent Mode) |  |  |  |  | High Impedance (Parallel Equivalent Mode) |  |  |  |
| Connection Type |  |  |  |  |  |  | mi | Co | tion |
|  | $\longleftarrow 5$ Terminal Connection $\longrightarrow$ |  |  |  |  |  |  |  |  |

## 3-Terminal Measurement



This measurement method is used for testing devices having high impedance. In general, components with large inductance, low capacitance, or high resistance fall into this category.
The major advantage to 3-terminal measurements is that the influence of stray capacitance and conductance between the test leads and nearby conductors becomes negligible.

4 or 5-Terminal Measurements


The 5-terminal measurement method can be used for all impedance ranges and has significant advantage over the 3 -terminal measurement method. The advantage is that in addition to canceling the effects of stray capacitance and conductance between the measurement leads and close proximity conductors, the residual inductance and resistance of the test lead are bypassed by placing the voltage sense points of contact directly at the DUT terminals.
A four-terminal measurement is the same as a five-terminal measurement except that the guard connection is not used.

## Making Accurate Measurements:

## Test Fixture Selection

Model 3510 Radial/ Axial Lead Adapter


The Model 3510 Radial/Axial Lead adapter is a general-purpose accessory used for testing components with radial or axial leads. Components are tested by plugging the leads directly into the adapter sockets.
The Model 3510 is designed for 5 -terminal measurements and is capable of measuring a wide range of impedances.

Model 47454 Kelvin Klip Leads are designed for 5wire, Kelvin measurement of all types of component styles. They may be used for both low and high impedance measurements.
Kelvin Klips are particularly convenient for low impedance test devices or components with short leads, however, the measurement frequency and impedance range are limited as shown in Table 4.4. Exceeding the recommended measurement ranges may result in erroneous and inaccurate readings.

Table 4.4-I mpedance and Frequency Limitations of Kelvin Klip Leads

| Frequency | Measurement Range |
| :--- | :--- |
| $42 \mathrm{~Hz} \sim 10 \mathrm{kHz}$ | $100 \mathrm{~m} \Omega \sim 1 \mathrm{M} \Omega$ |
| $10.1 \mathrm{kHz} \sim 100 \mathrm{kHz}$ | $1 \Omega \sim 100 \mathrm{k} \Omega$ |
| $101 \mathrm{kHz} \sim 1.00 \mathrm{MHz}$ | $10 \Omega \sim 10 \mathrm{k} \Omega$ |

NOTE: Additional test voltage and current restrictions of the 3550 unrelated to test fixtures apply for measurements exceeding 1 MHz .

## Making Accurate Measurements cont'd:

## Test Fixture Selection cont'd

## Model 3511 Surface Mount Device (SMD) Test Fixture



The 3511 is a test fixture designed to perform 3-wire impedance measurements of surface mount devices. This adapter is suitable for measurement of chip components with middle to high impedance ranges. The measurement frequency and range limitations are summarized in table 4.5 below Exceeding the recommended measurement ranges may result in erroneous and inaccurate readings. The signal level limitations of the instrument must also be considered when making measurements above 1 MHz .

Table 4.5-Impedance and Frequency Limitations of the SMD Test Fixture

| Frequency | Measurement Range |
| :--- | :--- |
| $42 \mathrm{~Hz} \sim 100 \mathrm{kHz}$ | $10 \Omega \sim 1 \mathrm{M} \Omega$ |
| $101 \mathrm{kHz} \sim 1.00 \mathrm{MHz}$ | $10 \Omega \sim 10 \mathrm{k} \Omega$ |
| $1.01 \mathrm{MHz} \sim 5.00 \mathrm{MHz}$ | $10 \Omega \sim 10 \mathrm{k} \Omega$ <br> $(10 \Omega$ Minimum $)$ |

## Model 2005B Chip Component Tweezers

2005B is designed for manual sorting of chip
 components from DC to 1 MHz . Four-terminal tweezers make solid connections on chips up to 0.50 in . ( 12.7 mm ) long. The set includes a 5 ft . (1.5m) cable for connection to the 3550

47422 - Chip Tweezer Rebuild Kit
Tweezer tips are intended to last from 100,000 to 500,000 operations. This tip replacement kit includes 12 replacement tips, 2 screws, and 1 wrench.

## Making Accurate Measurements cont'd:

## Zero Corrections

Residual Impedance and Leakage of test fixtures exists for all types of test fixtures. To maintain the performance accuracy of the 3550 it is highly recommended that a zero correction be performed whenever a change in test fixture takes place. For test fixtures such as Kelvin Klip Leads where the positioning may vary, extra effort must be made to perform the zero correction while positioning the leads in the exact location, as the measurement will be taken.

When performing a standard zero correction, the instrument will step through frequencies from 42 Hz to 5 MHz . This takes a considerable amount of time and may not be desired in certain applications especially when the actual component test will take place at a single frequency point. To overcome this, the 3550 has the ability to perform spot frequency corrections where zero corrections are performed on up to three user defined frequency set points. The spot frequency zero correction data is stored in the instrument's non-volatile RAM and will overwrite any correction data obtained from a standard zero correction procedure. A standard zero correction cannot write over data from a spot frequency zero correction. The spot frequency setting must be disabled in order for the standard zero correction to be able to write over all frequency points. Refer to "Defining Spot-Correction Frequencies for Zero Adjustments", [SHIFT] $\rightarrow$ [8] in the front panel description to learn how to enable or disable the spot frequency settings.

Table 4.6-Zero Correction Limits

| Zero Correction | Correction |  | Correction Limit |
| :--- | :--- | :--- | :--- |
| Open | Stray Capacitance \& Stray Conductance | $(C 0) \&(G 0)$ | $>1 \mathrm{k} \Omega$ |
| Short | Residual Inductance \& Residual Resistance | $(\mathrm{LO}) \&(\mathrm{RO})$ | $<1 \mathrm{k} \Omega$ |

If during OPEN correction the Impedance is less than $1 \mathrm{k} \Omega$, or during SHORT correction the Impedance is $1 \mathrm{k} \Omega$ or higher, a buzzer will go off to warn that correction cannot be made, and the system will reset without making the correction.

There are three methods of defining what frequencies a zero correction will be performed on. They are Standard, Frequency Limit, and Spot Frequency Zero Correction.

## Standard Zero Correction

Refer to Section 4 , "ZERO" Panel - for instructions to perform a standard open and short circuit correction. This procedure will perform a zero correction on all test frequencies, $42 \mathrm{~Hz} \sim 5 \mathrm{MHz}$ except for those designated as spot correction frequencies.

## Frequency Limit Zero Correction

For zero correction, [SHIFT] $\rightarrow$ [-], Correction Frequency Limit Setting Mode allows the user to define the upper and lower frequency limits instead of using the default $42 \mathrm{~Hz} \sim 5 \mathrm{MHz}$ range.

## Spot Frequency Zero Correction

Refer to [SHIFT] $\rightarrow$ [OPEN] and [SHIFT] $\rightarrow$ [SHORT] sections for instructions to perform a spot frequency open and short zero correction procedure.
After performing the zero correction procedure, perform a "before and after" measurement on a component with an accurately known value to confirm that a zero correction has taken place. A calibrated capacitance or inductance standard would be ideal (but not required) for this type of verification.

## Making Accurate Measurements cont'd:

## Zero Corrections cont'd

NOTE: The parasitic impedance of test adaptors and measurement cables differ from cable to cable. Whenever a test adaptor or cable is changed, make sure that zero correction is performed again.

Figure 4.4-Terminal Connections for Zero Correction

| Connection | Open Correction |  | Short Correction |  |
| :---: | :---: | :---: | :---: | :---: |
|  | Normal | Error | Normal | Error |
| BNC Terminals |  |  |  | $\mathrm{G}$ |
| 5-Terminal Correction |  |  |  | G L H |
| Kelvin Klip ${ }^{\text {m }}$ Correction | $\underbrace{L_{F}}_{L_{s}} H_{H_{s}}^{H_{F}}$ | $\mathrm{Le}_{\mathrm{LF}}^{\mathrm{H}_{\mathrm{F}}}$ | $\mathrm{L}_{\mathrm{F}}$ $\mathrm{H}_{\mathrm{F}}$ <br> Ls | LF $\quad H_{F}$ <br> Ls $\mathrm{H}_{5}$ |

Use Figure 4.4 as a reference when performing short-circuit and open-circuit zero corrections.

## Making Accurate Measurements cont'd:

## Equivalent Circuits

The DUT can be described in terms of Impedance (Z) or Admittance (Y). The relationships of the various characteristics are as follows:

$$
\begin{aligned}
& Z=R+j X \\
& Y=G-j B=\frac{1}{Z} \\
& D=\frac{R}{X}=\frac{G}{B} \\
& Q=\frac{1}{D} \\
& X_{L}=\omega L=2 \pi f L \\
& X_{C}=\frac{1}{\omega C}=\frac{1}{2 \pi f C} \\
& \theta=\tan ^{-1} \frac{X}{R}=\tan ^{-1} \frac{B}{G}
\end{aligned}
$$

Z: Impedance
$R$ : Equivalent Resistance
X : Reactance ( jX )
Y: Admittance
G: Conductance
B: Susceptance (jB)
D: Loss Coefficient
Q : Quality
$\theta$ : Phase Angle
f: Measurement Frequency Hz
$\omega$ : Measurement Frequency rad/s

The measurable quantities of the 3550 are $\mathrm{L}, \mathrm{C}, \mathrm{R}, \mathrm{Z}, \mathrm{Y}, \mathrm{D}, \mathrm{Q}, \mathrm{G}, \mathrm{Rp}, \mathrm{Rs}, \mathrm{X}, \mathrm{B}$, and $\theta$. The measured value of these parameters will change in value as the test frequency is increased or decreased. These measured parameters are said to be dependent upon test frequency.* Two examples are capacitive reactance, which is inversely proportional to frequency and inductive reactance, which is inversely proportional to frequency. Because of the direct relationship to test frequency, related quantities such as Dissipation Factor and Quality Factor is also frequency dependent.
*In measurement applications, the measured $R$ and $G$ values will change with frequency. True $R$ and $G$ are not theoretically dependent to frequency but in LCR measurement applications, parallel leakage and series losses can affect the measured $R$ and $G$ value of the component. Compensation for these errors is the reason for Series and Parallel Equivalent Circuit Measurement Modes.

In general, parallel leakage becomes significant in highly reactive (small capacitors or large inductors) measurements and series resistance is more significant in low reactance (large capacitors and small inductors) measurements. This is the reasoning behind the use of series or parallel equivalent circuit measurement modes.

If the dissipation factor, D is small then the difference between Series Equivalent and Parallel Equivalent Circuit Measurement Mode measurement will be small. As the dissipation factor increases, the difference between parallel and series equivalent measurements will increase. Thus, precautions must be taken when performing measurements on components with high dissipation factors.

## Making Accurate Measurements cont'd:

## Equivalent Circuits cont'd

Table 4.7 Illustrates the effects of leakage and series resistance on component measurements. It also provides some additional formulae to illustrate the relationship that dissipation factor has on a device's impedance measurement.

Table 4.7 - Equivalent Circuit Relationships

|  | Equivalent Circuit Mode | Dissipation Factor <br> (D) | Conversion Formula |  |
| :---: | :---: | :---: | :---: | :---: |
|  | $\begin{array}{\|cc} \text { (SER) } & \\ \text { Ls } & R \end{array}$ | $\mathrm{D}=\frac{\mathrm{R}}{\omega \mathrm{Ls}}=\frac{1}{\mathrm{Q}}$ | $\mathrm{LP}_{\mathrm{p}}=\left(1+\mathrm{D}^{2}\right) \cdot \mathrm{Ls}$ | $\mathrm{G}=\frac{\mathrm{D}^{2}}{1+\mathrm{D}^{2}} \cdot \frac{1}{\mathrm{R}}$ |
| L | (PRL) <br> G <br> Lp | $D=\omega L P G=\frac{1}{Q}$ | $\mathrm{Ls}=\frac{1}{1+\mathrm{D}^{2}} \cdot \mathrm{Lp}$ | $\mathrm{R}=\frac{\mathrm{D}^{2}}{1+\mathrm{D}^{2}} \cdot \frac{1}{\mathrm{G}}$ |
|  | (SER) <br> Cs $R$ | $\mathrm{D}=\omega \mathrm{CsR}=\frac{1}{\mathrm{Q}}$ | $\mathrm{Cp}=\frac{1}{1+\mathrm{D}^{2}} \cdot \mathrm{Cs}$ | $\mathrm{G}=\frac{\mathrm{D}^{2}}{1+\mathrm{D}^{2}} \cdot \frac{1}{\mathrm{R}}$ |
| C | (PRL) <br> G <br> $\mathrm{C}_{\mathrm{p}}$. | $D=\frac{G}{\omega C_{P}}=\frac{1}{Q}$ | $\mathrm{Cs}=\left(1+\mathrm{D}^{2}\right) \cdot \mathrm{Cp}$ | $\mathrm{R}=\frac{\mathrm{D}^{2}}{1+\mathrm{D}^{2}} \cdot \frac{1}{G}$ |

The Series Equivalent Circuit Mode of the 3550 can be used for testing devices where series impedance has a great effect on the measurement. Parallel Equivalent Circuit Mode is used for testing devices with high reactance where parallel leakage becomes more significant. The formulae in Table 4.7 can be used to convert readings in one equivalent circuit mode to the other.

Note that the measured value of D (or Q ) will not be different whether it is measured in Series or Parallel Equivalent circuit mode.

## Operating the 3550

## Preparation

Check the Power Source Voltage. The voltage range of this machine is displayed on the rear of the machine. The power voltage may be selected using the switching plug on the rear panel. See "Preparation for Use" for more setup details.

When the [POWER] Switch is turned ON the settings of the machine will be same as when the power was previously turned off. In order to reset the 3550, simply press [MAN/EXT] at the same time the [POWER] key is pressed. Resetting will clear the zero correction factors and return the instrument settings to factory defaults. A table summarizing the factory default settings can be found in Chapter 3, Quick Start Instructions.

## How to Perform a Zero Correction

Determine whether test leads, an adapter or some other fixture will be used to make measurements and connect it to the front panel BNC terminals. Perform a Standard, Frequency Limit, or Spot Frequency Zero Correction for both open and closed circuit conditions. To perform a standard zero correction, follow the instructions below:
a) With the tips of the test leads or the adapter in an "open" condition, push the [OPEN] switch. DISPLAY A will show "OP-57" to indicate that an open correction is being performed and " 57 " will indicate what step frequency the instrument is adjusting for. The instrument will count down from " 57 " to " 1 ". Do not touch or adjust the test leads/fixture while the zero correction procedure is taking place.
b) Once the "OPEN" correction is completed the unit will return to the measurement mode. Connect the test leads/fixture in the "shorted" position (see Figure 4.X) and press the [SHORT] key. The instrument will execute the short circuit correction procedure.

During the Open or Short Circuit Zero Correction process, if the Correction Value min/max threshold is exceeded, a warning buzzer will sound 3 times to warn that the correction could not be done. If this happens, lower the parasitic Impedance, and re-do the correction. If the test leads/fixture continue to fail the zero correction, double check that the operating frequency range of the leads/fixture have not been exceeded. See "Test Fixture Selection" to determine whether the test frequency range of your test leads/fixture have been exceeded and whether a Frequency Limit or Spot Frequency Zero Correction need to be performed instead of a Standard Zero Correction. Frequency Limit and Spot Frequency Zero Corrections allow the user to define the specific frequencies to be open and short compensated. Frequency Limit and Spot Frequency Corrections can also be used to shorten the total zero correction time by ignoring unused test frequencies.

If the proper frequency correction has been performed and the test leads/fixture continues to fail zero correction, have the leads/fixture tested by an authorized service person.


Detailed instructions for performing "open " or "short" circuit zero corrections are found in the "Measurement Tips" and in "Front panel Description" sections of this manual. Make sure that front panel operation and LCR measurement technique is thoroughly understood before proceeding further. LCR measurement can be quite complex and the slightest overlooked detail could greatly affect measurement accuracy. To maximize measurement accuracy it is highly recommended that this chapter be understood in its entirety.

## Operating the 3550 cont'd:

## Measuring I nductance (L), Capacitance (C) and Resistance (R)

1) Always perform a zero correction procedure if the condition of the test leads/fixture has changed. This procedure must be performed before making a measurement. Refer to "How to Perform a Zero Correction" for more details.
2) Press the [A] key and select "L", "C" or "R" on DISPLAY A.
3) Press the [FREQ] key and adjust the frequency using the [UP] or [DOWN] keys or by manually entering a new value for test frequency. See [SHIFT] $\rightarrow$ [0]: "Frequency Set Mode" for more details on manually setting the test frequency.
4) Press the [V] key, and adjust the measurement voltage using the [UP] or [DOWN] keys or by manually entering a new value for test frequency. See [SHIFT] $\rightarrow$ [1]: "Test Voltage Set Mode" for more details on manually setting the test frequency.
5) Press the [AUTO] key in the RANGE panel and verify that the "AUTO" LED is on. This puts the 3550 in AUTO range.

NOTE: When repeatedly measuring DUTs with similar values selecting the manual mode allows the measurement time to be shortened by eliminating the time needed for switching the ranges. See "RANGE" Selection Panel" for more details.
6) Press the [AUTO] key in the CIRCUIT MODE panel and verify that the "AUTO" LED is on.
7) Press the [INT] key in the TRIGGER panel and verify that the "INT" LED is on. This will continuously trigger the 3550 and update the reading shown on DISPLAY at a rate determined by measurement frequency, delay time, number of averages, and the time taken to auto range. If MAN/EXT trigger mode is selected the reading will not be updated until a new trigger is received from the front panel or remote interface.
8) Connect the DUT to the measurement terminals. The CIRCUIT MODE and RANGE will be automatically selected by the 3550 . The L, C, or R reading will be shown on DISPLAY A.

## Operating the 3550 cont'd:

## Measuring Inductance (L), Capacitance (C) and Resistance (R) cont'd:

## Notes of Caution for I nductance (L) Measurement

* For low inductance measurements, 5 Terminal Measurements are required to minimize series resistance and inductance errors. Margins of error for 3 terminal measurements on low inductances will add significant error to the reading.
* When performing measurements on small coils with a core, it is possible that the measured inductance value will vary with a change in test signal level. Take extra caution to match the test signal level of other machines in order to obtain matching results.
* Keep metal objects away from the DUT when performing measurements. The presence of metal objects in close proximity can affect the measured value. Especially in coils with air or other low permeability cores.


## Notes of Caution for Capacitance (C) Measurement

* For large capacitance measurements, 5 Terminal Measurements are required to minimize errors caused by series resistance and inductance. Margins of error for 3 terminal measurements on large capacitances will add significant error to the reading.
* $₫$ Always make sure that capacitors are completely discharged before connecting to the 3550 measurement terminals otherwise erroneous readings or damage to equipment could result.


## Notes of Caution for Resistance (R) Measurement

* For low resistance measurements, 5 Terminal Measurements are required to minimize series resistance and inductance errors. Margins of error for 3 terminal measurements on low resistance will add significant error to the reading.


## Operating the 3550 cont'd:

## Measuring Impedance (|Z|) and Admittance (|Y|)

1) Always perform a zero correction procedure if the condition of the test leads/fixture has changed. This procedure must be performed before making a measurement. Refer to "How to Perform a Zero Correction" for more details.
2) Press the [A] key in the "DISPLAY A-B panel to select "|Z|" or "|Y|".
3) Press the [FREQ] key and adjust the frequency using the [UP] or [DOWN] keys or by manually entering a new value for test frequency. See [SHIFT] $\rightarrow$ [0]: "Frequency Set Mode" for more details on manually setting the test frequency. The measurement frequency will be displayed on DISPLAY C.
4) Press the [V] key, and adjust the measurement voltage using the [UP] or [DOWN] keys or by manually entering a new value for test frequency. See [SHIFT] $\rightarrow$ [1]: "Test Voltage Set Mode" for more details on manually setting the test frequency. The measurement voltage will be displayed on DISPLAY C.
5) Press the [AUTO] key in the RANGE panel and verify that the "AUTO" LED is on. This puts the 3550 in AUTO range.

NOTE: When repeatedly measuring DUTs with similar values selecting the manual mode allows the measurement time to be reduced by eliminating the time needed for switching the ranges. See "RANGE" Selection Panel" for more details.
6) Press the [INT] key in the TRIGGER panel and verify that the "INT" LED is on. This will continuously trigger the 3550 and update the reading shown on DISPLAY A at a rate determined by measurement frequency, delay time, number of averages, and the time taken to auto range. If MAN/EXT trigger mode is selected the reading will not be updated until a new trigger is received from the front panel or remote interface.
7) Connect the DUT to the measurement terminals. The RANGE will be automatically selected by the 3550 . The $|\mathrm{Z}|$ or $|\mathrm{Y}|$ reading will be shown on DISPLAY A.

## Operating the 3550 cont'd:

## Measuring: Loss Coefficient (D), Quality (Q), Equivalent Series Resistance (Rs), Equivalent Parallel Resistance ( $\mathrm{R}_{\mathrm{P}}$ ), Conductance (G), Reactance (X), Susceptance (B), and Phase Angle ( $\theta$ )

1) Always perform a zero correction procedure if the condition of the test leads/fixture has changed. This procedure must be performed before making a measurement. Refer to "How to Perform a Zero Correction" for more details.
2) Press the [B] key in the "DISPLAY A-B panel to select $D, Q, R_{s}, R_{P}, G, X, B$, or $\theta$.
3) Press the [FREQ] key and adjust the frequency using the [UP] or [DOWN] keys or by manually entering a new value for test frequency. See [SHIFT] $\rightarrow$ [0]: "Frequency Set Mode" for more details on manually setting the test frequency. Frequency will be displayed on DISPLAY C.
4) Press the [V] key, and adjust the voltage using the [UP] or [DOWN] keys. See [SHIFT] $\rightarrow$ [1]: "Test Voltage Set Mode" for more details on manually setting the test frequency. The measurement voltage will be displayed on DISPLAY C.
5) Press the [AUTO] key in the RANGE panel and verify that the "AUTO" LED is on. This puts the 3550 in AUTO range.

NOTE: Selecting the manual mode allows the measurement time to be reduced by eliminating the time needed for switching the ranges. See "RANGE" Selection Panel" for more details.
6) Press the [INT] key in the TRIGGER panel and verify that the "INT" LED is on. This will continuously trigger the 3550 and update the reading shown on DISPLAY A at a rate determined by measurement frequency, delay time, number of averages, and the time taken to auto range. If MAN/EXT trigger mode is selected the reading will not be updated until a new trigger is received from the front panel or remote interface.
8) Connect the DUT to the measurement terminals. The CIRCUIT MODE and RANGE will be automatically selected by the 3550 . The $\mathrm{D}, \mathrm{Q}, \mathrm{R}_{\mathrm{s}}, \mathrm{R}_{\mathrm{p}}, \mathrm{G}, \mathrm{X}, \mathrm{B}$, or $\theta$ reading will be shown on DISPLAY B.

## Notes for Measuring Reactance \& $\boldsymbol{\theta}$

* On occasion a "-" sign will be observed occupying the same display as the most significant digit " 1 ". The minus sign indicates a negative phase angle from a capacitive reactance, $\mathrm{X}_{\mathrm{c}}$. This is normal functionality in order to maximize the number of significant digits for an upper-range measurement.

Display B indicating 16.775 $\boldsymbol{\Omega} X_{C}$ Value


Display B indicating 16.775 $\boldsymbol{\Omega}$ X Value


## The Comparator

## I mportant Notes for the Absolute and Percent Comparator Functions

Comparator settings can only be defined and stored into panels 1-9. Before a comparator setting can be defined, a panel, 1-9 must be recalled.
This is done by pressing the [0-9] key until the desired panel is active while the 3550 is in the measurement mode.

Settings for DISPLAY A, DISPLAY B and CIRCUIT MODE must be finalized in the panel setting, [19] before defining comparator upper and lower limits. This is because these values cannot be changed after the comparator high and low limits have been set.

If any of the DISPLAY A, DISPLAY B, or CIRCUIT MODE keys, ([A][B][AUTO][SER][PRL]) are pressed after the comparator limits have been set, the [LOW] and [HIGH] LEDs of the comparator will start flashing to indicate an illegal operation. If either the [LOW] or [HIGH] keys are pressed afterwards then all of the comparator settings will be cleared. This will be indicated by " $\qquad$ " appearing on the display. Pressing any other keys on the front panel will return the instrument to measurement mode without affecting the comparator settings.

The 3550 offers a dual-function comparator meaning that for each BIN there are two comparator settings that may be defined. The DISPLAY A setting allows a high and low limit to be defined for L, C, R, |Z|, and |Y| measurements while DISPLAY B allows limits to be set for D, Q, RS, RP, G, X, $B$, or $\theta$. The comparator is equipped to offer an output based on the measurement results of DISPLAY A only, DISPLAY B only or the combined measurement results of both DISPLAY A and DISPLAY B.

The comparator may be used in absolute or percent mode. In the absolute mode, the comparator high and low limits are defined by entering absolute value high or low limits. This means that the high and low limits are entered as actual magnitudes and units of measure. The percent mode requires that the high and low limits are defined in terms of a percentage of a nominal value. The following sections provide instruction for setting the high and low limits in the Absolute or Percent Comparator modes.

During high and low limit setup, if a numeric key is pressed that will create a limit value, which falls outside of the measured parameter's range, the instrument will disable the functionality of that key.

Refer to the following sections for additional information regarding the 3550 comparator functions.
[SHIFT] $\rightarrow$ [5] - Setting the comparator buzzer function.
[SHIFT] $\rightarrow$ [7] - Absolute or Percentage Comparator Function
8 - Comparator Limit Set Panel
18 - Comparator ON/OFF Switch

## The Comparator cont'd:

## Absolute Value Settings

NOTE: A condensed version of this procedure can be found in the "Quick Start Section"

1) Make sure that panel 1~9 is selected. Do this by pressing the [0~9] key until the desired panel \# appears on the Panel LED. Press [SHIFT] $\rightarrow$ [7] to access the Comparator Functions Mode. Either a flashing " 0 " or a " 1 " will appear on DISPLAY B. The meaning of the numbers is as follows:

## 0: Absolute Value Comparator Function <br> 1: Percent Comparator Function

To change the flashing digit, press [0] $\rightarrow$ [ENTER] to call the absolute comparator mode and return to the measurement mode.
2) In the measurement mode, press the [LOW] key in the Comparator Limit Set Panel. Make sure that a panel number from 1~9 is selected otherwise the comparator [HIGH] and [LOW] keys will be disabled. The [LOW] LED will light. The BIN segment LED will flash the numeral " 1 ". Press a numeric key [1]~[9] to define the bin number.
3) Press the [CURSOR ] once. This will cause the $5^{\text {th }}$ digit if DISPLAY A to flash. Type in the comparator low limit value using the [0-9] keys and the [CURSOR $\quad$ ] or [CURSOR 4] keys to navigate between the $1^{\text {st }}$ and $5^{\text {th }}$ digits. After digits 1 through digit 5 has been set, press the [CURSOR $\quad$ ] key until the decimal point begins to flash. Press the [DP] key until the decimal point is in the desired position. Then press the [CURSOR ] key once again to set the units of measure. Units are defined by pressing the [UNITS] key until the desired annunciator illuminates.
6) After the units for the low limit (DISPLAY A) have been selected, press the [CURSOR ] key. The $5^{\text {th }}$ digit of DISPLAY B will begin to blink indicating that a value can be entered for the high comparator limit.
7) Enter the values for the DISPLAY B low comparator limit in the same manner as performed for the DISPLAY A low limit.

NOTE: If the comparator function for DISPLAY A or DISPLAY B is not required, press the [IGNORE] key while the display is active and the comparator for that display will be disabled. A disabled display will show a "-----" in place of a numerical value.
8) To set the high value limit for the comparator press the [ HIGH ] key located in the Comparator Limit Set panel. The comparator high limit set mode is indicated when the [HIGH] LED lights. Repeat steps 3-7 to set the comparator's high limit values.
9) This completes setting the values for BIN \#1. To set the high and low limits of the remaining BINs return to step \#2. When the BIN LED is flashing select a BIN number from 1-9 by pressing the [1]-[9] keys and continue with the procedure.

NOTE: The BIN functionality is expressed as:
LOW $\leq$ BI N $\leq$ HI GH

## The Comparator cont'd:

## Percent Value Settings

NOTE: A condensed version of this procedure can be found in the "Quick Start Section"

## Set the Nominal Value

1) Make sure that panel $1 \sim 9$ is selected. Do this by pressing the [0~9] key until the desired panel \# appears on the Panel LED. Press [SHIFT] $\rightarrow$ [7] to access the Comparator Functions Mode. Either a flashing " 0 " or a " 1 " will appear on DISPLAY B. The meaning of the numbers is as follows:

## 0: Absolute Value Comparator Function <br> 1: Percent Comparator Function

To change the flashing digit, press [1] $\rightarrow$ [ENTER] to call the percent comparator mode and return to the measurement mode.
2) In the measurement mode, press the [LOW] key in the Comparator Limit Set Panel. Make sure that a panel number from 1~9 is active otherwise the comparator [HIGH] and [LOW] keys will be disabled. The [LOW] LED will light. This will cause the $4^{\text {th }}$ digit if DISPLAY C to flash either a " 1 " or a " 0 ". A flashing " 0 " indicates the Nominal Value Set Mode. This is where the nominal value of the measured value will be entered. High and low limits are calculated as a percent of this value. A flashing " 1 " indicates the High and Low Percent Limits Set Mode. The High and Low Percent Limits Mode requires a [ HIGH ] and [LOW] comparator setting. The Nominal Value Set Mode requires only one setting. Press the [0] key to set the instrument to Nominal Value Set Mode.
3) Press the [CURSOR -] once. The BIN LED in the Comparator Panel will flash a numeral " 1 ". Press a numeric key [1]~[9] to set the active bin number. BIN 0 cannot be used with the comparator function. Then press the [CURSOR - ] key once again so that the $5^{\text {th }}$ digit of DISPLAY A starts to flash.
4) Enter the nominal digit value of the \% comparator setting. After a value has been assigned for each digit the decimal point will start to blink. Use the [DP] key to position the decimal point and then press the [CURSOR - key to set the unit prefix of measure. Press the [UNITS] key to select the desired prefix for the DISPLAY A, nominal value setting.

NOTE: Units of measure in DISPLAY A or DISPLAY B cannot be changed once the comparator has been enabled. The [IGNORE] function and the equivalent circuit mode setting are also locked out.
5) After the prefix units for the nominal value have been selected, press the [CURSOR ] key. The $5^{\text {th }}$ digit of DISPLAY B will begin to blink indicating that a value can be entered for the DISPLAY B measurement. Enter a nominal value setting for DISPLAY B then press the [CURSOR $\quad$ ] key.
6) The $4^{\text {th }}$ digit of DISPLAY C will display a blinking " 0 ". Press the [1] key to enter the High and Low Percent Limits Mode.

## The Comparator cont'd:

## Percent Value Settings cont'd

7) To input an upper limit threshold value, press the [HIGH] key. Press the [LOW] key to set the lower limit threshold value. Then, highlight the first digit of DISPLAY C and press [1].
8) After selecting the threshold value input mode, use the cursor key, [ $\boldsymbol{\sim}$ ] to highlight the bin LED, and then press [1]~[9] to select the desired bin.
9) After entering the bin number, use the cursor key [ $\boldsymbol{D}$ ] to highlight DISPLAY A. Enter the 5-digit threshold value for DISPLAY A using keys [0]~[9]. (The setting range is from 000.00\%~199.99\%)
10) Enter the 5-digit threshold value for DISPLAY B using keys [0]~[9]. (The setting range is 000.00\% ~199.99\%)
11) To finalize an upper limit, press [HIGH] or press [LOW] to finalize a low limit setting.

NOTE: Step 7 determines whether a high or low limit \% comparator setting is defined be sure that both a low and high limit have been defined.
To input settings for other bins, return to Step 1 and repeat the process.
12. To invalidate the settings, for threshold values, simply enter the Threshold Percent Comparator Set Mode and move the cursor to any segment in DISPLAY A or DISPLAY B. Then press [IGNORE] to invalidate the \% comparator settings for that DISPLAY.

## NOTES:

* The comparator can only be set using panels 1~9. 0 cannot be used.
* This procedure is only for the percent comparator setting. Note that the procedure for the absolute value comparator is different.
* Make sure the comparator mode is set for "Percent Mode" otherwise the procedure will not work correctly.
* After setting the limit values for the comparator, the measurement parameters for DISPLAY A and DISPLAY B cannot be changed. This means that the measurement parameters must be defined before the comparator settings.
* For DISPLAY B, there are no units for D,Q, or $\theta$.

NOTE: The BIN functionality is expressed as:

## LOW $\leq$ BI N $\leq$ HI GH

Refer to Figures 4.5 and 4.6 for an illustration of BIN operation.

## The Comparator cont'd:

## BI N Operation

Comparator operation may be disabled for DISPLAY A or DISPLAY B by pressing the [IGNORE] key while in the high or low limit set mode. A disabled DISPLAY is indicated by "-----" in place of the limit value being shown on the display.

## Sequenced Sorting Configuration

There are two common multi category BIN settings for sorting components. The first is Sequenced Sorting as illustrated in Figure 4-5. In this setting, the 3550 comparator will sort components based on their limit values where each BIN\# will define a unique range of measured values. Any number of bins may be used for Sequenced Sorting. If there is no matching BIN found for the component value to fall under, then the component will be placed in BIN 0 .

Figure 4.5 Sequenced BI N Sorting LOW $\leq$ BI N $\leq H$ GH


BIN $2 \cdots \operatorname{L2} \quad 2 \quad \mathrm{H} 2$
BIN 3
 H3

BIN 7 M
BIN 8 -
BIN 9 -
L9 $\quad \mathbf{9} \quad \mathrm{H} 9$

## The Comparator cont'd:

## BI N Operation cont'd

## Nested Sorting Configuration

Nested sorting is typically used for tolerance-based sorting where an acceptable \% or value range is defined for each BIN \#. First, the 3550 evaluates the measured value according to the defined range of BIN 1. If the measured falls within the range of BIN 1 then the component is sorted into BIN 1. If the measured value falls outside of the BIN 1 range then it is evaluated for BIN 2. If the component value falls within the BIN 2 range then it is sorted into BIN 2. If not, then the 3550 proceeds the evaluation to BIN 3 and so on. If the measured value does not fall within any defined ranges then the component will be sorted into BIN 0 , the reject BIN .

Figure 4.6 Nested BI N Sorting LOW $\leq$ BI N $\leq$ HI GH


BIN 9 ․

## The Comparator cont'd:

## Outputting the Comparator's Results

There are two ways to determine the state of the comparator. The LEDs of the Comparator Panel, and the optically isolated, open collector outputs of the Control I/O Connector on the rear of the instrument.

Comparator values may be entered and sorted into BINs 1~9. When a measured value falls within ant of the ranges of BINs 1~9, the TOTAL-GO LED will light. When a measured value falls outside of the defined 1~9 BIN ranges, then either the "LO" or "HI" LEDs on the Comparator Panel will illuminate (depending on whether the measured value is higher or lower than the BIN settings). Measured values outside of the comparator range will be sorted to BIN 0 .

For instructions regarding the pin connections of the Control I/O Connector, refer to "Programming and Interfacing"

## Audible Buzzer Operation

When the [SHIFT] $\rightarrow$ [5]: Comparator Buzzer Function is set to " 1 ", the buzzer will sound with a "TOTAL GO" condition. If it is set as "2", the buzzer will sound with "TOTAL NO-GO" condition. If the buzzer function is set to "0", then the buzzer will be disabled. See [SHIFT] $\rightarrow$ [5]: Comparator Buzzer Function for more information on setting the comparator-state buzzer function.

## INSTRUMENT DESCRIPTION PREPARATION FOR USE QUICK START INSTRUCTIONS OPERATING INSTRUCTIONS PROGRAMMING \& I NTERFACI NG SERVICE INFORMATION <br> APPENDIX

## I nterfacing to the $\mathbf{3 5 5 0}$

This section provides detailed information about the 3550 electrical interfaces and their functionality. It will provide all of the necessary information required to integrate the 3550 easily into a working test application. A Control I/O connector is available for optically coupled TTL interface to PLCs and other control hardware. The 3550 has a standard RS232 communications port and an optional GPIB interface for software-based applications.

## Control I/ O Connector

Located on the rear panel, the Control I/O Connector offers an optically isolated, TTL-level interface for integration into PLC and other hardware controlled applications.
These terminals require a positive $5 \mathrm{~V} \sim 24 \mathrm{~V}$ signal across the $3 \sim 8$ Pins (these are the anode connections for external trigger, panel enable/disable, and the four panel BCD inputs) and a common potential across pins 28~33. A constant current diode is in series with the $5 \sim 24 \mathrm{~V}$ supply to limit the current flowing through the photo diode. There is no need for a current limiting resistor for the inputs or outputs of the Control I/O Connector.

## I nputs

There are 3 groups of inputs available from the Control I/O Connector:

* CONTROL PANEL/EXT (Pins $3 \& 28$ ) - This input works in conjunction with the front panel trigger or the rear panel External Trigger Input. When this input is true (current flows through pins $3 \& 28$ ) the rear panel External Trigger is enabled. If the Control PANEL/EXT input is false, then the triggering must be performed from the front panel.
* External Trigger (Pins 4 \& 29) - Used with the CONTROL PANEL/EXT input. The 3550 will take measurements when the CONTROL PANEL/EXT input AND External Trigger are true.
* Panel BCD Inputs, [Pins 5~8 (Anode) and Pins 30~33 (Cathode)]. - A BCD setting of 0~9 is required. Settings other than $0 \sim 9$ will automatically default to panel 9.

The inputs of the Control I/O Connector are optically Isolated. The figure below is a representation of a typical input.

Figure 5.1 - Input Schematic


28~33

## Control I/ O Connector cont'd:

## Outputs

The 3550 has 5 data output lines available for external monitoring. Each of the data outputs are optically isolated and current limited through the use of a constant current diode as shown in the illustration below:

Figure 5.2 - Output Schematic


## Control I/ O Connector cont'd:

## Timing Diagrams

Figure 5.3a - Test Busy Operation


Figure 5.3b - Measure End Operation


Figure 5.3c-GO/ NO-GO Operation


## Control I/ O Connector cont'd:

Table 5.1-Connector Pin Designations

| $\begin{aligned} & \text { PI N } \\ & \text { NO. } \end{aligned}$ | Signal Name | PIN NO. | Signal Name |
| :---: | :---: | :---: | :---: |
| 1 | EXT POWER | 26 | EXT POWER |
| 2 | EMITTER COMMON | 27 | EMITTER COMMON |
| 3* | CONTROL PANEL/EXT (A) | 28* | CONTROL PANEL/EXT (K) |
| 4* | EXTERNAL TRIGGER (A) | 29* | EXTERNAL TRIGGER (K) |
| 5* | PANEL $2^{3}$ (A) | 30* | PANEL $2^{3}$ (K) |
| 6* | PANEL $2^{2}$ ( A$)$ | 31* | PANEL $2^{2}$ (K) |
| 7* | PANEL $2^{1}$ ( A$)$ | 32* | PANEL $2^{1}$ (K) |
| 8* | PANEL $2^{0}$ ( A$)$ | 33* | PANEL $2^{0}$ (K) |
| 9 |  | 34 |  |
| 10 |  | 35 |  |
| 11 |  | 36 |  |
| 12 |  | 37 |  |
| 13 | DISPLAY A HNG | 38 | DISPLAY B HNG |
| 14 | DISPLAY A LNG | 39 | DISPLAY B LNG |
| 15 | DISPLAY A GO | 40 | DISPLAY B GO |
| 16 | TOTAL GO | 41 | TOTAL NG |
| 17 | BIN $2^{3}$ | 42 | BIN $2^{2}$ |
| 18 | BIN $2^{1}$ | 43 | BIN $2^{0}$ |
| 19 | TEST BUSY | 44 | MEASURE END |
| 20 | ERROR | 45 |  |
| 21 |  | 46 |  |
| 22 |  | 47 |  |
| 23 |  | 48 |  |
| 24 |  | 49 |  |
| 25 |  | 50 |  |
| * : Input Pin <br> (A) and (K) are the Anode(A) and Cathode( $K$ ) of the photo coupler LED Output is the Open Collector of the transistor of the photo coupler |  |  |  |

## Control I/ O Connector cont'd:

Table 5.2-Control I/ O Function Summary


## Control I/ O Connector cont'd:

Figure 5.4-Sample Diagram of External Connections to Sequencer


Note: The diagram above provides examples of typical input and output connections as required for interface to a sequencer. Similar connections apply to the remaining terminals of the I/O Connector.

## RS-232C

## I nterface Cable

The interface is based on RS-232C. The 3550 is designed to act as the DTE side, so please use a cross cable when connecting with a personal computer or other controller unit.

## I nput Format

Remote In-Commands
To activate the RS-232C, send the "REN" command. This will change the 3550 from Panel Mode to Remote Mode.

## Entering Program Codes

Program codes will be sent from the controller unit to the 3550 as a string of ASCII characters. To change the panel number, "PAN*" should be sent. (If a Panel Number is not relayed, then the currently displayed panel will be re-set by the command)
e.g.) "PANO FAO RO MO SO EO"

Notice that a space is necessary between each of the commands. If a space does not precede a command, then the subsequent command/s will be ignored.

## Setting Limit Values

Below is an example of how the high and low limits of a BIN are set for DISPLAY A and DISPLAY B.
e.g.) "BIN1 CAL+1.0000e-06 CAH+1.5000E-06"
"BIN1 CBL+0.0100e00 CBL+0.1000e00"
The order of LOW and HIGH values may be reversed. Programming LOW or HIGH alone is also permitted.
$\begin{array}{ll}\text { e.g.) } & \text { "BIN1 CAH+1.5000e-06 CAH+1.0000e-06" } \\ & \text { "BIN1 CAL+1.0000e00" }\end{array}$
To invalidate a specific BIN's high or low limit value replace the polarity and numerical data with a series of nine dashes as expressed below:
e.g.) "BIN1 CAL---------"

This command will invalidate the comparator's DISPLAY A, low limit value.

## RS-232C

## I nput Format cont'd

## Setting the Measurement Voltage

The voltage setting range is from 0.01 V through 5.00 V , in 0.01 V increments. However, for frequencies between $1.00 \mathrm{MHz} \sim 5.00 \mathrm{MHz}$, the range is limited to $0.01 \mathrm{~V} \sim 1.00 \mathrm{~V}$.

Units: Volts
Resolution: 3 digits

$$
\begin{array}{lll}
\text { e.g.) } & \text { "LEV1.00EO" } & \text { (Set the Measurement Voltage to } 1.00 \mathrm{~V} \text { ) } \\
& \text { "LEV1.52EO" } & \text { (Set the Measurement Voltage to } 1.52 \mathrm{~V} \text { ) }
\end{array}
$$

Values, which are less than the 0.01 V steps, will be automatically truncated.
e.g.) "LEV1.248E00" (Set the Measurement Voltage to 1.24 V )

The 3550 will automatically reassign voltage levels if the absolute maximum levels are exceeded. As shown above, any voltage defined with less than 0.01 V resolution will automatically be truncated to 0.01 V resolution. Voltage levels exceeding 5.00 V will automatically become 5.00 V . If the test frequency is greater than 1.00 MHz , voltages defined that exceed 1.00 V will become 1.00 V .

## Setting Measurement Currents

For frequencies from 42.0 Hz to 1.00 MHz , the test current setting ranges from $0.01 \mathrm{~mA} \sim 99.99 \mathrm{~mA}$ in 0.01 mA steps. If the test frequency is between $1.01 \mathrm{MHz} \sim 5.00 \mathrm{MHz}$, the current setting are limited to $0.01 \mathrm{~mA} \sim 20.00 \mathrm{~mA}$.

Unit: mA Significant Digits: 3 digits

$$
\begin{array}{ll}
\text { e.g.) } & \text { "LEI1.00E0" } \\
& \text { "LEI15.20E0" }
\end{array}
$$

Like the voltage settings, any values less than the 0.01 mA resolution will be automatically truncated.
e.g.) "LEV1.549E00" (Set the Measurement Current to 1.54 mA )

The 3550 will automatically reassign test current levels if the absolute minimum or maximum levels are exceeded. As shown above, any current level defined with less than 0.01 mA resolution will automatically be truncated to a value with 0.01 mA resolution. Defined current levels exceeding 99.99 mA will automatically become 99.99 mA . If the test frequency is greater than 1.00 MHz , test current will be limited to 20.00 mA .

## RS-232C

## I nput Format cont'd

## Setting the Measurement Frequency

The setting range for Measurement Frequency is between $42.0 \mathrm{~Hz} \sim 5.00 \mathrm{MHz}$.
Unit: Hz
Significant Digits: 3 digits.

```
e.g.) "FRE42.0EO" ~ "FRE99.9E0" 42.0Hz ~ 99.9Hz
    "FRE100EO" ~ "FRE999E0" 100Hz ~ 999Hz
    "FRE1.00E3" ~ "FRE9.99E3" 1.00kHz ~ 9.99kHz
    "FRE10.0E3" ~ "FRE99.9E3" 10.0kHz ~ 99.9kHz
    "FRE100E3" ~ "FRE999E3" 100kHz ~ 999kHz
    "FRE1.00E6" ~ "FRE5.00E6" 1.00MHz ~ 5.00MHz
```

Because the 3550 uses exponential number formatting for the test frequency, variations of the above format may be used. To set 100 kHz , the following methods are also valid:

```
e.g.) "FRE1.00E5" -OR- "FRE10.0E4"
    (Set the test frequency to 100kHz)
```


## Setting the Number of Averages per Reading

To change the number of measurements to be averaged use the " $\mathrm{V} *$ " command.

* can be replaced by values between 1~100
e.g.) "V55" (Set the number of averages to 55 samples)

Errors in defining the number of samples to be averaged for a reading are addressed as follows:

Settings outside the range of $1 \sim 100$, are considered program errors.
e.g.) The values 0 or 101 would be considered invalid values for the average parameter.

## RS-232C

Table 5.3a - Command Summary

| Function | Program Code | Content | Remarks |
| :---: | :---: | :---: | :---: |
| Panel | $\begin{gathered} \text { *PANO } \\ \text { PAN9 } \end{gathered}$ | Panel Number |  |
| DISPLAY A Measurement Function | $\begin{array}{\|l} \text { FA0 } \\ \text { FFA1 } \\ \text { FA2 } \\ \text { FA3 } \\ \text { FA4 } \\ \hline \end{array}$ | DISPLAY A Measurement Item Change | Measurement Item "L" Measurement Item "C" Measurement Item "R" Measurement Item "\|Z|" Measurement Item " $\mathrm{Y} \mid$ " |
| DISPLAY B Measurement Function | FA *FB0 FB1 FB2 FB3 FB4 FB5 FB6 FB7 | DISPLAY B Measurement Item Change | Measurement Item "D" Measurement Item "Q" Measurement Item " $\mathrm{R}_{\mathrm{s}}$ " Measurement Item "Rp" Measurement Item "G" Measurement Item "X" Measurement Item "B" Measurement Item " ${ }^{\text {" }}$ |
| Measurement Range | $\begin{aligned} & \text { *R0 } \\ & \text { R1 } \\ & \text { R2 } \\ & \text { R3 } \\ & \text { R4 } \\ & \text { R5 } \\ & \text { R6 } \\ & \text { R7 } \\ & \text { R8 } \\ & \text { R9 } \end{aligned}$ | Auto Range Settings <br> Rangel <br> Range2 <br> Range3 <br> Range4 <br> Range5 <br> Range6 <br> Range7 <br> Range8 <br> Range9 | AUTO RANGE <br> $100 \mathrm{~m} \Omega$ Range <br> $1 \Omega$ Range <br> $10 \Omega$ Range <br> 100 RRange <br> $1 \mathrm{k} \Omega$ Range <br> 10k RRange <br> $100 \mathrm{k} \Omega$ Range <br> $1 \mathrm{M} \Omega$ Range <br> $10 \mathrm{M} \Omega$ Range $100 \mathrm{M} \Omega$ Range |
| Measurement Mode | $\begin{aligned} & * \text { M0 } \\ & \text { M1 } \\ & \text { M2 } \end{aligned}$ | Auto Mode Settings Series Mode Settings Parallel Mode Setting | AUTO MODE SER MODE PRL MODE |
| Measurement Frequency | FRE | Measurement Frequency Settings | "42.0E0"~"5.00E6" |
| Measurement Mode Change | $\begin{aligned} & * \mathrm{JV} \\ & \mathrm{JCV} \\ & \mathrm{JCC} \end{aligned}$ | Voltage <br> Measurement <br> Fixed Voltage Measurement <br> Fixed Current Measurement | Open Terminal Voltage Measurement Mode Fixed Voltage Measurement Mode <br> Fixed Current Measurement Mode |
| Measurement Signal Voltage | LEV | Measurement Signal Voltage Settings | "0.01E0"~"5.00E0" |
| Measurement Signal Current | LEI | Fixed Current Mode Current Settings | "0.01"~"99.99" |

## RS-232C

Table 5.3b-Command Summary cont'd

| Function | Program Code | Content | Remarks |
| :---: | :---: | :---: | :---: |
| Service Request | $\begin{aligned} & * \text { s0 } \\ & \text { S1 } \end{aligned}$ | OFF | SRQ Settings for GPIB |
| Measurement Start-Up Trigger | $\begin{array}{\|l\|} \hline \text { *E0 } \\ \text { E1 } \\ \text { E2 } \\ \text { E3 } \\ \hline \end{array}$ | Internal Trigger External Trigger TRIGGER EXT "T0"Trigger | Address Command GET Start <br> Start by "MAN" <br> Listener-Address Designation <br> Start |
| Trigger | T0 | Trigger Command | Only Valid for "E3" |
| Initial Settings | $\left\lvert\, \begin{aligned} & 10 \\ & 11 \end{aligned}\right.$ | Clear Panel Clear All Panels |  |
| Zero Offset | Z0 | Offset Clear | Clear Correction Value |
|  | Z1 | ZERO OPEN | Measurement Terminal OPEN -ZERO Correction |
|  | Z2 | ZERO SHORT | Measurement <br> Terminal <br> SHORT-ZERO Correction |
|  | Z3 | Spot OPEN | OPEN-ZERO Spot Correction |
|  | Z4 | Spot SHORT | SHORT-ZERO <br> Spot Correction |
|  | Z5 | Spot Correction Clear | Correction Value Spot Clear |
| Command Lock | $\begin{aligned} & \hline \begin{array}{l} * \mathrm{LO} \\ \mathrm{LI} \\ \hline \end{array} \mathbf{l} \\ & \hline \end{aligned}$ | Lock OFF <br> Lock ON |  |
| Measurement Conditions Monitor | MON | Measurement Conditions Monitor |  |
| Measurement Data Averaging | V | Averaging Times | Set 1~100 |
| Data Output | REN | Measurement Data Output | Set so that data output will be through GPIB/RS232C |
| Correction Frequency Limit | WCLIO | Invalid Low Frequency limit |  |
|  | WCLI 1 | Effectively Low Frequency limit |  |
|  | WCHIO | Invalid High Frequency limit |  |
|  | WCHI 1 | Effectively Low Frequency limit |  |
|  | WCL | Low Frequency limit setting | "WCL42.0E0" ~ "WCL5.00E6" |
|  | WCH | High Frequency limit setting | "WCH42.0E0" ~ "WCH5.00E6" |
| Data Output Destination Selection | O0 | Output OFF | GPIB only valid with Installed Option |
|  | 01 | RS232C Only |  |
|  | 02 | GPIB Only |  |
|  | 03 | RS232C/GPIB |  |

## RS-232C

Table 5.3c - Command Summary cont'd

| Function | Program Code | Content | Remarks |
| :---: | :---: | :---: | :---: |
| Soft Version | VER | Information on the Software Version |  |
| Spot Correction Input Number | SPX | Spot Correction Select from 1 to 3 | "SP1" |
| Spot Correction Frequency Limit | XXX | Set Spot Frequency | "SPF42.0E0" ~ "SPF5.00E6 |
| *1) * indicates initial setting <br> *2) If a non-program code is entered, it will be considered invalid, and no setting will be made. In this case, the previous setting will be unchanged. <br> NOTE 1: After receiving "L1", only "L0", "T0" and GET can be received. <br> NOTE 2: As soon as "MON" is sent, make sure that the system is ready to receive. <br> NOTE 3: Settings will vary according to the measurement range and measurement frequency. <br> Please refer to the range charts. <br> NOTE 4: After the termination of zero offset, the following indications are shown on the computer. <br> "Correct OK" - Zero correction has executed properly <br> "Correct Error Impedance Under" - The open circuit impedance is less than $1 \mathrm{k} \Omega$, which is beyond correction limits. <br> "Correct Error Impedance Over" The short circuit impedance has exceeded $1 \mathrm{k} \Omega$, which is beyond correction limits. |  |  |  |

## RS-232C

Table 5.4-Comparator Instructions

| Function | Program Code | Content | Remarks |
| :---: | :---: | :---: | :---: |
| Comparator | *C0 | Comparator OFF |  |
|  | C1 | Comparator ON |  |
| Comparator Mode | CP0 | Absolute Value Setting | Absolute Value Setting Comparator |
|  | CP1 | \% Setting | \% Setting Comparator |
| Bin Number | BIN |  | Sorting Category BIN No.(19) |
| Absolute Value Setting Limit Values | $\begin{aligned} & \text { CALXXXX } \\ & \text { CAHXXXX } \\ & \text { CBLXXXX } \\ & \text { CBHXXXX } \end{aligned}$ | DISPLAY A LOW DISPLAY A HIGH DISPLAY B LOW DISPLAY B HIGH | XXXX: $\pm 0.0000 \mathrm{e} 00 \sim \pm 1.9999 \mathrm{e} 08$ Disabled Setting = "---------" |
| \% Setting Limit Values | CAPXXXX <br> CBPXXXX <br> PALXXXX <br> PBLXXXX <br> PAHXXXX <br> PBHXXXX | DISPLAY A Std. Value DISPLAY B Std. Value DISPLAY A Min. \% DISPLAY B Min. \% DISPLAY A Max. \% DISPLAY B Max. \% | XXXX: $\pm 0.0000 \mathrm{e} 00 \sim \pm 1.9999 \mathrm{e} 08 \mathrm{XXXX}$ : $\pm 0.0000 \mathrm{e} 00 \sim \pm 2.000 \mathrm{e} 02$ <br> Disabled Setting = "---------" |
| *1) * indicates a initial setting <br> NOTE 1: As soon as "LIM" is sent, make sure that the system is ready to receive signals. |  |  |  |

## RS-232C

## Data Output Format for Measurement Settings

## Output Format Sample



| 1 | Indexing Number | 15 | Circuit Mode <br> There is no circuit mode on Z and <br> Y, alternatively. "-- is outputted. |
| :---: | :--- | :---: | :--- |
| 2 | Panel Number | 16 | Data Temp. Value (A) |$|$| 3 | Measurement Frequency Temp. Value | 17 |
| :---: | :---: | :--- |
| Data Exponent (A) |  |  |
| 4 | Measurement Frequency Exponent | 18 |
| Data Unit (A) |  |  |
| 5 | Measurement Frequency Unit | 19 |
| 6 | Measurement Mode | 20 |
| Status (B) |  |  |
| 7 | Test Piece Voltage Temp. Value | 21 |
| 8 | Test Piece Voltage Exponent | 22 |
| 9 | Test Piece Voltage Unit | Data Temp. Value (B) |
| 10 | Test Piece Current Temp. Value | 23 |
| 11 | Test Piece Current Exponent | 24 |
| 12 | Test Piece Current Unit | 25 |
| 13 | Status Unit (B) (A) | 26 |
| 14 | Function (A) | 27 |

NOTES:

* For the Comparator Result, if the Comparator is OFF, 2 "_" symbols (ASCII Code 2Dh) will be outputted instead of a result.
* For the Bin No., if the Comparator is OFF, 4 " " symbols (ASCII Code 2Dh) will be outputted.
* In the Format Sample, the "_" denotes a "space" (ASCII code 20h).


## RS-232C

Table 5.5a - Data Output Code Functions

| Number | Output Code | Content |
| :---: | :---: | :---: |
| 1 | **** | Index Number (0001~9999) |
| 2 | P* | Panel Number (0~9) |
| 3 | $\begin{aligned} & * * . * \\ & * . * * \\ & * * * \end{aligned}$ | Measurement Frequency Temp. Value <br> e.g.) $42.0 \mathrm{~Hz} \rightarrow$ "42.0": $100 \mathrm{~Hz} \rightarrow$ "100.": $1.00 \mathrm{kHz} \rightarrow$ "1.00" |
| 4 | E** | Measurement Frequency Exponent <br> e.g.) "E+00" $\rightarrow \mathrm{Hz}: ~ " E+03 " \rightarrow \mathrm{kHz:} \mathrm{"E+06"} \rightarrow \mathrm{MHz}$ |
| 5 | Hz | Measurement Frequency Unit |
| 6 | OV | Open Voltage Mode |
|  | CV | Fixed Voltage Mode |
|  | CC | Fixed Current Mode |
| 7 <br> 8 | +*.****E ${ }^{* *}$ | $\begin{aligned} & \text { Test Piece Voltage Temp. Value Exponent } \\ & \text { e.g.) } 1.00 \mathrm{~V} \rightarrow " 1.0000 \mathrm{E}+00 " \\ & 0.10 \mathrm{~V} \rightarrow " 100.00 \mathrm{E}-03 " \\ & \hline \end{aligned}$ |
| 9 | V | Test Piece Voltage Unit |
| 10 <br> 11 | +*.****E-** | Test Piece Voltage Temp. Value Exponent e.g.) $10.00 \mathrm{~mA} \rightarrow$ " $10.000 \mathrm{E}-03$ " $0.01 \mathrm{~mA} \rightarrow " 10.000 \mathrm{E}-06 "$ |
| 12 | A | Test Piece Current Unit |
| 13 | 0 | Over Range |
|  | N | Measurement Data Normal |
|  | U | Under Range |
|  | E | Error |
| 14 | L | Inductance Measurement (L) |
|  | C | Capacity Measurement (C) |
|  | R | Resistance Measurement (R) |
|  | Z | Impedance Measurement (\|Z|) |
|  | Y | Admittance Measurement (\|Y|) |
| 15 | $\begin{array}{\|l} \hline S \\ P \\ \hline \end{array}$ | Series Mode Measurement <br> Parallel Mode Measurement - $\mathrm{Z}\|,\|\mathrm{Y}\|$ "-"symbols (ASCII Code 2Dh) |
| 16 | +1.9999 | Over Range, Measurement Data Abnormal |
|  | $\pm * . * * * *$ | Under Range, Measurement Data Normal |
| 17 |  | Measurement Data Exponent |
|  | E-12 | p |
|  | E-09 | $\left(10^{-9}\right)$ |
|  | E-06 | $\mathrm{M} \quad\left(10^{-6}\right)$ |
|  | E-03 | m |
|  | E+00 | (10) |
|  | E+03 | $\left(10^{3}\right)$ |
|  | E+06 | M (106) |

## RS-232C

Table 5.5b - Data Output Code Functions cont'd:

| Number | Output Code | Content |
| :---: | :---: | :---: |
| 18 |  | DISPLAY A Display Unit |
|  | H | For Inductance Measurement |
|  | F | For Capacity Measurement |
|  | R | For Resistance, Impedance Measurement |
|  | S | For Admittance Measurement |
| 19 | LO | LOW NO-GO |
|  | GO | GO |
|  | HI | HIGH NO-GO |
|  | -- | Comparator OFF (ASCII Code 2Dh, outputted 2 times) |
| 20 | $\begin{array}{\|l\|} \hline \mathrm{O} \\ \mathrm{~N} \end{array}$ | Over Range Measurement Data Normal |
| 21 | D0 | Loss Coefficient Measurement (D) |
|  | Q0 | Quality Measurement (Q) |
|  | RS | Equivalent Series Resistance Measurement( $\mathrm{R}_{\mathrm{s}}$ ) |
|  | RP | Equivalent Parallel Resistance Measurement ( $\mathrm{R}_{\mathrm{P}}$ ) |
|  | G0 | Conductance Measurement (G) |
|  | X0 | Reactance Measurement (X) |
|  | B0 | Susceptance Measurement (B) |
|  | A0 | Phase Angle Measurement ( $\theta$ ) |
| 22 | +1.9999 | Over Range, Measurement Data Abnormal |
|  | $\pm$ *.**** | Under Range, Measurement Data Normal |
| 23 |  | Measurement Data Exponent |
|  | E-09 | n ( $\left.10^{-9}\right)$ |
|  | E-06 | $\mu$ $\left(10^{-6}\right)$ |
|  | E-03 | $\mathrm{m} \quad\left(10^{-3}\right)$ |
|  | E+00 | (10 ${ }^{\circ}$ ) |
|  | E+03 | k ${ }^{\text {k }}$ (103) |
|  | E+06 | M $\left(10^{6}\right)$ |
| 24 | R | For Equivalent Parallel + Series Resistance Measurement, and also Reactance Measurement |
|  | S | For Conductance and Susceptance Measurement |
|  | - | For Loss Coefficient, Quality Measurement, Phase Angle Measurement (ASCII Code 5Fh) |
| 25 | LO | LOW NO-GO |
|  | GO | GO |
|  | HI | HIGH NO-GO |
|  | -- | Comparator OFF (ASCII Code 2Dh, outputted 2 times) |
| 26 | BIN* | BIN Number Decision Result ( *:0 9) If Comparator is OFF, then " $\qquad$ "(ASCII Code 2Dh, 4times) |
| 27 | GO | TOTAL GO |
|  | NG | TOTAL NO-GO |
|  | -- | Comparator OFF (ASCII Code 2Dh, 2times) |
| 28 | $\mathrm{C}_{\mathrm{R}}+\mathrm{L}_{\mathrm{F}}$ | Delimiter. For RS-232C, only $\mathrm{C}_{\mathrm{R}}+\mathrm{L}_{\mathrm{F}}$ |

## RS-232C

## Monitor Output Format

## Output in Relation to Monitor Command "MON"

For all 10 panels, (0~9) the PANEL No., DISPLAY A Function, DISPLAY B Function, CIRCUIT MODE, RANGE, Measurement Signal Frequency and Measurement Signal Voltage will be outputted and divided by spaces. At the end, whether or not there is a Limit Value will be indicated as well.

Output Format Sample:


| 1 | - Panel Number |
| :--- | :--- |
| 2 | - DISPLAY A Function |
| 3 | - DISPLAY B Function |
| 4 | - Range Number |
| 5 | - Measurement Circuit Mode |
| 6 | - Measurement Signal Frequency Temp. Value |
| 7 | - Measurement Signal Frequency Exponent |
| 8 | - Measurement Mode |
| 9 | - Measurement Signal Voltage Temp. Value |
| 10 | - Measurement Signal Voltage Exponent |
| $\frac{11}{12}$ | - Measurement Data Averaging |
| 13 | - Comparator (*:ON -: OFF) |

NOTE: In the Output Format Sample, the "_" denotes a space (ASCII Code 20h).

## RS-232C

## Monitor Output Format

## Output in Relation to Limit Monitor Command "LI M"

## Absolute Value Settings Mode

This will output the PANEL No., BIN No., LOW LIMIT, and HIGH LIMIT for BIN No. 1 No. 9 in the order of DISPLAY A and then DISPLAY B.
However, if "LIM" is sent when the Panel Number is" 0 ", the system will announce an error.
Output Format Sample

```
P1_BIN1_CPO_+9.9000E-03H/+10.100E-03H_+1.0000E+00R/+10.000E+00R
P1_BIN2_CPO_+9.8000E-03H/+10.200E-03H_+10.000E+00R/+100.00E+00R
P1_BIN3_CPO_+9.7000E-03H/+10.300E-03H_+100.00E+00R/+1.0000E+03R
P1_BIN4_CPO_-----------/-------------------------------------
P1_BIN5_CPO_-----------/-------------------------------------
P1_BIN6_CPO_-----------/--------------------------------------
P1_BIN7_CPO_-----------/--------------------------------------
P1_BIN8_CPO_-----------/--------------------------------------
P1-BIN9-CPO----------/---------------------------------------10
```

\author{

- Delimiter
}

BIN Number

- Low Limit Setting Value
- Divider for High/Low Settings (2Fh)
- High Limit Setting Value
- Comparator Mode


## NOTES:

* Places with no setting will be filled with "- $\qquad$ -" (ASCII Code 2Dh×12)
* D, Q, and $\theta$ will have a "_"(ASCII Code 5Fh) for their "Unit"
* In Output Format Sample, the "_" denotes a space (ASCII Code 20h)


## RS-232C

## Monitor Output Format

Output in Relation to Limit Monitor Command "LI M"
\% Setting Mode
Output Format Sample


1 - Panel Number
13 - Delimiter
14 - BIN Number
16 - Divider for High and Low Settings (2Fh)
18 - Comparator Mode
19 - Standard (Std.) Value
20 - Low Limit Value Setting
21 - High Limit Value Setting

NOTES:

* Places with no setting will be filled with "-------" (ASCII Code 2Dh×7)
* D, Q, and $\theta$ will have a " _"(ASCII Code 5Fh) for their "Unit"
* In Output Format Sample, the "_" denotes a space (ASCII Code 20h)


## RS-232C

Table 5.6a-Monitor Output Code Functions

| Number | Output Code | Content |
| :---: | :---: | :---: |
| 1 | P* | Panel Number(*:1~9) |
| 2 | L | Inductance Measurement (L) |
|  | C | Capacity Measurement (C) |
|  | R | Resistance Measurement (R) |
|  | \| $\mathrm{Z} \mid$ | Impedance Measurement (\|Z|) |
|  | \|Y| | Admittance Measurement (\|Y|) |
| 3 | D0 | Loss Coefficient Measurement (D) |
|  | Q0 | Quality Measurement (Q) |
|  | RS | Equivalent Series Resistance Measurement ( $\mathrm{R}_{\mathrm{S}}$ ) |
|  | RP | Equivalent Parallel Resistance Measurement ( $\mathrm{R}_{\mathrm{P}}$ ) |
|  | G0 | Conductance Measurement (G) |
|  | X0 | Reactance Measurement (X) |
|  | B0 | Susceptance Measurement (B) |
|  | A0 | Phase Angle Measurement ( $\theta$ ) |
| 4 | A | Auto Circuit Mode |
|  | S | Series Equivalent Circuit Mode |
|  | P | Parallel Equivalent Circuit Mode |
| 5 | R0 | Auto Range |
|  | R1 | $100 \mathrm{~m} \Omega$ Range |
|  | R2 | $1 \Omega$ Range |
|  | R3 | 10תRange |
|  | R4 | 100תRange |
|  | R5 | 1 k RRange |
|  | R6 | 10k 2 Range |
|  | R7 | 100kRRange |
|  | R8 | $1 \mathrm{M} \Omega$ Range |
|  | R9 | $10 \mathrm{M} \Omega$ Range |
| 6 | $\begin{aligned} & \hline * * . * \\ & * . * * \\ & * * * . \end{aligned}$ | Measurement Frequency Temp. Value e.g.) $42.0 \mathrm{~Hz} \sim$ "42.0": 100Hz~"100.": 1.00kHz~"1.00" |
| 7 | E+** | Measurement Frequency Exponent e.g.) " $\mathrm{E}+00$ " $\rightarrow \mathrm{Hz}:$ : $\mathrm{E}+03$ " $\rightarrow \mathrm{kHz:} \mathrm{"} \mathrm{E}+06$ " $\rightarrow \mathrm{MHz}$ |
| 8 | OV | Open Terminal Voltage Measurement Mode |
|  | CV | Fixed Voltage Measurement Mode |
|  | CC | Fixed Current Measurement Mode |
| 9 <br> 10 | +*.**** $\mathrm{E} \pm * *$ | Test Piece Voltage Temp. Value Exponent e.g.) 1.00V $\rightarrow$ "1.0000E +00 ": $0.10 \mathrm{~V} \rightarrow$ " $100.00 \mathrm{E}-03$ " |
| 11 |  |  |
| 12 | * | Comparator ON |
|  | - | Comparator OFF |
| 13 | $\mathrm{C}_{\text {R }}+\mathrm{L}_{\text {F }}$ | Delimiter, for RS-232C is $\mathrm{C}_{\mathrm{R}}+\mathrm{L}_{F}$ only |
| 14 | BIN* | BIN Number (*:0~9) |

## RS-232C

Table 5.6b - Monitor Output Code Functions cont'd


## RS-232C

## RS-232C Hardware and Computer Settings

Set the settings as indicated below. These are the default settings of the RS-232C interface.

| Baud rate | 9600 bps |
| :--- | :--- |
| Data length | 8 bit |
| Parity | NONE |
| Stop Bit | 1 bit |

## Sample programs for RS-232C

## Explanation of SAMPLE.BAS

The following is a sample program establishing basic initial settings and data Display conditions for the purpose of controlling the 3550 through the RS-232C.

* 1000-1070 are initial settings
* 1010 is the setting for the RS232C environment on the computer side.
* 1030 is the setting for the "break-in" (interruption) action by the computer.

When the power for the 3550 is turned on, the 3550 sends the text signal "3550" to the computer in order to determine whether a control device exists on the computer. The computer receives the signal, and then sends signals to establish the necessary basic settings within the 3550 main unit.

If the textual signal "3550" is received by the computer prior to line "1260" of sample.bas, the computer will send the command line "E3 REN O1" to the 3550, LCR meter.

For more details regarding "E3 REN O1" and other commands, refer to the command summary, Tables 5.3 a \& 5.3 b on pages 5-11 and 5-12. Basically, the RS-232C will use the external trigger and output the measurement data to an external device. The textual signal that the computer receives at this point will be displayed on the CRT. The "VER" in 1110 is the output command of the ROM version. The wait times indicated in 1120 and 1125 allow time for the computer to read the data. When the display is finished, the program will end.

## RS-232C

Sample programs for RS-232C

## SAMPLE.BAS

```
1000 REM sample.bas
1010 OPEN "COM:N81" AS #1 : CLS
1030 ON COM GOSUB *RECIEVE
1040 COM ON:KAN = 0
1050'
1055 *LABEL
1060 GOSUB *WAIT10
1070 IF KAN = 0 THEN GOTO *LABEL
1080'
1100 *LABEL2
1110 PRINT#1,"VER"
1115 F = 0
1120 GOSUB *WAIT10
1125 IF F = 0 THEN GOTO 1120
1130 PRINT "end"
1140 COM OFF
1150 END
1160'
1170 *RECIEVE
1180 IF LOC(1) <> 0 THEN GOTO 1200
1190 GOTO 1290
1200 GOSUB *WAIT10
1210 W$ = INPUT$(LOC(1),#1)
1220 D$ = LEFT$(W$,6):F = 1
1230 IF(D$ = "3550" AND KAN = 0)THEN GOTO 1260
1240 PRINT LEFT$(W$,LEN(W$)-3)
1250 GOTO 1290
1260 PRINT#1,"E3 REN O1"
1270 PRINT D$
1280 KAN = 1:GOSUB *WAIT10
1290 RETURN
1299'
1300 *WAIT10
1310 FOR I=0 TO 1000:NEXT I
1320 RETURN
```


## RS-232C

## Sample programs for RS-232C

## Explanation of SAMPLE2.BAS

This sample program changes frequencies from 100 Hz to 10 kHz in 100 Hz increments, and calculates the capacitor value and phase angle in relation to the changes.

* Lines 1000 to 1070 are basic settings for the main unit of the 3550 .
* In Line 1130, PRINT \#1, "PAN2 E3 O1, FA1 FB7" indicates settings for measurement conditions that will calculate the condenser value and phase angle, and output with RS232C, panel 2, TO trigger 01.

The 3550 can store 10 pages of settings. However, the initial setting of the trigger is the internal trigger for EO, so it is necessary to change the trigger mode to the mode of the external TO command immediately after changing the panel number. Note that each command is separated by a space. Also, single commands like: PRINT \#1 "TO" are also possible, but when the panels need to be changed, complex commands such as below are necessary:

PRINT \#1 "PAN2 E3"

* Lines 1150 to 1220 are where measurements are made while the frequency is changing.
* Line 1180 is "FRExxxxxx TO", where xxxxxx is the frequency value setting and TO is the measurement trigger.
* The wait times of 1200 and 1210 are used to wait for data reception and end of display.
* The program will cycle through 1150 to 1220 until the measurement frequency reaches 10 kHz . and then it will terminate.


## RS-232C

Sample programs for RS-232C
SAMPLE2.BAS

```
1000 REM sample2.bas
1010 OPEN "COM:N81" AS #1 : CLS
1020 KAN = 0
1030 ON COM GOSUB *RECIEVE
1040 COM ON
1050 *LABEL
1060 GOSUB *WAIT10
1070 IF KAN = 0 THEN GOTO *LABEL
1080'
1090 GOSUB *WAIT10
1110 *LABEL2
1120 GOSUB *WAIT10
1130 PRINT#1,"PAN2 E3 O1 FA1 FB7"
1140 GOSUB *WAIT10
1150 FOR J=100 TO 10000 STEP 100
1160 K= LEN(STR$(J))
1170 A$=MID$(STR$(J),2,K-1)
1180 PRINT#1,"FRE"+A$+" T0"
1190 F = 1
1200 GOSUB *WAIT10
1210 IF F=1 THEN GOTO 1200
1220 NEXT J
1230 PRINT "end"
1235 COM OFF
1240 END
1250'
1260 *RECIEVE
1280 IF LOC(1) <> 0 THEN GOTO 1300
1290 GOTO 1390
1300 GOSUB *WAIT10
1320 D$ =INPUT$(LOC(1),#1):PRINT D$
1330 D$=LEFT$(D$,6):F = 0
1340 IF D$ = "3550" THEN GOTO 1360
1350 GOTO 1390
1360 PRINT#1,"E3 REN O1"
1380 KAN = 1:GOSUB *WAIT10
1390 COM ON: RETURN
1400 *WAIT10
1410 FOR I=0 TO 1000:NEXT I
1420 RETURN
```


## RS-232C

Sample programs for RS-232C

## SAMPLE2.BAS cont'd:

Note 1: In Line 1400, WAIT10 may need be adjusted according to the speed of the computer. This program was tested on a Epson PC 486 Note AU DX4. Make adjustments for your computer if necessary.

The settings format and weight adjustments are the same even if Visual Basic 6 is used, so there should be no problem using the above sample as reference.

Note 2: When running this program, please start-up the program first. Then, after the program is started, power the 3550 .

## The GPI B I nterface (Optional)

## General Description of GPI B

Part \#3505, is the optional GPIB communications board offered with the 3550 LCR Meter. Installing the board onto the main unit of the 3550 LCR Meter makes remote control and data output possible. After the 3505 has been installed into the 3550 , it will have the capability to perform both "talker" and "listener" functions.

## Primary Specifications of GPI B

The GPIB connector is a standard 24-pin connector. The pin arrangement and signal protocol conform to the IEEE-488 standard (1978). The GPIB interface functions are listed in the table below:

Table 5.7 - GPI B Functions

| NAME | Code | FUNCTI ON |
| :--- | :--- | :--- |
| Source Handshake | SH1 | All source handshake functions |
| Acceptor Handshake | AH1 | All accepting handshake functions |
| Talker | T5 | Basic Talker functions <br> Serial poll <br> Talker deactivation using MLA <br> Talk only-function |
| Listener | L4 | Basic listener functions <br> Listener deactivation using MTA |
| Service Request | SR1 | Send message during serial poll |
| Remote/Local | RL1 | Remote/Local switching function |
| Device Clear | DC1 | Machine initialization function |
| Device Trigger | DT1 | 4 types of DT1 commands; "E0","E1","E2",E3" |

## The GPI B I nterface

## I nstallation of the GPI B Board, Option \#3505

When installing this option board onto the main unit, follow the following directions:

1. Turn OFF the power of the 3550 and remove the $A C$ line cord. Remove screws " 1 " and " 2 " of the cord hook on the upper part of the rear side, and proceed to remove the top cover by pulling it rearward.

Figure 5.4a-Rear View

2. Remove screws " 3 " and " 4 " from the "blank panel", and then remove the "blank panel".
3. Next, install the GPIB board. Insert the GPIB board into the main unit through the place in the rear where the "blank panel" came off. Then tighten screws " 3 " and " 4 ".

## The GPI B I nterface

Installation of the GPI B Board, Option \#3505 cont'd:

Figure 5.4b-Side View

4. Then, connect the cable " 6 " of the GPIB board with the connector of the Control Board " 5 ".
5. Match the 2 holes (" 7 " and " 8 ") to the "pillars" on the Control Board, and tighten the screws.

Figure 5.4c - Top View

6. Replace the top cover.

NOTE: The input and output commands \& formats for GPIB are the same as they are for RS232C. Refer to the previous section on RS-232C communications for details regarding specific commands and formats.

## The GPI B I nterface

## Front Panel Status Display LEDs

On the front of the main unit, there are 4 LED's displaying the interface status of GPIB.
They light up under the following circumstances:
[SRQ]: An SRQ (service request) is being sent from the 3550 to the GPIB bus line.
[LTN]: The 3550 is set to be the Listener
[TLK]: The 3550 is set to be the Talker
[RMT]: The 3550 is being controlled remotely. When the GPIB bus line receives the commands REN, MLA "REN", and enters remote mode.

## LOCAL Key Switch

Pushing the LOCAL key-switch changes the machine to front panel operation.

## GPI B Switches (Delimiter, Talk-Only, Address Switch)

The optional GPIB board has switches for setting the Delimiter and Address.


When setting the GPIB address exercise caution not use the same address as other GPIB devices on the same bus. Please set the "TALK ONLY/ADDRESSABLE" switch to the "ADDRESSABLE" side, and establish different addresses for each device. On the "TALK ONLY" side, a GPIB interface may be installed, or the Listen-only Mode Printer may be used.

## Delimiter Output Format

Four output format choices are available using switches A \& B of the "DELIMITER", as shown below in chart 9-4.

| DELI MITER |  | Content <br> (Added to last line of data) | Output Code |
| :---: | :---: | :---: | :---: |
| A | B |  |  |
| 0 | 0 | Return+New Line( also EOI) | CR+LF |
| 0 | 1 | Return only | CR |
| 1 | 0 | New Line only | LF |
| 1 | 1 | EOI line is LOW |  |

The Address switches (A5 through A1) can be set within the binary range of (00000~11110) and decimal range of ( $0 \sim 30$ ). In binary " 11111 " and in decimal ' 31 ' cannot be set.

## The GPI B Interface

## Output Status Bits for Service Requests

After the power is turned ON, sending the command, "S1" allows "Service Requests" to be used. The status bits for the 3550 are positioned as indicated below.

Figure 5.5-GPIB Status Bits

| Bit7 | Bit6 | Bit5 | Bit4 | Bit3 | Bit2 | Bit1 | Bit0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0 | SRQ | 0 | Command Error | 0 | Data Continue | Hand Shake Error | Data Ready |
| (DIO8) | (DIO7) | (DIO6) | (DIO5) | (DIO4) | ( DIO 3$)$ | (DIO2) | (DIO1) |

Bit6: If a Service Request occurs under program code "S1", this will become "1" and the SRQ Line will be "True".
Bit4: When improper program codes or numerical data are received, this will become "1".
Bit2: While data flow is continuing, this will be "1".
Bit1: If a GPIB Handshake Error, or an unknown command is received, this will become "1".
Bit0: When data to be output is ready to go, this will become "1".

## Additional Notes for Using the GPI B Interface

1) Almost all of the switches on the front and rear panel of the 3550 can be controlled remotely through an external controller.
2) The 3550 should be designated as the Listener, and the necessary measurement parameter program codes should be sent from the controller. The program codes for GPIB are the same as the program codes for the RS-232C.
3) By setting "E1" within the program code, measurement using a "GET" message is possible. If "E2" is set; measurements will be made every time the "MAN/EXT" key on the panel is pressed.
4) The controller will then designate the 3550 as the Talker, and read the data.
5) If you would like to issue Service Requests from the serial poll, make sure that the controller reads the status bit related to the request.

## The GPI B I nterface

## Programming Examples

Below is a sample program for remotely controlling the 3550 using the GPIB controller. In this program, measurement is carried out while changing the frequency.
The example here is based on the commonly used PC-9801(NEC).

```
TO Trigger (without SRQ)
    110 ON HELP GOSUB *TESTEND
    120 CLS
    130 HELP ON
    140 ISET IFC
    150 FOR I=0 TO 100000!: NEXT I
    160 ISET REN
    170 CMD DELIM = 0
    180 PRINT @5;"ren"@
    190 PRINT @5;"s0 e3 o2"@
    200 FOR J=100 TO 10000! STEP 100
    210 K = LEN(STR$(J))
    220 A$ = MID$(STR$(J),2,K-1)
    230 PRINT @5;"fre"+A$+" T0"@
    240 LINE INPUT @5;A$
    250 LOCATE 0,10 : PRINT A$
    260 NEXT J
    270 GOTO 200
    280 *TESTEND
    290 END
```

TO Trigger (with SRQ)
110 ON HELP GOSUB *TESTEND
120 CLS
130 HELP ON
160 ISET IFC
170 FOR I=0 TO 100000! : NEXT I
180 ISET REN
190 CMD DELIM $=0$
200 PRINT @5;"ren"@
210 PRINT @5;"s1 e3 o2"@
220 FOR J=100 TO 10000! STEP 100
$230 \mathrm{~K}=\operatorname{LEN}(\mathrm{STR} \$(\mathrm{~J}))$
240 A $\$=$ MID $\$($ STR\$ (J) $), 2, \mathrm{~K}-1)$
250 PRINT @5;"fre"+A\$+" T0"@
260 FOR I = 0 TO 30 : NEXT I
270 POLL 5,SB
280 IF SB < 64 THEN GOTO 260
290 LINE INPUT @5;A\$
300 LOCATE 0,10:PRINT A\$
310 NEXT J
320 GOTO 220
330 *TESTEND
340 END

## The GPI B I nterface

## Programming Examples

GET Trigger

```
110 CLS
120 ISET IFC
130 FOR I=0 TO 100000!: NEXT I
140 ISET REN
150 CMD DELIM = 0
160 PRINT @5;"ren"@
170 PRINT @5;"s0 e1 o2"@
180 FOR J=100 TO 10000! STEP 100
190 K = LEN(STR$(J))
200 A$ = MID$(STR$(J),2,K-1)
210 PRINT @5;"fre"+A$ @
220 WBYTE &H2F,&H8;
230 LINE INPUT @5;A$
240 LOCATE 0,10 : PRINT A$
250 NEXT J
260 GOTO 180
270*TESTEND
280 END
```


## INSTRUMENT DESCRIPTION PREPARATION FOR USE QUICK START INSTRUCTIONS OPERATING INSTRUCTIONS PROGRAMMING \& INTERFACING SERVI CE I NFORMATI ON APPENDIX

## Warranty:

TEGAM, Inc. warrants this product to be free from defects in material and workmanship for a period of one year from the date of shipment. During this warranty period, if a product proves to be defective, TEGAM Inc., at its option, will either repair the defective product without charge for parts and labor, or exchange any product that proves to be defective.

TEGAM, Inc. warrants the calibration of this product for a period of 6 months from date of shipment. During this period, TEGAM, Inc. will recalibrate any product, which does not conform to the published accuracy specifications.

In order to exercise this warranty, TEGAM, Inc., must be notified of the defective product before the expiration of the warranty period. The customer shall be responsible for packaging and shipping the product to the designated TEGAM service center with shipping charges prepaid. TEGAM Inc. shall pay for the return of the product to the customer if the shipment is to a location within the country in which the TEGAM service center is located. The customer shall be responsible for paying all shipping, duties, taxes, and additional costs if the product is transported to any other locations. Repaired products are warranted for the remaining balance of the original warranty, or 90 days, whichever period is longer.

## Warranty Limitations:

The TEGAM, Inc. warranty does not apply to defects resulting from unauthorized modification or misuse of the product or any part. This warranty does not apply to fuses, batteries, or damage to the instrument caused by battery leakage.

## Statement of Calibration:

This instrument has been inspected and tested in accordance with specifications published by TEGAM Inc. The accuracy and calibration of this instrument are traceable to the National Institute of Standards and Technology through equipment, which is calibrated at planned intervals by comparison to certified standards maintained in the laboratories of TEGAM Inc.

## Contact I nformation:

TEGAM INC.
10 TEGAM WAY
GENEVA, OHIO 44041
PH: 440.466.6100
FX: 440466.6110
EMAIL: sales@tegam.com

## Repair Parts

The Model 3550 has no user replaceable parts. Available accessories are listed in Section I.

## Troubleshooting:

The TEGAM Model 3550 has been designed to provide many years of trouble free performance. However, there are some instances where harsh operating environments or excessive physical strain may cause premature failure. Should a malfunction of the 3550 be observed, it is recommended that certain steps be taken in order to assist our service department in identifying the cause of the malfunction and to provide the quickest possible turn around time for the repair cycle.

Below is a summary of some commonly observed symptoms and some possible remedies for ruling out the possibilities of user error or environmentally-related problems.

No Display - The display is completely blank.

- Check the power supply. Make sure that the AC line is operational and is supplying power to the unit.
- Check the fuse located in the rear panel. If a blown fuse is identified there is usually a reason for the fuse blowing, so the probability of another related problem is high.

Unstable Reading - The reading bounces erratically with no apparent pattern.
Be sure that the Operating Instructions have been reviewed and thoroughly understood. Constant voltage or constant current modes, sample averages, frequency and other settings can affect the stability of the reading. Readings that bounce out of the specification ranges can also indicate a problem with noise.

- Make sure that the test leads or fixtures are manufactured by TEGAM. All accessories for the 3550 are specially designed to minimize the effects of external noise to the measurement signal.
- Verify that there are no sources of noise in close proximity to the 3550, test leads, power leads, or test fixture. Sources of noise such as CRTs, relays, and other switching devices are primary causes for erratic readings.

I naccurate Reading - Measurements do not fall within expected or known values or accuracies.

- Perform Open and Closed Circuit Zero Correction procedures as instructed in this manual.
- Make sure that the Range is appropriate for the measurement.
- Verify that four or five-wire Kelvin measurement leads are being used and that they are not defective.
- Measured component values can sometimes vary with the test voltage or current being applied. Make sure that the manufacturer's recommended test settings are followed in order to duplicate measurement results. Sometimes constant current or constant voltage modes may be required to stabilize readings.
- Verify that the test fixture or leads is appropriate for the measurement to be performed. Not all fixtures and leads are designed for the entire range of 3550 test frequencies and measurement accuracies.


## Preparation for Repair or Calibration Service:

Once you have verified that the cause for 3550 problem cannot be solved in the field and the need for repair and calibration service arises, contact TEGAM customer service to obtain an RMA, (Returned Material Authorization), number. You can contact TEGAM customer service via the TEGAM website, www.tegam.com or by calling 440.466.6100 OR 800.666.1010.

The RMA number is unique to your instrument and will help us identify your instrument and to address the particular service request by you which is assigned to that RMA number. Of even importance, a detailed written description of the problem should be attached to the instrument. Many times repair turnaround is unnecessarily delayed due to a lack of repair instructions or of a detailed description of the problem.

This description should include information such as measurement settings, type of components being tested, whether the problem intermittent or constant?, when is the problem most frequent?, has the test changed since the last time the instrument was used?, Etc. Any detailed information provided to our technicians will assist them in identifying and correcting the problem in the quickest possible manner. Use the Expedite Repair \& Calibration form provided on the next page.

Once this information is prepared and sent with the instrument and RMA number to our service department, we will do our part in making sure that you receive the best possible customer service and turnaround time possible.

## Expedite Repair \& Calibration Form

Use this form to provide additional repair information and service instructions. The completion of this form and including it with your instrument will expedite the processing and repair process.


## Repair I nstructions:

$\square$ EvaluationRepair OnlyRepair \& CalibrationZ540 (Extra Charge)

## Detailed Symptoms:

Include information such as measurement range, instrument settings, type of components being tested, is the problem intermittent? When is the problem most frequent?, Has anything changed with the application since the last time the instrument was used?, etc.

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## Model 3550 Verification Procedure:

## EQUIPMENT NEEDED

| MODEL NUMBER | DESCRIPTION | REQUIREMENTS |
| :---: | :---: | :---: |
| Agilent 42033A | $100 \mathrm{~m} \Omega$ STANDARD RESISTOR | Four terminal BNC male connectors. . 863 in centers |
| Agilent 42034A | $1 \Omega$ STANDARD RESISTOR | Four terminal BNC male connectors. .863in centers |
| Agilent 42035A | $10 \Omega$ STANDARD RESISTOR | Four terminal BNC male connectors. . 863 in centers |
| Agilent 42036A | $100 \Omega$ STANDARD RESISTOR | Four terminal BNC male connectors. . 863 in centers |
| Agilent 42037A | $1 \mathrm{k} \Omega$ STANDARD RESISTOR | Four terminal BNC male connectors. . 863 in centers |
| Agilent 42038A | 10k STANDARD RESISTOR | Four terminal BNC male connectors. .863in centers |
| Agilent 42039A | 100k STANDARD RESISTOR | Four terminal BNC male connectors. .863in centers |
| Process Instruments 106 | 1M $\Omega$ STANDARD RESISTOR | Capable of measurement at 1 KHz |
| Process Instruments 107 | 10M $\Omega$ STANDARD RESISTOR | Capable of measurement at 1 KHz |
| Process Instruments 108 | 100M $\Omega$ STANDARD RESISTOR | Capable of measurement at 1 KHz |
| Agilent 16089B | Kelvin Clip Leads | Capable of measuring at 1 KHz , Through 100M ohms |
| Agilent 4284A | Precision LCR Meter | Frequency Range: 20Hz to 1 MHz Four Terminal Pair * |
| Agilent 4285A | Precision LCR Meter | Freq. Range: 75 kHz to 30 MHz Four Terminal Pair * |
| Agilent 42090A | Open Termination | Four terminal BNC male connectors. .863in centers |
| Agilent 42091A | Short Termination | Four terminal BNC male connectors. .863in centers |
| Agilent 16385A | . $01 \mu \mathrm{~F}$ Standard Capacitor | Four terminal BNC male connectors. .863in centers |
| Agilent 16386A | . $1 \mu \mathrm{~F}$ Standard Capacitor | Four terminal BNC male connectors. .863in centers |
| Agilent 16387A | $1 \mu \mathrm{~F}$ Standard Capacitor | Four terminal BNC male connectors. . 863 in centers |

[^0]
## Model 3550 Verification Procedure cont'd:

## PREPARATION FOR TEST:

## A. SET UP THE TEGAM 3550:

1. Cycle power on the 3550 and depress MANUAL to obtain manufacturer's default.
2. Set Display $A$ to $|Z|$.
3. Set Display B to $\theta$
4. Verify that the frequency is set to 1 KHz .
5. Verify that the level is set to 1 V .
6. Set the averaging to 100 as follows:

7. Allow the unit thirty minutes (minimum) to warm up.
8. Connect the Open Termination, Model 42090A, to the UNKNOWN BNC connectors on the 3550.
9. In the ZERO Section, press OPEN.
10. Wait for the open correction to complete.

Note: If a problem with the open correction was detected, a series of beeps will be heard.
11. Replace the Open Termination with the Short Termination, Model 42091A.
12. In the ZERO Section, press SHORT.
13. Wait for the short correction to complete.

Note: If a problem with the short correction was detected, a series of beeps will be heard.
14. Press the Manual button.

## B. SET UP THE AGI LENT 4284A:

1. Cycle power on the 4284A to obtain manufacturer's default.
2. Use the cursor keys and the soft-keys to set the function to Z-日 deg.
3. Verify that the frequency is set to 1 KHz .
4. Verify that the level is set to 1 V .
5. Press the MEAS SETUP key.
6. Set the Hi-Pw Mode to OFF.
7. Set TRIG to MAN.
8. Set the AVG to 32.
9. Allow the unit thirty minutes (minimum) to warm up.
10. Connect the Open Termination, Model 42090A, to the UNKNOWN BNC connectors on the 4284A.
11. Press the MEAS SETUP key.

## Model 3550 Verification Procedure cont'd:

SET UP THE AGI LENT 4284A cont'd:
12. Press the soft key labeled CORRECTION.
13. Set the CABLE to 0 m .
14. Use the cursor keys to select OPEN. Press the soft key labeled ON.
15. Press the soft key labeled MEAS OPEN.
16. Wait for the open correction to complete.

Note: When the measurement is complete, the unit will indicate "Open Measurement Complete."
17. Replace the Open Termination with the Short Termination, Model 42091A.
18. Use the cursor keys to select SHORT. Press the soft key labeled ON.
19. Press the soft key labeled MEAS SHORT.
20. Wait for the short correction to complete.

Note: When the measurement is complete, the unit will indicate "Short Measurement Complete."

## C. Measure Standards as follows:

1. Select the first Resistance Standard Model 42033A, connect to the UNKNOWN terminals of the 4284A.
2. Press TRIGGER, when the measurement changes, record the values for impedance and phase in the 4284A column.
3. Move the standard to the 3550, and press MAN/EXT. Wait for the reading to display and press MAN/EXT again. Record the values for impedance and phase in the 3550 column.
4. Repeat for each step in the 4284A table.
5. Calculate the difference in counts (3550) between the units.
6. Verify that each step is within tolerance.

Note: The last few steps require that the leads be changed to incorporate Kelvin Klip leads to measure the higher value resistance standards. Open and Short corrections must be completed using the Kelvin Klip leads.
7. Set up the 4285A using the same steps as for the 4284A with the exception of $\mathrm{Hi}-\mathrm{Pw}$ mode.
8. Measure and record each standard in the 4285 Table.
9. Calculate the difference in counts (3550) between the units.
10. Verify that each step is within tolerance.

Note: For instances where the 4284A or 4285A does not meet a $4: 1$ calibration ratio with the 3550, for verification purposes, the allowable number of counts may need to be adjusted to reflect the added error of the Agilent meters.

## Model $\mathbf{3 5 5 0}$ Verification Procedure cont'd:

TEGAM 3550 AND AGI LENT 4284A MEASUREMENTS

| STANDARD VALUE | $\begin{aligned} & \hline \text { FREQ } \\ & (\mathrm{Hz}) \\ & \hline \end{aligned}$ | LEVEL (V) | PARAMETER | $\begin{array}{\|c\|} \hline A \\ \hline 4284 A \end{array}$ | $\begin{gathered} \hline \mathbf{B} \\ \hline 3550 \end{gathered}$ | A-B |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  |  | ERROR | $\begin{aligned} & \text { TOL. } \\ & \text { (CTS) } \end{aligned}$ |
| $100 \mathrm{~m} \Omega$ | 1k | 1 | Z |  |  | $=(1000 \mathrm{~A}-\mathrm{B}) * 100$ | 1400 |
| $100 \mathrm{~m} \Omega$ | 1k | 1 | $\theta$ |  |  | $=(\mathrm{A}-\mathrm{B}) * 100$ | 101 |
| $1 \Omega$ | 1k | 1 | Z |  |  | $=(\mathrm{A}-\mathrm{B}) * 10 \mathrm{k}$ | 340 |
| $1 \Omega$ | 1k | 1 | $\theta$ |  |  | $=(\mathrm{A}-\mathrm{B}) * 100$ | 20 |
| $10 \Omega$ | 1k | 1 | Z |  |  | $=(\mathrm{A}-\mathrm{B}) * 1 \mathrm{k}$ | 94 |
| $10 \Omega$ | 1k | 1 | $\theta$ |  |  | $=(\mathrm{A}-\mathrm{B}) * 100$ | 10 |
| $100 \Omega$ | 1k | 1 | Z |  |  | $=(\mathrm{A}-\mathrm{B}) * 100$ | 22 |
| $100 \Omega$ | 1k | 1 | $\theta$ |  |  | $=(\mathrm{A}-\mathrm{B}) * 100$ | 10 |
| $1 \mathrm{k} \Omega$ | 1k | 1 | Z |  |  | $=(\mathrm{A}-\mathrm{B}) * 10 \mathrm{k}$ | 21 |
| $1 \mathrm{k} \Omega$ | 1k | 1 | $\theta$ |  |  | $=(\mathrm{A}-\mathrm{B}) * 100$ | 10 |
| $10 \mathrm{k} \Omega$ | 1k | 1 | Z |  |  | $=(\mathrm{A}-\mathrm{B}) * 1 \mathrm{k}$ | 21 |
| $10 \mathrm{k} \Omega$ | 1k | 1 | $\theta$ |  |  | $=(\mathrm{A}-\mathrm{B}) * 100$ | 10 |
| $100 \mathrm{k} \Omega$ | 1k | 1 | Z |  |  | $=(\mathrm{A}-\mathrm{B}) * 100$ | 21 |
| $100 \mathrm{k} \Omega$ | 1k | 1 | $\theta$ |  |  | $=(\mathrm{A}-\mathrm{B}) * 100$ | 10 |
| $100 \Omega$ | 42 | 1 | Z |  |  | $=(\mathrm{A}-\mathrm{B}) * 100$ | 27 |
| $100 \Omega$ | 42 | 1 | $\theta$ |  |  | $=(\mathrm{A}-\mathrm{B}) * 100$ | 10 |
| $1 \mathrm{k} \Omega$ | 42 | 1 | Z |  |  | $=(\mathrm{A}-\mathrm{B}) * 10 \mathrm{k}$ | 26 |
| $1 \mathrm{k} \Omega$ | 42 | 1 | $\theta$ |  |  | $=(\mathrm{A}-\mathrm{B}) * 100$ | 10 |
| $100 \Omega$ | 10k | 1 | Z |  |  | $=(\mathrm{A}-\mathrm{B}) * 100$ | 27 |
| $100 \Omega$ | 10k | 1 | $\theta$ |  |  | $=(\mathrm{A}-\mathrm{B}) * 100$ | 10 |
| $1 \mathrm{k} \Omega$ | 10k | 1 | Z |  |  | $=(\mathrm{A}-\mathrm{B}) * 10 \mathrm{k}$ | 27 |
| $1 \mathrm{k} \Omega$ | 10k | 1 | $\theta$ |  |  | $=(\mathrm{A}-\mathrm{B}) * 100$ | 10 |
| $100 \Omega$ | 100k | 1 | Z |  |  | $=(\mathrm{A}-\mathrm{B}) * 100$ | 85 |
| $100 \Omega$ | 100k | 1 | $\theta$ |  |  | $=(\mathrm{A}-\mathrm{B}) * 100$ | 40 |
| $1 \mathrm{k} \Omega$ | 100k | 1 | Z |  |  | $=(\mathrm{A}-\mathrm{B}) * 10 \mathrm{k}$ | 85 |
| $1 \mathrm{k} \Omega$ | 100k | 1 | $\theta$ |  |  | $=(\mathrm{A}-\mathrm{B}) * 100$ | 40 |
| $10 \Omega$ | 1M | 1 | Z |  |  | $=(\mathrm{A}-\mathrm{B}) * 1 \mathrm{k}$ | 204 |
| $10 \Omega$ | 1M | 1 | $\theta$ |  |  | $=(\mathrm{A}-\mathrm{B}) * 100$ | 50 |
| $100 \Omega$ | 1M | 1 | Z |  |  | $=(\mathrm{A}-\mathrm{B}) * 100$ | 115 |
| $100 \Omega$ | 1M | 1 | $\theta$ |  |  | $=(\mathrm{A}-\mathrm{B}) * 100$ | 40 |
| $1 \mathrm{k} \Omega$ | 1M | 1 | Z |  |  | $=(\mathrm{A}-\mathrm{B}) * 10 \mathrm{k}$ | 115 |
| $1 \mathrm{k} \Omega$ | 1M | 1 | $\theta$ |  |  | $=(\mathrm{A}-\mathrm{B}) * 100$ | 40 |
| . $01 \mu \mathrm{~F}$ | 1k | 1 | Z |  |  | $=(\mathrm{A}-\mathrm{B}) * 1 \mathrm{k}$ | 22 |
| . $01 \mu \mathrm{~F}$ | 1k | 1 | $\theta$ |  |  | $=(\mathrm{A}-\mathrm{B}) * 100$ | 20 |
| . $1 \mu \mathrm{~F}$ | 1k | 1 | Z |  |  | $=(\mathrm{A}-\mathrm{B}) * 10 \mathrm{k}$ | 22 |
| . $1 \mu \mathrm{~F}$ | 1k | 1 | $\theta$ |  |  | $=(\mathrm{A}-\mathrm{B}) * 100$ | 20 |
| $1 \mu \mathrm{~F}$ | 1k | 1 | Z |  |  | $=(\mathrm{A}-\mathrm{B}) * 100$ | 21 |
| $1 \mu \mathrm{~F}$ | 1k | 1 | $\theta$ |  |  | $=(\mathrm{A}-\mathrm{B}) * 100$ | 20 |

## Model 3550 Verification Procedure cont'd:

TEGAM 3550 AND AGI LENT 4284A MEASUREMENTS

|  |  |  |  | A | B | A-B |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| STANDARD VALUE | FREQ <br> (Hz) | LEVEL <br> (V) | PARAMETER | 4284A | 3550 | ERROR | $\begin{aligned} & \text { TOL. } \\ & \text { (CTS) } \end{aligned}$ |
| . $1 \mu \mathrm{~F}$ | 100k | 1 | $\theta$ |  |  | $=(\mathrm{A}-\mathrm{B}) * 100$ | 187 |
| . $01 \mu \mathrm{~F}$ | 10k | 1 | Z |  |  | $=(\mathrm{A}-\mathrm{B}) * 10 \mathrm{k}$ | 33 |
| . $01 \mu \mathrm{~F}$ | 10k | 1 | $\theta$ |  |  | $=(\mathrm{A}-\mathrm{B}) * 100$ | 28 |
| . $1 \mu \mathrm{~F}$ | 10k | 1 | Z |  |  | $=(\mathrm{A}-\mathrm{B}) * 100$ | 26 |
| . $1 \mu \mathrm{~F}$ | 10k | 1 | $\theta$ |  |  | $=(\mathrm{A}-\mathrm{B}) * 100$ | 20 |
| $1 \mu \mathrm{~F}$ | 10k | 1 | Z |  |  | $=(\mathrm{A}-\mathrm{B}) * 1 \mathrm{k}$ | 96 |
| $1 \mu \mathrm{~F}$ | 10k | 1 | $\theta$ |  |  | $=(\mathrm{A}-\mathrm{B}) * 100$ | 86 |
| . $01 \mu \mathrm{~F}$ | 100k | 1 | Z |  |  | $=(\mathrm{A}-\mathrm{B}) * 100$ | 83 |
| . $01 \mu \mathrm{~F}$ | 100k | 1 | $\theta$ |  |  | $=(\mathrm{A}-\mathrm{B}) * 100$ | 78 |
| . $1 \mu \mathrm{~F}$ | 100k | 1 | Z |  |  | $=(\mathrm{A}-\mathrm{B}) * 1 \mathrm{k}$ | 203 |
| $1 \mu \mathrm{~F}$ | 100k | 1 | Z |  |  | $=(\mathrm{A}-\mathrm{B}) * 10 \mathrm{k}$ | 425 |
| $1 \mu \mathrm{~F}$ | 100k | 1 | $\theta$ |  |  | $=(\mathrm{A}-\mathrm{B}) * 100$ | 341 |
| . $01 \mu \mathrm{~F}$ | 1M | 1 | Z |  |  | $=(\mathrm{A}-\mathrm{B}) * 1 \mathrm{k}$ | 203 |
| . $01 \mu \mathrm{~F}$ | 1M | 1 | $\theta$ |  |  | $=(\mathrm{A}-\mathrm{B}) * 100$ | 187 |
| . $1 \mu \mathrm{~F}$ | 1M | 1 | Z |  |  | $=(\mathrm{A}-\mathrm{B}) * 10 \mathrm{k}$ | 525 |
| . $1 \mu \mathrm{~F}$ | 1M | 1 | $\theta$ |  |  | $=(\mathrm{A}-\mathrm{B}) * 100$ | 531 |
| $1 \mathrm{M} \Omega$ | 1k | 1 | $\theta$ |  |  | $=(\mathrm{A}-\mathrm{B}) * 10 \mathrm{k}$ | 180 |
| $1 \mathrm{M} \Omega$ | 1k | 1 | Z |  |  | $=(\mathrm{A}-\mathrm{B}) * 100$ | 23 |
| $10 \mathrm{M} \Omega$ | 1k | 1 | $\theta$ |  |  | $=(\mathrm{A}-\mathrm{B}) * 1 \mathrm{k}$ | 235 |
| $10 \mathrm{M} \Omega$ | 1k | 1 | Z |  |  | $=(\mathrm{A}-\mathrm{B}) * 100$ | 44 |
| $100 \mathrm{M} \Omega$ | 1k | 1 | $\theta$ |  |  | $=(\mathrm{A}-\mathrm{B}) * 100$ | 1015 |
| $100 \mathrm{M} \Omega$ | 1k | 1 | Z |  |  | $=(\mathrm{A}-\mathrm{B}) * 100$ | 426 |

NOTE: Phase values are dependent on the phase of the device under test. If the Standard is beyond . 1 degree in phase for resistance values the tolerance must be recalculated. Exceptions are 1 M ohm and 10 M ohm, which should be within 2 degrees and 100 M ohm, which should be within 5 degrees.

## TEGAM 3550 AND AGI LENT 4284A MEASUREMENTS

|  |  |  | A | B | A-B |  |  |
| :--- | :--- | :--- | :--- | :---: | :---: | :---: | :---: |
| STANDARD <br> VALUE | FREQ <br> $\mathbf{( H z )}$ | LEVEL <br> $\mathbf{( V )}$ | PARAMETER | $\mathbf{4 2 8 4 A}$ | $\mathbf{3 5 5 0}$ | ERROR | TOL. <br> (CTS) |
| $10 \mathrm{k} \Omega$ | 1 M | 1 | Z |  |  | $=(\mathrm{A}-\mathrm{B}) * 1 \mathrm{k}$ | 205 |
| $10 \mathrm{k} \Omega$ | 1 M | 1 | $\theta$ |  | $=(\mathrm{A}-\mathrm{B}) * 100$ | 71 |  |
| $100 \mathrm{k} \Omega$ | 1 M | 1 | Z |  | $=(\mathrm{A}-\mathrm{B}) * 100$ | 605 |  |
| $100 \mathrm{k} \Omega$ | 1 M | 1 | $\theta$ |  |  | $=(\mathrm{A}-\mathrm{B}) * 100$ | 183 |
| $100 \Omega$ | 5 M | 1 | Z |  |  | $=(\mathrm{A}-\mathrm{B}) * 100$ | 355 |
| $100 \Omega$ | 5 M | 1 | $\theta$ |  |  | $=(\mathrm{A}-\mathrm{B}) * 100$ | 153 |
| $1 \mathrm{k} \Omega$ | 5 M | 1 | Z |  |  | $=(\mathrm{A}-\mathrm{B}) * 10 \mathrm{k}$ | 655 |
| $1 \mathrm{k} \Omega$ | 5 M | 1 | $\theta$ |  |  | $=(\mathrm{A}-\mathrm{B}) * 100$ | 353 |

NOTE: Phase values are dependent on the phase of the device under test. If the Standard is beyond 1 degree in phase for resistance values the tolerance must be recalculated.

## Model 3550 Calibration Adjustment Procedure:

Please contact TEGAM in order to obtain Calibration or Repair Service for your Instrument.

## SPECIFICATIONS PREPARATION FOR USE QUICK START INSTRUCTIONS OPERATING INSTRUCTIONS PROGRAMMING \& INTERFACING SERVICE INFORMATION APPENDIX

## Setting the Constant Voltage Mode

## To Enable the Constant Voltage Mode

1. Check and confirm that the [CV/CC] button is not illuminated.
2. Press the [V] button until Display C indicates voltage.
3. Press the [CV/CC] button.
4. Check and confirm that both the [CV/CC] and [V] button are illuminated.

The 3550 is now operating in Constant Voltage Mode.

## Calculating the Maximum Allowable Constant Voltage Setting

The figure bellow is an equivalent circuit of the Output Oscillator of the 3550. When connected to a DUT of a known impedance, $|\mathrm{Z}|$ and known phase angle, theta; the constant voltage maximum limit for a defined impedance and theta may be determined by using formula 1.
NOTE: The absolute maximum allowable constant voltage setting (regardless of DUT impedance) is limited by instrument capability. This maximum amount is 3.58 V .


$$
C V \leq\left|\frac{Z \cos \theta+j Z \sin \theta}{50+(Z \cos \theta+j Z \sin \theta)} \times V\right|
$$

Formula 1

Where:
CV $=$ Constant Voltage Setting Limit
$\mathrm{V}=$ Maximum Oscillator Voltage Setting

## Sample Calculation:

For a test frequency of $1 \mathrm{kHz},|\mathrm{Z}|=100 \Omega$, and theta $(\theta)=450$, the maximum constant voltage setting is calculated as follows:

$$
\begin{aligned}
& C V \leq\left|\frac{Z \cos \theta+j Z \sin \theta}{50+(Z \cos \theta+j Z \sin \theta)} \times 5\right| \\
& C V \leq\left|\frac{100 \cos 45^{\circ}+j 100 \sin 45^{\circ}}{50+\left(100 \cos 45^{\circ}+j 100 \sin 45^{\circ}\right)} \times 5\right| \\
& C V \leq|3.458+j 0.903| \\
& C V \leq 3.574 V
\end{aligned}
$$

## Setting the Constant Current Mode

## To Enable the Constant Current Mode

1. Check and confirm that the [CV/CC] button is not illuminated.
2. Push the [I] button until Display C indicates current.
3. Press the [CV/CC] button.
4. Check and confirm that both the [CV/CC] and [I] button are illuminated.

The 3550 is now operating in Constant Current Mode.

## Calculating the Maximum Allowable Constant Current Setting

The figure bellow is an equivalent circuit of the Output Oscillator of the 3550. When connected to a DUT of a known impedance, $|Z|$ and known phase angle, theta; the constant current maximum limit may be determined by using formula 2.

NOTE: The absolute maximum allowable constant current setting (regardless of DUT impedance) is limited by the instruments sourcing capability. This maximum amount is 35.74 mA .


$$
\mathrm{CC} \leq\left|\frac{\mathrm{V}}{50+\left(\begin{array}{c}
\mathrm{Z} \cos \theta+\mathrm{j} \sin \theta) \\
\text { Formula } 2
\end{array}\right.}\right|
$$

Where:
$\mathrm{CC}=$ Constant Current Setting Limit
$\mathrm{V}=$ Maximum Oscillator Voltage Setting

## Sample Calculation:

For a test frequency of $1 \mathrm{kHz},|\mathrm{Z}|=100 \Omega$, and theta $(\theta)=450$, the maximum constant current setting is calculated as follows:

$$
\begin{aligned}
& C C=\left|\frac{5}{50+(Z \cos \theta+\mathrm{j} Z \sin \theta)}\right| \\
& C C \leq\left|\frac{5}{50+\left(100 \cos 45^{\circ}+\mathrm{j} 100 \sin 45^{\circ}\right)}\right| \\
& C C \leq|0.03083-\mathrm{j} 0.01806| \\
& C C \leq 0.03573 \mathrm{~A}
\end{aligned}
$$

Table A.1: Basic Accuracy Table

| Range | Impedance | Measurement Frequency |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | $42 \mathrm{~Hz} \sim 99.9 \mathrm{~Hz}$ | $100 \mathrm{~Hz} \sim 1 \mathrm{kHz}$ | $1.01 \mathrm{kHz} \sim 10.0 \mathrm{kHz}$ | $10.1 \mathrm{kHz} \sim 30.0 \mathrm{kHz}$ | $30.1 \mathrm{kHz} \sim 100 \mathrm{kHz}$ | $101 \mathrm{kHz} \sim 1.00 \mathrm{MHz}$ | $1.01 \mathrm{MHz} \sim 5.00 \mathrm{MHz}$ |
| $100 \mathrm{~m} \Omega$ | $\begin{gathered} 10.00 \mathrm{~m} \Omega \sim \\ 199.99 \mathrm{~m} \Omega \end{gathered}$ | $(5+4 \beta) \%+500$ | $(5+4 \beta) \%+500$ | $(5+4 \beta) \%+500$ | $(5+4 \beta) \%+500$ | $(10+4 \beta) \%+500$ |  |  |
|  |  | $(5+2 \beta) \%+100$ | $(5+2 \beta) \%+100$ | $(5+2 \beta) \%+100$ | $(5+2 \beta) \%+250$ | $(10+4 \beta) \%+500$ |  |  |
| $1 \Omega$ | $\begin{gathered} 0.1800 \Omega \sim \\ 1.9999 \Omega \end{gathered}$ | $(2+0.4 \beta) \%+200$ | $(1+0.4 \beta) \%+200$ | $(1.5+0.4 \beta) \%+200$ | $(1.5+0.4 \beta) \%+200$ | $(2+0.4 \beta) \%+200$ | $(3+0.4 \beta) \%+200$ |  |
|  |  | $(2+0.3 \beta) \%+20$ | $(1+0.2 \beta) \%+20$ | $(1.5+0.2 \beta) \%+20$ | $(1.5+0.2 \beta) \%+60$ | $(2+0.2 \beta) \%+150$ | $(3+0.2 \beta) \%+250$ |  |
| $10 \Omega$ | $\begin{gathered} 1.800 \Omega \sim \\ 19.999 \Omega \end{gathered}$ | $(1+0.4 \beta) \%+200$ | $(0.8+0.04 \beta) \%+10$ | $(0.8+0.04 \beta) \%+10$ | $(0.8+0.04 \beta) \%+10$ | $(1.5+0.04 \beta) \%+50$ | $(1.5+0.04 \beta) \%+50$ | $(5+0.4 \beta) \%+200$ |
|  |  | $(1+0.2 \beta) \%+20$ | $(0.8+0.03 \beta) \%+10$ | $(0.8+0.03 \beta) \%+10$ | (0.8+0.03ß) \% +10 | $(1.5+0.03 \beta) \%+50$ | $(1.5+0.03 \beta) \%+50$ | $(5+0.3 \beta) \%+200$ |
| $100 \Omega$ | $\begin{gathered} 18.00 \Omega \sim \\ 199.99 \Omega \end{gathered}$ | $(0.15+0.02 \beta) \%+10$ | $(0.1+0.02 \beta) \%+10$ | $(0.15+0.02 \beta) \%+10$ | $(0.15+0.02 \beta) \%+10$ | $(0.4+0.05 \beta) \%+40$ | $(0.6+0.05 \beta) \%+50$ | $(3+0.05 \beta) \%+50$ |
|  |  | $(0.15+0.01 \beta) \%+10$ | $(0.1+0.01 \beta) \%+10$ | $(0.1+0.01 \beta) \%+10$ | $(0.1+0.01 \beta) \%+10$ | $(0.4+0.03 \beta) \%+40$ | $(0.6+0.03 \beta) \%+40$ | $(3+0.03 \beta) \%+150$ |
| $1 \mathrm{k} \Omega$ | $\begin{gathered} 0.1800 \mathrm{k} \Omega \sim \\ 1.9999 \mathrm{k} \Omega \end{gathered}$ | $(0.15+0.01 a) \%+10$ | (0.1+0.01a) \% +10 | $(0.15+0.05 a) \%+10$ | $(0.15+0.05 a) \%+10$ | (0.4+0.05a) \% +40 | $(0.6+0.05 \beta) \%+50$ | $(3+0.05 \beta) \%+350$ |
|  |  | (0.1+0.005a) \% +10 | $(0.1+0.005 a) \%+10$ | $(0.1+0.03 a) \%+10$ | (0.1+0.03a) \% +10 | (0.4+0.03a) \% +40 | $(0.6+0.03 \beta) \%+40$ | $(3+0.05 \beta) \%+350$ |
| 10k $\Omega$ | $\begin{gathered} 1.800 \mathrm{k} \Omega \sim \\ 19.999 \mathrm{k} \Omega \end{gathered}$ | $(0.15+0.01 a) \%+10$ | (0.1+0.01a) \% +10 | $(0.15+0.05 a) \%+10$ | $(0.15+0.05 a) \%+10$ | $(0.4+0.05 a) \%+40$ | $(1+0.05 a) \%+100$ | $(3+0.05 a) \%+400$ |
|  |  | (0.1+0.005a) \% +10 | $(0.1+0.005 a) \%+10$ | $(0.1+0.03 a) \%+10$ | (0.1+0.03a) \% +10 | (0.4+0.03a) \% +40 | $(1+0.03 a) \%+70$ | $(3+0.05 a) \%+300$ |
| $100 \mathrm{k} \Omega$ | $\begin{gathered} 18.00 \mathrm{k} \Omega \sim \\ 199.99 \mathrm{k} \Omega \end{gathered}$ | $(0.15+0.01 a) \%+10$ | $(0.1+0.01 a) \%+10$ | $(0.15+0.05 a) \%+10$ | (0.8+0.05a) \% +50 | $(1+0.05 a) \%+50$ | $(3+0.05 a) \%+300$ | $(20+0.5 a) \%+700$ |
|  |  | $(0.1+0.005 a) \%+10$ | $(0.1+0.005 a) \%+10$ | $(0.1+0.03 a) \%+10$ | $(0.8+0.05 a) \%+180$ | $(2+0.05 a) \%+180$ | $(3+0.05 a) \%+180$ | $(20+0.5 a) \%+500$ |
| $1 \mathrm{M} \Omega$ | $\begin{gathered} 0.1800 \mathrm{M} \Omega \sim \\ 1.9999 \mathrm{M} \Omega \end{gathered}$ | $(1.5+0.1 a) \%+20$ | $(1.5+0.1 a) \%+20$ | $(1.5+0.1 a) \%+20$ | $(2+0.1 a) \%+70$ | $(2+0.1 a) \%+70$ | $(20+0.1 a) \%+700$ |  |
|  |  | $(1.5+0.1 a) \%+20$ | (1.5+0.1a) \% +20 | $(1.5+0.1 a) \%+20$ | $(2+0.1 a) \%+200$ | $(2+0.1 a) \%+250$ | $(20+0.1 a) \%+200$ |  |
| $10 \mathrm{M} \Omega$ | $\begin{gathered} 1.800 \mathrm{M} \Omega \sim \\ 19.999 \mathrm{M} \Omega \end{gathered}$ | $(2+0.15 a) \%+20$ | $(2+0.15 a) \%+20$ | $(2+0.15 a) \%+20$ | $(2+0.15 a) \%+70$ | $(20+0.15 a) \%+500$ |  |  |
|  |  | $(2+0.1 a) \%+40$ | $(2+0.1 a) \%+40$ | $(2+0.1 a) \%+40$ | $(2+0.1 a) \%+200$ | $(20+0.1 a) \%+700$ |  |  |
| $10 \mathrm{M} \Omega$ | $\begin{gathered} 18.00 \mathrm{M} \Omega \sim \\ 199.99 \mathrm{M} \Omega \end{gathered}$ | $(5+0.15 a) \%+500$ | $(5+0.15 a) \%+500$ | $(5+0.15 a) \%+500$ | $(5+0.15 a) \%+500$ | (50+0.15a) \% +500 |  |  |
|  |  | $(5+0.1 \alpha) \%+400$ | $(5+0.1 \alpha) \%+400$ | $(5+0.1 \alpha) \%+400$ | $(5+0.1 \alpha) \%+400$ | $(50+0.1 \alpha) \%+700$ |  |  |

Upper Specification: Accuracy of $|Z| \pm$ (Nominal\% + Counts)
Lower Specification: Accuracy of $\theta \pm$ (Nominal\% + Counts)
The count coefficient should be calculated as follows:

Table A.2: Basic Accuracy Table [.01V to .04V]

| Range | Impedance | Measure Frequency |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | $42 \mathrm{~Hz} \sim 99.9 \mathrm{~Hz}$ | $100 \mathrm{~Hz} \sim 1 \mathrm{kHz}$ | $1.01 \mathrm{kHz} \sim 10.0 \mathrm{kHz}$ | $10.1 \mathrm{kHz} \sim 30.0 \mathrm{kHz}$ | $30.1 \mathrm{kHz} \sim 100 \mathrm{kHz}$ | $101 \mathrm{kHz} \sim 1.00 \mathrm{MHz}$ | $1.01 \mathrm{MHz} \sim 5.00 \mathrm{MHz}$ |
| $100 \mathrm{~m} \Omega$ | $\begin{array}{\|c\|} 10.00 \mathrm{~m} \Omega \sim \\ 199.99 \mathrm{~m} \Omega \end{array}$ |  |  |  |  |  |  |  |
| $1 \Omega$ | $\begin{array}{\|c\|} \hline 0.1800 \Omega \sim \\ 1.9999 \Omega \end{array}$ |  |  |  |  |  |  |  |
| $10 \Omega$ | $\begin{array}{\|c\|} 1.800 \Omega \sim \\ 19.999 \Omega \end{array}$ | $(6+2.4 \beta) \%+1200$ | $(4.8+0.24 \beta) \%+60$ | $(4.8+0.24 \beta) \%+60$ | $(4.8+0.24 \beta) \%+60$ | $(9+0.24 \beta) \%+300$ |  |  |
|  |  | $(6+1.2 \beta) \%+120$ | $(4.8+0.18 \beta) \%+60$ | $(4.8+0.18 \beta) \%+60$ | $(4.8+0.18 \beta) \%+250$ | $(9+0.18 \beta) \%+300$ |  |  |
| $100 \Omega$ | $\left.\begin{gathered} 18.00 \Omega \sim \\ 199.99 \Omega \end{gathered} \right\rvert\,$ | $(0.9+0.12 \beta) \%+60$ | $(0.6+0.12 \beta) \%+60$ | $(0.9+0.12 \beta) \%+60$ | $(0.9+0.12 \beta) \%+60$ | $(2.4+0.3 \beta) \%+240$ | $(3.6+0.3 \beta) \%+300$ |  |
|  |  | $(0.9+0.06 \beta) \%+60$ | $(0.6+0.06 \beta) \%+60$ | $(0.6+0.06 \beta) \%+60$ | $(0.6+0.06 \beta) \%+120$ | $(2.4+0.18 \beta) \%+240$ | $(3.6+0.18 \beta) \%+240$ |  |
| $1 \mathrm{k} \Omega$ | $\left\|\begin{array}{r} 0.1800 \mathrm{k} \Omega \sim \\ 1.9999 \mathrm{k} \Omega \end{array}\right\|$ | $(0.9+0.06 a) \%+60$ | $(0.6+0.06 a) \%+60$ | $(0.9+0.3 a) \%+60$ | $(0.9+0.3 a) \%+60$ | $(2.4+0.3 a) \%+240$ | $(3.6+0.3 \beta) \%+300$ |  |
|  |  | $(0.6+0.03 a) \%+60$ | $(0.6+0.03 a) \%+60$ | $(0.6+0.18 a) \%+60$ | $(0.6+0.18 a) \%+120$ | (2.4+0.18a) \% +240 | $(3.6+0.18 \beta) \%+240$ |  |
| $10 \mathrm{k} \Omega$ | $\begin{gathered} 1.800 \mathrm{k} \Omega \sim \\ 19.999 \mathrm{k} \Omega \end{gathered}$ | $(0.9+0.06 a) \%+60$ | $(0.6+0.06 a) \%+60$ | $(0.9+0.3 a) \%+60$ | $(0.9+0.3 a) \%+60$ | $(2.4+0.3 a) \%+240$ | $(6+0.3 a) \%+600$ |  |
|  |  | $(0.6+0.03 a) \%+60$ | $(0.6+0.03 a) \%+60$ | $(0.6+0.18 a) \%+60$ | $(0.6+0.18 a) \%+120$ | $(2.4+0.18 a) \%+240$ | $(6+0.18 a) \%+420$ |  |
| 100k $\Omega$ | $\left\lvert\, \begin{gathered} 18.00 \mathrm{k} \Omega \sim \\ 199.99 \mathrm{k} \Omega \end{gathered}\right.$ | $(0.9+0.06 a) \%+60$ | $(0.6+0.06 a) \%+60$ | $(0.9+0.3 a) \%+60$ | $(4.8+0.3 a) \%+300$ | $(6+0.3 a) \%+300$ |  |  |
|  |  | (0.6+0.03a) \% +60 | $(0.6+0.03 a) \%+60$ | $(0.6+0.18 a) \%+60$ | $(4.8+0.3 a) \%+1080$ | $(12+0.3 a) \%+1080$ |  |  |
| $1 \mathrm{M} \Omega$ | $\begin{array}{\|c\|} 0.1800 \mathrm{M} \Omega \sim \\ 1.9999 \mathrm{M} \Omega \end{array}$ |  |  |  |  |  |  |  |
| $10 \mathrm{M} \Omega$ | $\begin{array}{\|c} 1.800 \mathrm{M} \Omega \sim \\ 19.999 \mathrm{M} \Omega \end{array}$ |  |  |  |  |  |  |  |
| $100 \mathrm{M} \Omega$ | $\begin{array}{\|c\|} \hline 18.00 \mathrm{M} \Omega \sim \\ 199.99 \mathrm{M} \Omega \end{array}$ |  |  |  |  |  |  |  |

Upper Specification: Accuracy of $|Z| \pm$ (Nominal\% + Counts)
Lower Specification: Accuracy of $\theta \pm$ (Nominal\% + Counts)
The count coefficient should be calculated as follows:

The Set Measurement Voltage

$$
\alpha=\frac{Z x}{10,000} \quad \beta=\frac{10,000}{Z x} \quad Z x=\text { the number of counts for }|Z|
$$

Table A.3: Basic Accuracy Table [.05V to .10V]

| Range | Impedance | Measure Frequency |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | $42 \mathrm{~Hz} \sim 99.9 \mathrm{~Hz}$ | $100 \mathrm{~Hz} \sim 1 \mathrm{kHz}$ | $1.01 \mathrm{kHz} \sim 10.0 \mathrm{kHz}$ | $10.1 \mathrm{kHz} \sim 30.0 \mathrm{kHz}$ | 30.1 kHz 100 kHz | $101 \mathrm{kHz} \sim 1.00 \mathrm{MHz}$ | $1.01 \mathrm{MHz} \sim 5.00 \mathrm{MHz}$ |
| $100 \mathrm{~m} \Omega$ | $\begin{gathered} 10.00 \mathrm{~m} \Omega \sim \\ 199.99 \mathrm{~m} \Omega \end{gathered}$ |  |  |  |  |  |  |  |
| $1 \Omega$ | $\begin{gathered} 0.1800 \Omega \sim \\ 1.9999 \Omega \end{gathered}$ |  |  |  |  |  |  |  |
| $10 \Omega$ | $\begin{array}{\|c} 1.800 \Omega \sim \\ 19.999 \Omega \end{array}$ | $(4+1.6 \beta) \%+800$ | $(3.2+0.16 \beta) \%+40$ | $(3.2+0.16 \beta) \%+40$ | $(3.2+0.16 \beta) \%+40$ | $(6+0.16 \beta) \%+200$ | $(6+0.16 \beta) \%+200$ | $(20+1.6 \beta) \%+800$ |
|  |  | $(4+0.8 \beta) \%+80$ | $(3.2+0.12 \beta) \%+40$ | $(3.2+0.12 \beta) \%+40$ | $(3.2+0.12 \beta) \%+40$ | $(6+0.12 \beta) \%+200$ | $(6+0.12 \beta) \%+200$ | $(20+1.2 \beta) \%+800$ |
| $100 \Omega$ | $\begin{array}{\|c\|} \hline 18.00 \Omega \sim \\ 199.99 \Omega \end{array}$ | $(0.6+0.08 \beta) \%+40$ | $(0.4+0.08 \beta) \%+40$ | $(0.6+0.08 \beta) \%+40$ | $(0.6+0.08 \beta) \%+40$ | $(1.6+0.2 \beta) \%+160$ | $(2.4+0.2 \beta) \%+200$ | $(12+0.2 \beta) \%+200$ |
|  |  | $(0.6+0.04 \beta) \%+40$ | (0.4+0.04ß) \% +40 | $(0.4+0.04 \beta) \%+40$ | $(0.4+0.04 \beta) \%+40$ | $(1.6+0.12 \beta) \%+160$ | $(2.4+0.12 \beta) \%+160$ | $(12+0.12 \beta) \%+600$ |
| $1 \mathrm{k} \Omega$ | $0.1800 \mathrm{k} \Omega \sim$ $1.9999 \mathrm{k} \Omega$ | $(0.6+0.04 a) \%+40$ | (0.4+0.04a) \% +40 | $(0.6+0.2 a) \%+40$ | $(0.6+0.2 a) \%+40$ | $(1.6+0.2 a) \%+160$ | $(2.4+0.2 a) \%+200$ | $(12+0.2 \beta) \%+1400$ |
|  |  | (0.4+0.02a) \% +40 | (0.4+0.02a) \% + 40 | (0.4+0.12a) \% + 40 | (0.4+0.12a) \% +40 | $(1.6+0.12 a) \%+160$ | (2.4+0.12a) \% +160 | $(12+0.2 \beta) \%+1400$ |
| 10k $\Omega$ | $\begin{gathered} 1.800 \mathrm{k} \Omega \sim \\ 19.999 \mathrm{k} \Omega \end{gathered}$ | $(0.6+0.04 a) \%+40$ | (0.4+0.04a) \% +40 | $(0.6+0.2 a) \%+40$ | $(0.6+0.2 a) \%+40$ |  | $(4+0.2 a) \%+400$ | $(12+0.2 a) \%+1600$ |
|  |  | (0.4+0.02a) \% +40 | (0.4+0.02a) \% +40 | (0.4+0.12a) \% +40 | (0.4+0.12a) \% +40 | $(1.6+0.12 a) \%+160$ | $(4+0.12 \mathrm{a}) \%+280$ | $(12+0.2 a) \%+1200$ |
| 100k $\Omega$ | $\begin{gathered} 18.00 \mathrm{k} \Omega \sim \\ 199.99 \mathrm{k} \Omega \end{gathered}$ | $(0.6+0.04 a) \%+40$ | $(0.4+0.04 a) \%+40$ | $(0.6+0.2 a) \%+40$ | $(3.2+0.2 a) \%+200$ | $(4+0.2 a) \%+200$ | $(12+0.2 \mathrm{a}) \%+1200$ |  |
|  |  | (0.4+0.02a) \% +40 | (0.4+0.02a) \% +40 | (0.4+0.12a) \% +40 | $(3.2+0.2 a) \%+720$ | (8+0.2a) \% +720 | $(12+0.2 a) \%+720$ |  |
| $1 \mathrm{M} \Omega$ | $\begin{gathered} 0.1800 \mathrm{M} \Omega \sim \\ 1.9999 \mathrm{M} \Omega \end{gathered}$ |  |  |  |  |  |  |  |
| $10 \mathrm{M} \Omega$ | $\begin{gathered} 1.800 \mathrm{M} \Omega \sim \\ 19.999 \mathrm{M} \Omega \end{gathered}$ |  |  |  |  |  |  |  |
| 100M $\Omega$ | $\begin{gathered} 18.00 \mathrm{M} \Omega \sim \\ 199.99 \mathrm{M} \Omega \end{gathered}$ |  |  |  |  |  |  |  |

Upper Specification: Accuracy of $|Z| \pm$ (Nominal\% + Counts) Lower Specification: Accuracy of $\theta \pm$ (Nominal\% + Counts) The count coefficient should be calculated as follows:


The Set Measurement Voltage

$$
\alpha=\frac{Z x}{10,000} \quad \beta=\frac{10,000}{Z x} \quad Z x=\text { the number of counts for }|Z|
$$

Table A.4: Basic Accuracy Table [.11V to .20V]

| Range | Impedance | Measure Frequency |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | $42 \mathrm{~Hz} \sim 99.9 \mathrm{~Hz}$ | $100 \mathrm{~Hz} \sim 1 \mathrm{kHz}$ | $1.01 \mathrm{kHz} \sim 10.0 \mathrm{kHz}$ | $10.1 \mathrm{kHz} \sim 30.0 \mathrm{kHz}$ | $30.1 \mathrm{kHz} \sim 100 \mathrm{kHz}$ | $101 \mathrm{kHz} \sim 1.00 \mathrm{MHz}$ | $1.01 \mathrm{MHz} \sim 5.00 \mathrm{MHz}$ |
| $100 \mathrm{~m} \Omega$ | $\begin{gathered} 10.00 \mathrm{~m} \Omega \sim \\ 199.99 \mathrm{~m} \Omega \end{gathered}$ |  |  |  |  |  |  |  |
| $1 \Omega$ | $\begin{gathered} 0.1800 \Omega \sim \\ 1.9999 \Omega \end{gathered}$ | $(4+0.8 \beta) \%+400$ | $(2+0.8 \beta) \%+400$ | $(3+0.8 \beta) \%+400$ | $(3+0.8 \beta) \%+400$ | $(4+0.8 \beta) \%+400$ | $(6+0.8 \beta) \%+400$ |  |
|  |  | $(4+0.6 \beta) \%+80$ | $(2+0.4 \beta) \%+80$ | $(3+0.4 \beta) \%+80$ | $(3+0.4 \beta) \%+120$ | $(4+0.4 \beta) \%+300$ | $(6+0.4 \beta) \%+500$ |  |
| $10 \Omega$ | $\begin{gathered} 1.800 \Omega \sim \\ 19.999 \Omega \end{gathered}$ | $(2+0.8 \beta) \%+400$ | $(1.6+0.08 \beta) \%+20$ | $(1.6+0.08 \beta) \%+20$ | $(1.6+0.08 \beta) \%+20$ | $(3+0.08 \beta) \%+100$ | $(3+0.08 \beta) \%+100$ | $(10+0.8 \beta) \%+400$ |
|  |  | $(2+0.4 \beta) \%+40$ | $(1.6+0.06 \beta) \%+20$ | (1.6+0.06ß) \% +20 | $(1.6+0.06 \beta) \%+20$ | $(3+0.06 \beta) \%+100$ | $(3+0.06 \beta) \%+100$ | $(10+0.6 \beta) \%+400$ |
| $100 \Omega$ | $\begin{gathered} 18.00 \Omega \sim \\ 199.99 \Omega \end{gathered}$ | $(0.3+0.04 \beta) \%+20$ | $(0.2+0.04 \beta) \%+20$ | $(0.3+0.04 \beta) \%+20$ | $(0.3+0.04 \beta) \%+20$ | $(0.8+0.1 \beta) \%+80$ | $(1.2+0.1 \beta) \%+100$ | $(6+0.1 \beta) \%+100$ |
|  |  | $(0.3+0.02 \beta) \%+20$ | $(0.2+0.02 \beta) \%+20$ | $(0.2+0.02 \beta) \%+20$ | $(0.2+0.02 \beta) \%+20$ | $(0.8+0.06 \beta) \%+80$ | $(1.2+0.06 \beta) \%+80$ | $(6+0.06 \beta) \%+300$ |
| $1 \mathrm{k} \Omega$ | $\begin{gathered} 0.1800 \mathrm{k} \Omega \sim \\ 1.9999 \mathrm{k} \Omega \end{gathered}$ | $(0.3+0.02 a) \%+20$ | $(0.2+0.02 a) \%+20$ | $(0.3+0.1 a) \%+20$ | $(0.3+0.1 a) \%+20$ | $(0.8+0.1 a) \%+80$ | $(1.2+0.1 \beta) \%+100$ | $(6+0.1 \beta) \%+700$ |
|  |  | $(0.2+0.01 a) \%+20$ | (0.2+0.01a) \% +20 | (0.2+0.06a) \% +20 | $(0.2+0.06 a) \%+20$ | (0.8+0.06a) \% +80 | $(1.2+0.06 \beta) \%+80$ | $(6+0.1 \beta) \%+700$ |
| 10k $\Omega$ | $\begin{gathered} 1.800 \mathrm{k} \Omega \sim \\ 19.999 \mathrm{k} \Omega \end{gathered}$ | $(0.3+0.02 a) \%+20$ | $(0.2+0.02 a) \%+20$ | $(0.3+0.1 a) \%+20$ | $(0.3+0.1 a) \%+20$ | $(0.8+0.1 a) \%+80$ | $(2+0.1 a) \%+200$ | ( $6+0.1 \mathrm{a}) \%+800$ |
|  |  | $(0.2+0.01 a) \%+20$ | (0.2+0.01a) \% +20 | (0.2+0.06a) \% +20 | $(0.2+0.06 a) \%+20$ | (0.8+0.06a) \% +80 | $(2+0.06 a) \%+140$ | $(6+0.1 a) \%+600$ |
| 100k $\Omega$ | $\begin{gathered} 18.00 \mathrm{k} \Omega \sim \\ 199.99 \mathrm{k} \Omega \end{gathered}$ | $(0.3+0.02 a) \%+20$ | $(0.2+0.02 a) \%+20$ | $(0.3+0.1 a) \%+20$ | $(1.6+0.1 a) \%+100$ | $(2+0.1 a) \%+100$ | $(6+0.1 a) \%+600$ |  |
|  |  | $(0.2+0.01 a) \%+20$ | (0.2+0.01a) $\%+20$ | (0.2+0.06a) \% +20 | (1.6+0.1a) \% +360 | $(4+0.1 a) \%+360$ | (6+0.1a) \% +360 |  |
| $1 \mathrm{M} \Omega$ | $\begin{gathered} 0.1800 \mathrm{M} \Omega \sim \\ 1.9999 \mathrm{M} \Omega \end{gathered}$ | $(3+0.2 a) \%+40$ | $(3+0.2 a) \%+40$ | $(3+0.2 a) \%+40$ | $(4+0.2 a) \%+140$ | $(4+0.2 a) \%+140$ |  |  |
|  |  | $(3+0.2 a) \%+40$ | $(3+0.2 a) \%+40$ | $(3+0.2 a) \%+40$ | $(4+0.2 a) \%+400$ | $(4+0.2 a) \%+500$ |  |  |
| 10M $\Omega$ | $\begin{gathered} 1.800 \mathrm{M} \Omega \sim \\ 19.999 \mathrm{M} \Omega \end{gathered}$ | $(4+0.3 a) \%+40$ | $(4+0.3 a) \%+40$ | $(4+0.3 a) \%+40$ |  |  |  |  |
|  |  | ( $4+0.2 \mathrm{a}$ ) \% +80 | $(4+0.2 a) \%+80$ | $(4+0.2 a) \%+80$ |  |  |  |  |
| $100 \mathrm{M} \Omega$ | $\begin{gathered} 18.00 \mathrm{M} \Omega \sim \\ 199.99 \mathrm{M} \Omega \end{gathered}$ | $(10+0.3 a) \%+1000$ | $(10+0.3 a) \%+1000$ | $(10+0.3 a) \%+1000$ |  |  |  |  |
|  |  | $(10+0.2 a) \%+800$ | $(10+0.2 a) \%+800$ | $(10+0.2 a) \%+800$ |  |  |  |  |

Upper Specification: Accuracy of $|Z| \pm$ (Nominal\% + Counts)
Lower Specification: Accuracy of $\theta \pm$ (Nominal\% + Counts)
The count coefficient should be calculated as follows:
$\left[\begin{array}{c}\text { Accuracy Limit from } \\ \text { Measurement Limit Chart }\end{array}\right] \times\left[\begin{array}{c}\text { Maximum Voltage } \\ \text { Limit for Chart }\end{array}\right]$
The Set Measurement Voltage

$$
\alpha=\frac{Z x}{10,000} \quad \beta=\frac{10,000}{Z x} \quad Z x=\text { the number of counts for }|Z|
$$

Table A.5: Basic Accuracy Table [.21V to .45V]

| Range | Impedance | Measure Frequency |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | $42 \mathrm{~Hz} \sim 99.9 \mathrm{~Hz}$ | $100 \mathrm{~Hz} \sim 1 \mathrm{kHz}$ | $1.01 \mathrm{kHz} \sim 10.0 \mathrm{kHz}$ | $10.1 \mathrm{kHz} \sim 30.0 \mathrm{kHz}$ | $30.1 \mathrm{kHz} \sim 100 \mathrm{kHz}$ | $101 \mathrm{kHz} \sim 1.00 \mathrm{MHz}$ | $1.01 \mathrm{MHz} \sim 5.00 \mathrm{MHz}$ |
| $100 \mathrm{~m} \Omega$ | $\begin{gathered} 10.00 \mathrm{~m} \Omega \sim \\ 199.99 \mathrm{~m} \Omega \end{gathered}$ |  |  |  |  |  |  |  |
| $1 \Omega$ | $\begin{gathered} 0.1800 \Omega \sim \\ 1.9999 \Omega \end{gathered}$ | $(3+0.6 \beta) \%+300$ | $(1.5+0.6 \beta) \%+300$ | $(2.25+0.6 \beta) \%+300$ | $(2.25+0.6 \beta) \%+300$ | $(3+0.6 \beta) \%+300$ | $(4.5+0.6 \beta) \%+300$ |  |
|  |  | $(3+0.45 \beta) \%+30$ | $(1.5+0.3 \beta) \%+30$ | $(2.25+0.3 \beta) \%+30$ | $(2.25+0.3 \beta) \%+90$ | $(3+0.3 \beta) \%+225$ | $(4.5+0.3 \beta) \%+375$ |  |
| $10 \Omega$ | $\begin{array}{\|c\|} \hline 1.800 \Omega \sim \\ 19.999 \Omega \end{array}$ | $(1.5+0.6 \beta) \%+300$ | $(1.2+0.06 \beta) \%+15$ | $(1.2+0.06 \beta) \%+15$ | $(1.2+0.06 \beta) \%+15$ | $(2.25+0.06 \beta) \%+75$ | $(2.25+0.06 \beta) \%+75$ | $(7.5+0.6 \beta) \%+300$ |
|  |  | $(1.5+0.3 \beta) \%+30$ | $(1.2+0.045 \beta) \%+15$ | $(1.2+0.045 \beta) \%+15$ | $(1.2+0.045 \beta) \%+15$ | $(2.25+0.045 \beta) \%+75$ | $2.25+0.045 \beta) \%+75$ | $(7.5+0.45 \beta) \%+300$ |
| $100 \Omega$ | $\begin{array}{\|c\|} 18.00 \Omega \sim \\ 199.99 \Omega \end{array}$ | $(0.225+0.03 \beta) \%+15$ | $(0.15+0.03 \beta) \%+15$ | $(0.225+0.03 \beta) \%+15$ | $(0.225+0.03 \beta) \%+15$ | $(0.6+0.075 \beta) \%+60$ | $(0.9+0.075 \beta) \%+75$ | $(4.5+0.075 \beta) \%+75$ |
|  |  | $(0.225+0.015 \beta) \%+15$ | $(0.15+0.015 \beta) \%+15$ | $(0.15+0.015 \beta) \%+15$ | $(0.15+0.015 \beta) \%+15$ | $(0.6+0.045 \beta) \%+60$ | $(0.9+0.045 \beta) \%+60$ | $(4.5+0.045 \beta) \%+225$ |
| $1 \mathrm{k} \Omega$ | $\begin{array}{r} 0.1800 \mathrm{k} \Omega \sim \\ 1.9999 \mathrm{k} \Omega \end{array}$ | $(0.225+0.015 a) \%+15$ | $(0.15+0.015 a) \%+15$ | $(0.225+0.075 a) \%+15$ | $(0.225+0.075 a) \%+15$ | $(0.6+0.075 a) \%+60$ | $(0.9+0.075 \beta) \%+75$ | $(4.5+0.075 \beta) \%+525$ |
|  |  | $(0.15+0.0075 a) \%+15$ | $(0.15+0.0075 a) \%+15$ | $(0.15+0.045 a) \%+15$ | $(0.15+0.045 a) \%+15$ | $(0.6+0.045 a) \%+60$ | $(0.9+0.045 \beta) \%+60$ | $(4.5+0.075 \beta) \%+525$ |
| $10 \mathrm{k} \Omega$ | $1.800 \mathrm{k} \Omega \sim$ $19.999 \mathrm{k} \Omega$ | $(0.225+0.015 a) \%+15$ | $(0.15+0.015 a) \%+15$ | $(0.225+0.075 a) \%+15$ | $(0.225+0.075 a) \%+15$ | $(0.6+0.075 a) \%+60$ | $(1.5+0.075 a) \%+150$ | $(4.5+0.075 a) \%+600$ |
|  |  | $(0.15+0.0075 a) \%+15$ | $(0.15+0.0075 a) \%+15$ | $(0.15+0.045 a) \%+15$ | $(0.15+0.045 a) \%+15$ | $(0.6+0.045 a) \%+60$ | $(1.5+0.045 a) \%+105$ | $(4.5+0.075 a) \%+450$ |
| 100k $\Omega$ | $18.00 \mathrm{k} \Omega \sim$ $199.99 \mathrm{k} \Omega$ | $(0.225+0.015 a) \%+15$ | $(0.15+0.015 a) \%+15$ | $(0.225+0.075 a) \%+15$ | $(1.2+0.075 a) \%+75$ | $(1.5+0.075 a) \%+75$ | $(4.5+0.075 a) \%+450$ | $(30+0.75 a) \%+1050$ |
|  |  | $(0.15+0.0075 a) \%+15$ | $(0.15+0.0075 a) \%+15$ | $(0.15+0.045 a) \%+15$ | $(1.2+0.075 a) \%+270$ | $(3+0.075 a) \%+270$ | $(4.5+0.075 a) \%+270$ | $(30+0.75 a) \%+750$ |
| $1 \mathrm{M} \Omega$ | $\begin{gathered} 0.1800 \mathrm{M} \Omega \sim \\ 1.9999 \mathrm{M} \Omega \end{gathered}$ | $(2.25+0.15 a) \%+30$ | $(2.25+0.15 a) \%+30$ | $(2.25+0.15 a) \%+30$ | $(3+0.15 a) \%+105$ | $(3+0.15 a) \%+105$ |  |  |
|  |  | $(2.25+0.15 a) \%+30$ | $(2.25+0.15 a) \%+30$ | $(2.25+0.15 a) \%+30$ | $(3+0.15 a) \%+300$ | $(3+0.15 a) \%+375$ |  |  |
| $10 \mathrm{M} \Omega$ | $\begin{gathered} 1.800 \mathrm{M} \Omega \sim \\ 19.999 \mathrm{M} \Omega \end{gathered}$ | $(3+0.225 a) \%+30$ | $(3+0.225 a) \%+30$ | $(3+0.225 a) \%+30$ | $(3+0.225 a) \%+105$ | $(30+0.225 a) \%+750$ |  |  |
|  |  | $(3+0.15 a) \%+60$ | $(3+0.15 a) \%+60$ | $(3+0.15 a) \%+60$ | $(3+0.15 a) \%+300$ | $(30+0.15 a) \%+1050$ |  |  |
| $100 \mathrm{M} \Omega$ | $\begin{gathered} 18.00 \mathrm{M} \Omega \sim \\ 199.99 \mathrm{M} \Omega \end{gathered}$ | $(7.5+0.225 a) \%+750$ | $(7.5+0.225 a) \%+750$ | $(7.5+0.225 a) \%+750$ | $(7.5+0.225 a) \%+750$ |  |  |  |
|  |  | $(7.5+0.15 a) \%+600$ | $(7.5+0.15 a) \%+600$ | $(7.5+0.15 a) \%+600$ | $(7.5+0.15 a) \%+2250$ |  |  |  |

Upper Specification: Accuracy of $|Z| \pm$ (Nominal\% + Counts)
Lower Specification: Accuracy of $\theta \pm$ (Nominal\% + Counts)
The count coefficient should be calculated as follows:
$\underline{\left[\begin{array}{c}\text { Accuracy Limit from } \\ \text { Measurement Limit Chart }\end{array}\right] \times\left[\begin{array}{c}\text { Maximum Voltage } \\ \text { Limit for Chart }\end{array}\right]}$

The Set Measurement Voltage

$$
\alpha=\frac{Z x}{10,000} \quad \beta=\frac{10,000}{Z x} \quad Z x=\text { the number of counts for }|Z|
$$

Table A.6: Basic Accuracy Table [.46V to 1.00V]

| Range | Impedance | Measure Frequency |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | $42 \mathrm{~Hz} \sim 99.9 \mathrm{~Hz}$ | $100 \mathrm{~Hz} \sim 1 \mathrm{kHz}$ | $1.01 \mathrm{kHz} \sim 10.0 \mathrm{kHz}$ | $10.1 \mathrm{kHz} \sim 30.0 \mathrm{kHz}$ | $30.1 \mathrm{kHz} \sim 100 \mathrm{kHz}$ | $101 \mathrm{kHz} \sim 1.00 \mathrm{MHz}$ | $1.01 \mathrm{MHz} \sim 5.00 \mathrm{MHz}$ |
| $100 \mathrm{~m} \Omega$ | $\begin{gathered} 10.00 \mathrm{~m} \Omega \sim \\ 199.99 \mathrm{~m} \Omega \end{gathered}$ | $(5+4 \beta) \%+500$ | $(5+4 \beta) \%+500$ | $(5+4 \beta) \%+500$ | $(5+4 \beta) \%+500$ | $(10+4 \beta) \%+500$ |  |  |
|  |  | $(5+2 \beta) \%+100$ | $(5+2 \beta) \%+100$ | $(5+2 \beta) \%+100$ | $(5+2 \beta) \%+500$ | $(10+4 \beta) \%+1500$ |  |  |
| $1 \Omega$ | $\begin{gathered} 0.1800 \Omega \sim \\ 1.9999 \Omega \end{gathered}$ | $(2+0.4 \beta) \%+200$ | $(1+0.4 \beta) \%+200$ | $(1.5+0.4 \beta) \%+200$ | $(1.5+0.4 \beta) \%+200$ | $(2+0.4 \beta) \%+200$ | $(3+0.4 \beta) \%+200$ |  |
|  |  | $(2+0.3 \beta) \%+20$ | $(1+0.2 \beta) \%+20$ | $(1.5+0.2 \beta) \%+20$ | $(1.5+0.2 \beta) \%+60$ | $(2+0.2 \beta) \%+150$ | $(3+0.2 \beta) \%+250$ |  |
| $10 \Omega$ | $\begin{gathered} 1.800 \Omega \sim \\ 19.999 \Omega \\ \hline \end{gathered}$ | $(1+0.4 \beta) \%+200$ | $(0.8+0.04 \beta) \%+10$ | $(0.8+0.04 \beta) \%+10$ | $(0.8+0.04 \beta) \%+10$ | (1.5+0.04ß)\%+50 | $(1.5+0.04 \beta) \%+50$ | $(5+0.4 \beta) \%+200$ |
|  |  | $(1+0.2 \beta) \%+20$ | $(0.8+0.03 \beta) \%+10$ | $(0.8+0.03 \beta) \%+10$ | $(0.8+0.03 \beta) \%+10$ | (1.5+0.03ß)\%+50 | $(1.5+0.03 \beta) \%+50$ | $(5+0.3 \beta) \%+200$ |
| $100 \Omega$ | $\begin{array}{c\|} 18.00 \Omega \sim \\ 199.99 \Omega \end{array}$ | $(0.15+0.02 \beta) \%+10$ | $(0.1+0.02 \beta) \%+10$ | $(0.15+0.02 \beta) \%+10$ | $(0.15+0.02 \beta) \%+10$ | $(0.4+0.05 \beta) \%+40$ | $(0.6+0.05 \beta) \%+50$ | $(3+0.05 \beta) \%+50$ |
|  |  | $(0.15+0.01 \beta) \%+10$ | $(0.1+0.01 \beta) \%+10$ | $(0.1+0.01 \beta) \%+10$ | $(0.1+0.01 \beta) \%+10$ | (0.4+0.03ß)\% $\%$ +40 | $(0.6+0.03 \beta) \%+40$ | $(3+0.03 \beta) \%+150$ |
| $1 \mathrm{k} \Omega$ | $\begin{gathered} 0.1800 \mathrm{k} \Omega \sim \\ 1.9999 \mathrm{k} \Omega \end{gathered}$ | (0.15+0.01a) \% +10 | (0.1+0.01a) \% +10 | $(0.15+0.05 a) \%+10$ | $(0.15+0.05 a) \%+10$ | $(0.4+0.05 a) \%+40$ | $(0.6+0.05 \beta) \%+50$ | $(3+0.05 \beta) \%+350$ |
|  |  | (0.1+0.005a) \% +10 | (0.1+0.005a) \% +10 | (0.1+0.03a)\%+10 | (0.1+0.03a) \% +10 | (0.4+0.03a) \% +40 | $(0.6+0.03 \beta) \%+40$ | $(3+0.05 \beta) \%+350$ |
| 10k $\Omega$ | $\begin{gathered} 1.800 \mathrm{k} \Omega \sim \\ 19.999 \mathrm{k} \Omega \end{gathered}$ | $(0.15+0.01 a) \%+10$ | $(0.1+0.01 a) \%+10$ | $(0.15+0.05 a) \%+10$ | $(0.15+0.05 a) \%+10$ | (0.4+0.05a) \% +40 | $(1+0.05 a) \%+100$ | $(3+0.05 \alpha) \%+400$ |
|  |  | $(0.1+0.005 a) \%+10$ | (0.1+0.005a) \% +10 | (0.1+0.03a) \% +10 | (0.1+0.03a) \% +10 | (0.4+0.03a) \% +40 | $(1+0.03 \mathrm{a}) \%+70$ | $(3+0.05 \alpha) \%+300$ |
| 100k $\Omega$ | $\begin{gathered} 18.00 \mathrm{k} \Omega \sim \\ 199.99 \mathrm{k} \Omega \end{gathered}$ | (0.15+0.01a) \% +10 | (0.1+0.01a)\%+10 | $(0.15+0.05 a) \%+10$ | $(0.8+0.05 a) \%+50$ | $(1+0.05 a) \%+50$ | $(3+0.05 a) \%+300$ | $(20+0.5 \alpha) \%+700$ |
|  |  | $(0.1+0.005 a) \%+10$ | (0.1+0.005a) \% +10 | (0.1+0.03a) \% +10 | $(0.8+0.05 a) \%+180$ | $(2+0.05 a) \%+180$ | (3+0.05a) \% +180 | $(20+0.5 \alpha) \%+500$ |
| $1 \mathrm{M} \Omega$ | $\begin{gathered} 0.1800 \mathrm{M} \Omega \sim \\ 1.9999 \mathrm{M} \Omega \end{gathered}$ | $(1.5+0.1 a) \%+20$ | $(1.5+0.1 a) \%+20$ | $(1.5+0.1 a) \%+20$ | $(2+0.1 a) \%+70$ | $(2+0.1 a) \%+70$ | $(20+0.1 a) \%+700$ |  |
|  |  | $(1.5+0.1 a) \%+20$ | $(1.5+0.1 \mathrm{a}) \%+20$ | $(1.5+0.1 a) \%+20$ | $(2+0.1 a) \%+200$ | $(2+0.1 a) \%+250$ | $(20+0.1 a) \%+200$ |  |
| 10M $\Omega$ | $\begin{gathered} 1.800 \mathrm{M} \Omega \sim \\ 19.999 \mathrm{M} \Omega \end{gathered}$ | $(2+0.15 a) \%+20$ | $(2+0.15 a) \%+20$ | $(2+0.15 a) \%+20$ | $(2+0.15 a) \%+70$ | $(20+0.15 a) \%+500$ |  |  |
|  |  | $(2+0.1 a) \%+40$ | $(2+0.1 a) \%+40$ | $(2+0.1 a) \%+40$ | $(2+0.1 a) \%+200$ | $(20+0.1 a) \%+700$ |  |  |
| $100 \mathrm{M} \Omega$ | $\begin{gathered} 18.00 \mathrm{M} \Omega \sim \\ 199.99 \mathrm{M} \Omega \end{gathered}$ | $(5+0.15 a) \%+500$ | $(5+0.15 a) \%+500$ | $(5+0.15 a) \%+500$ | $(5+0.15 a) \%+500$ | $(50+0.15 a) \%+500$ |  |  |
|  |  | $(5+0.1 \alpha) \%+400$ | $(5+0.1 \alpha) \%+400$ | $(5+0.1 \alpha) \%+400$ | $(5+0.1 \alpha) \%+1500$ | $(50+0.1 \alpha) \%+1500$ |  |  |

Upper Specification: Accuracy of $|\mathrm{Z}| \pm$ (Nominal\% + Counts) Lower Specification: Accuracy of $\theta \pm$ (Nominal\% + Counts) The count coefficient should be calculated as follows:
$\left[\begin{array}{c}\text { Accuracy Limit from } \\ \text { Measurement Limit Chart }\end{array}\right] \times\left[\begin{array}{c}\text { Maximum Voltage } \\ \text { Limit for Chart }\end{array}\right]$

The Set Measurement Voltage

$$
\alpha=\frac{Z x}{10,000} \quad \beta=\frac{10,000}{Z X} \quad Z x=\text { the number of counts for }|Z|
$$

Table A.7: Basic Accuracy Table [1.01V to 5.00V]

| Range | Impedance | Measure Frequency |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | $42 \mathrm{~Hz} \sim 99.9 \mathrm{~Hz}$ | $100 \mathrm{~Hz} \sim 1 \mathrm{kHz}$ | $1.01 \mathrm{kHz} \sim 10.0 \mathrm{kHz}$ | $10.1 \mathrm{kHz} \sim 30.0 \mathrm{kHz}$ | $30.1 \mathrm{kHz} \sim 100 \mathrm{kHz}$ | $101 \mathrm{kHz} \sim 1.00 \mathrm{MHz}$ | $1.01 \mathrm{MHz} \sim 5.00 \mathrm{MHz}$ |
| $100 \mathrm{~m} \Omega$ | $\begin{gathered} 10.00 \mathrm{~m} \Omega \sim \\ 199.99 \mathrm{~m} \Omega \end{gathered}$ | $(7.5+6 \beta) \%+750$ | $(7.5+6 \beta) \%+750$ | $(7.5+6 \beta) \%+750$ | $(7.5+6 \beta) \%+750$ | $(15+6 \beta) \%+750$ |  |  |
|  |  | $(7.5+3 \beta) \%+150$ | $(7.5+3 \beta) \%+150$ | $(7.5+3 \beta) \%+150$ | $(7.5+3 \beta) \%+750$ | $(15+6 \beta) \%+2250$ |  |  |
| $1 \Omega$ | $\begin{gathered} 0.1800 \Omega \sim \\ 1.9999 \Omega \end{gathered}$ | $(3+0.6 \beta) \%+300$ | $(1.5+0.6 \beta) \%+300$ | $(2.25+0.6 \beta) \%+300$ | $(2.25+0.6 \beta) \%+300$ | $(3+0.6 \beta) \%+300$ | $(4.5+0.6 \beta) \%+300$ |  |
|  |  | $(3+0.45 \beta) \%+30$ | $(1.5+0.3 \beta) \%+30$ | $(2.25+0.3 \beta) \%+30$ | $(2.25+0.3 \beta) \%+90$ | $(3+0.3 \beta) \%+225$ | $(4.5+0.3 \beta) \%+375$ |  |
| $10 \Omega$ | $\begin{gathered} 1.800 \Omega \sim \\ 19.999 \Omega \end{gathered}$ | $(1.5+0.6 \beta) \%+300$ | $(1.2+0.06 \beta) \%+15$ | $(1.2+0.06 \beta) \%+15$ | $(1.2+0.06 \beta) \%+15$ | $(2.25+0.06 \beta) \%+75$ | $(2.25+0.06 \beta) \%+75$ |  |
|  |  | $(1.5+0.3 \beta) \%+30$ | $(1.2+0.045 \beta) \%+15$ | $(1.2+0.045 \beta) \%+15$ | $(1.2+0.045 \beta) \%+15$ | $(2.25+0.045 \beta) \%+75$ | $(2.25+0.045 \beta) \%+75$ |  |
| $100 \Omega$ | $\begin{gathered} 18.00 \Omega \sim \\ 199.99 \Omega \end{gathered}$ | $(0.225+0.03 \beta) \%+15$ | $(0.15+0.03 \beta) \%+15$ | $(0.225+0.03 \beta) \%+15$ | $(0.225+0.03 \beta) \%+15$ | $(0.6+0.075 \beta) \%+60$ | $(0.9+0.075 \beta) \%+75$ |  |
|  |  | $(0.225+0.015 \beta) \%+15$ | $(0.15+0.015 \beta) \%+15$ | $(0.15+0.015 \beta) \%+15$ | $(0.15+0.015 \beta) \%+15$ | $(0.6+0.045 \beta) \%+60$ | $(0.9+0.045 \beta) \%+60$ |  |
| $1 \mathrm{k} \Omega$ | $\begin{gathered} 0.1800 \mathrm{k} \Omega \sim \\ 1.9999 \mathrm{k} \Omega \end{gathered}$ | $(0.225+0.015 a) \%+15$ | $(0.15+0.015 a) \%+15$ | $(0.225+0.075 a) \%+15$ | $(0.225+0.075 a) \%+15$ | $(0.6+0.075 a) \%+60$ | $(0.9+0.075 \beta) \%+75$ |  |
|  |  | $(0.15+0.0075 a) \%+15$ | (0.15+0.0075a)\%+15 | 0.15+0.045a)\%+15 | $(0.15+0.045 a) \%+15$ | (0.6+0.045a)\%+60 | $(0.9+0.045 \beta) \%+60$ |  |
| 10k $\Omega$ | $\begin{gathered} 1.800 \mathrm{k} \Omega \sim \\ 19.999 \mathrm{k} \Omega \end{gathered}$ | $(0.225+0.015 a) \%+15$ | $(0.15+0.015 a) \%+15$ | $(0.225+0.075 a) \%+15$ | (0.225+0.075a)\%+15 | (0.6+0.075a)\%+60 | $(1.5+0.075 a) \%+150$ |  |
|  |  | $(0.15+0.0075 a) \%+15$ | $(0.15+0.0075 a) \%+15$ | $(0.15+0.045 a) \%+15$ | $(0.15+0.045 a) \%+15$ | $(0.6+0.045 a) \%+60$ | $(1.5+0.045 a) \%+105$ |  |
| 100k $\Omega$ | $\begin{gathered} 18.00 \mathrm{k} \Omega \sim \\ 199.99 \mathrm{k} \Omega \end{gathered}$ | $(0.225+0.015 a) \%+15$ | $(0.15+0.015 a) \%+15$ | $(0.225+0.075 a) \%+15$ | (1.2+0.075a) \% +75 | $(1.5+0.075 a) \%+75$ | $(4.5+0.075 a) \%+450$ |  |
|  |  | $(0.15+0.0075 a) \%+15$ | (0.15+0.0075a) \% +15 | $(0.15+0.045 a) \%+15$ | $(1.2+0.075 a) \%+270$ | $(3+0.075 a) \%+270$ | $(4.5+0.075 a) \%+270$ |  |
| $1 \mathrm{M} \Omega$ | $\begin{gathered} 0.1800 \mathrm{M} \Omega \sim \\ 1.9999 \mathrm{M} \Omega \end{gathered}$ | $(2.25+0.15 a) \%+30$ | $(2.25+0.15 a) \%+30$ | $(2.25+0.15 a) \%+30$ | $(3+0.15 a) \%+105$ | $(3+0.15 a) \%+105$ | $(30+0.15 a) \%+1050$ |  |
|  |  | $(2.25+0.15 a) \%+30$ | $(2.25+0.15 a) \%+30$ | $(2.25+0.15 a) \%+30$ | $(3+0.15 a) \%+300$ | $(3+0.15 a) \%+375$ | $(30+0.15 a) \%+300$ |  |
| $10 \mathrm{M} \Omega$ | $\begin{gathered} 1.800 \mathrm{M} \Omega \sim \\ 19.999 \mathrm{M} \Omega \end{gathered}$ | $(3+0.225 a) \%+30$ | $(3+0.225 a) \%+30$ | $(3+0.225 a) \%+30$ | $(3+0.225 a) \%+105$ | $(30+0.225 a) \%+750$ |  |  |
|  |  | $(3+0.15 a) \%+60$ | $(3+0.15 a) \%+60$ | $(3+0.15 a) \%+60$ | $(3+0.15 a) \%+300$ | $(30+0.15 a) \%+1050$ |  |  |
| 100M $\Omega$ | $\begin{gathered} 18.00 \mathrm{M} \Omega \sim \\ 199.99 \mathrm{M} \Omega \end{gathered}$ | $(7.5+0.225 a) \%+750$ | $(7.5+0.225 a) \%+750$ | $(7.5+0.225 a) \%+750$ | (7.5+0.225a) \% +750 | $(75+0.225 a) \%+750$ |  |  |
|  |  | $(7.5+0.15 \alpha) \%+600$ | $(7.5+0.15 \alpha) \%+600$ | $(7.5+0.15 \alpha) \%+600$ | $(7.5+0.15 \alpha) \%+2250$ | $(75+0.15 \alpha) \%+1950$ |  |  |

Upper Specification: Accuracy of $|Z| \pm$ (Nominal\% + Counts) Lower Specification: Accuracy of $\theta \pm$ (Nominal\% + Counts) The count coefficient should be calculated as follows:


The Set Measurement Voltage

$$
\alpha=\frac{Z x}{10,000} \quad \beta=\frac{10,000}{Z x} \quad Z x=\text { the number of counts for }|Z|
$$



## Error Codes

| DISPLAY CODE | ERROR TITLE | ERROR CONDITION |
| :---: | :---: | :---: |
| 601 | PRINTER BUSY | When becoming timeout causing from printer output |
| 1102 | COMPARATOR RELATION SETTING ERROR | Input miss of character code following C through program code |
| 1103 | TRIGGER ERROR | Input miss of character code following E through program code |
| 1104 | FUNCTION ERROR | Input miss of character code following F through program code |
| 1105 | INITIAL SETTING RELATION ERROR | Input miss of character code following I through program code |
| 1106 | MEASUREMENT SIGNAL•COMMAND LOCK ERROR | Input miss of character code following L through program code |
| 1107 | MEASUREMENT MODE - MONITOR ERROR | Input miss of character code for $\mathrm{MO}^{*} \sim \mathrm{M} 2^{*} \cdot \mathrm{MON}$ through program code |
| 1108 | SELECT ERROR TO DATA OUTPUT | Input miss of character code for OO*~O3* through program code |
| 1109 | COMPARATOR RELATION SETTING ERROR | Input miss of character code following P through program code |
| 1111 | SERVICE REQUEST• SPOT CORRECTION ERROR | Input miss of character code following S0*,S1*,SP1*~SP3* through program code |
| 1112 | TRIGGER ERROR | Input miss of character code following TO*,TO* through program code |
| 1114 | ZERO OFFSET ERROR | Input miss of character code for $\mathrm{ZO}^{*} \sim$ Z5** through program code |
| 1115 | MEASUREMENT MODE ERROR | Input miss of character code for JV, JVC, JCC through program code |
| 1120 | CORRECTION FREQUENCY CONTORL RELATION ERROR | Input miss of character code following W through program code |
| 1121 | COMPARATOR RELATION SETTING ERROR | Input miss of character code following PALXXXX through program code |
| 1122 | COMPARATOR RELATION SETTING ERROR | Input miss of character code following PAHXXXX through program code |
| 1123 | COMPARATOR RELATION SETTING ERROR | Input miss of character code following PBLXXXX through program code |
| 1124 | COMPARATOR RELATION SETTING ERROR | Input miss of character code following PBHXXXX through program code |
| 1128 | CORRECTION FREQUENCY CONTROL RELATION ERROR | Input miss of character code following WCH through program code |
| 1129 | CORRECTION FREQUENCY CONTROL RELATION ERROR | Input miss of character code following WCL through program code |
| 1201 | FREQUENCY SETTING RETATION ERROR | Input miss of character code following FRE. SPF through program code |
| 1202 | Ver COMMUNICATION ERROR | Miss-communication when sending Ver Command through program code |
| 1603 | COMPARATOR SW SETTING ERROR | When turning on program code C1 (comparator ON) in panel O |
| 1604 | FUNCTION A ERROR | Input miss of character code for FA0*~FA4* through program code |
| 1605 | FUNCTION B• RANGE• DATA OUTPUT ERROR | Input miss of character code for $\mathrm{FBO}^{*} \sim \mathrm{FB}^{*}, \mathrm{R} 0^{*} \sim \mathrm{R} 9^{*}$. REN through program code |
| 1606 | VOLTAGE SETTING MEASUREMENT AVERAGE VERSION ERROR | Input miss of character code for• V001*~V101*. Ver* which is out of LEV setting range through program code |
| 1607 | PANELNUMBER SETTING ERROR | Input miss of character code for FAN0*~FAN9* through program code |


[^0]:    * NOTE: All required accuracy specifications and features of the Agilent equipment are not listed.

